



Operating Instructions

VLT® AutomationDrive FC 300, 0.25-75 kW

Safety

⚠ WARNING

HIGH VOLTAGE!

Frequency converters contain high voltage when connected to AC mains input power. Installation, start up, and maintenance should be performed by qualified personnel only. Failure to perform installation, start up, and maintenance by qualified personnel could result in death or serious injury.

High Voltage

Frequency converters are connected to hazardous mains voltages. Extreme care should be taken to protect against shock. Only trained personnel familiar with electronic equipment should install, start, or maintain this equipment.

⚠ WARNING

UNINTENDED START!

When the frequency converter is connected to AC mains, the motor may start at any time. The frequency converter, motor, and any driven equipment must be in operational readiness. Failure to be in operational readiness when the frequency converter is connected to AC mains could result in death, serious injury, equipment, or property damage.

Unintended Start

When the frequency converter is connected to the AC mains, the motor may be started by means of an external switch, a serial bus command, an input reference signal, or a cleared fault condition. Use appropriate cautions to guard against an unintended start.

⚠ WARNING

DISCHARGE TIME!

Frequency converters contain DC-link capacitors that can remain charged even when the frequency converter is not powered. To avoid electrical hazards, disconnect AC mains, any permanent magnet type motors, and any remote DC-link power supplies, including battery backups, UPS and DC-link connections to other frequency converters. Wait for the capacitors to fully discharge before performing any service or repair work. The amount of wait time is listed in the *Discharge Time* table. Failure to wait the specified time after power has been removed before doing service or repair could result in death or serious injury.

Voltage [V]	Minimum waiting time (minutes)	
	4	15
200-240	0.25-3.7 kW	5.5-37 kW
380-480	0.25-7.5 kW	11-75 kW
525-600	0.75-7.5 kW	11-75 kW
525-690		11-75 kW
High voltage may be present even when the warning LED indicator lights are off.		

Discharge Time

Symbols

The following symbols are used in this manual.

⚠ WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

⚠ CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury. It may also be used to alert against unsafe practices.

CAUTION

Indicates a situation that may result in equipment or property-damage-only accidents.

NOTE

Indicates highlighted information that should be regarded with attention to avoid mistakes or operate equipment at less than optimal performance.

Approvals



Table 1.2

NOTE

Imposed limitations on the output frequency (due to export control regulations):

From software version 6.72 the output frequency of the frequency converter is limited to 590 Hz. Software versions 6x.xx also limit the maximum output frequency to 590 Hz, but these versions cannot be flashed, i.e. neither downgraded nor upgraded.

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1 Introduction

1

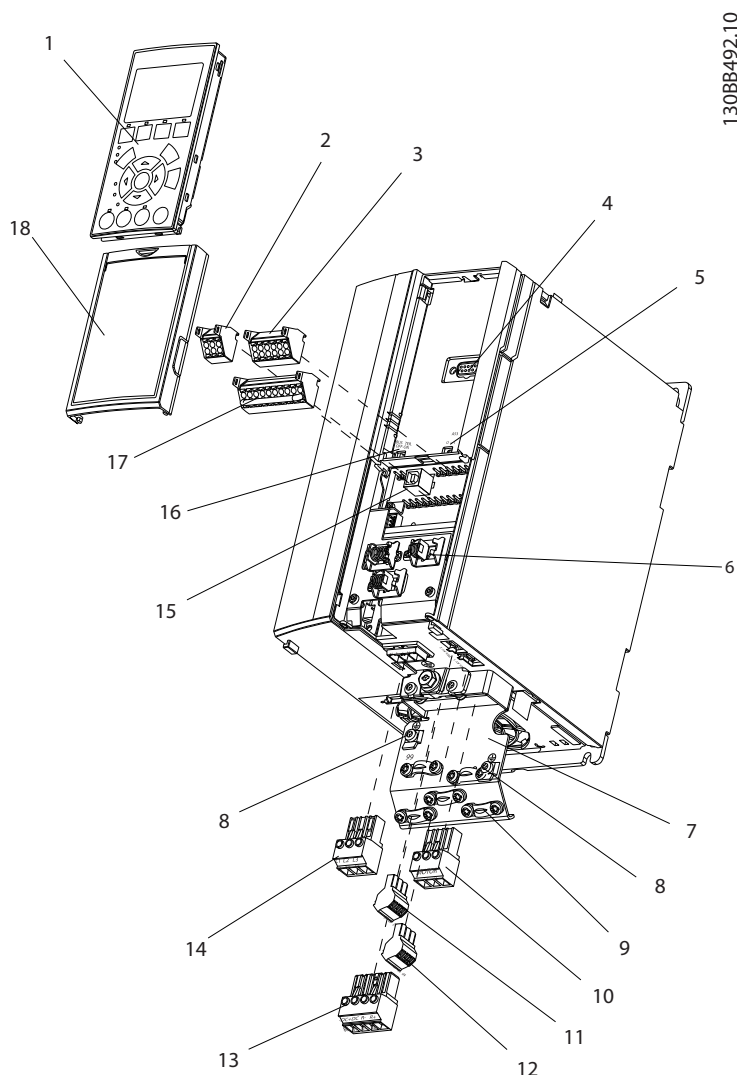


Illustration 1.1 Exploded View A1-A3, IP20

1	LCP	10	Motor output terminals 96 (U), 97 (V), 98 (W)
2	RS-485 serial bus connector (+68, -69)	11	Relay 1 (01, 02, 03)
3	Analog I/O connector	12	Relay 2 (04, 05, 06)
4	LCP input plug	13	Brake (-81, +82) and load sharing (-88, +89) terminals
5	Analog switches (A53), (A54)	14	Mains input terminals 91 (L1), 92 (L2), 93 (L3)
6	Cable strain relief/PE ground	15	USB connector
7	Decoupling plate	16	Serial bus terminal switch
8	Grounding clamp (PE)	17	Digital I/O and 24 V power supply
9	Shielded cable grounding clamp and strain relief	18	Control cable cover plate

Table 1.1 Legend to *Illustration 1.1*

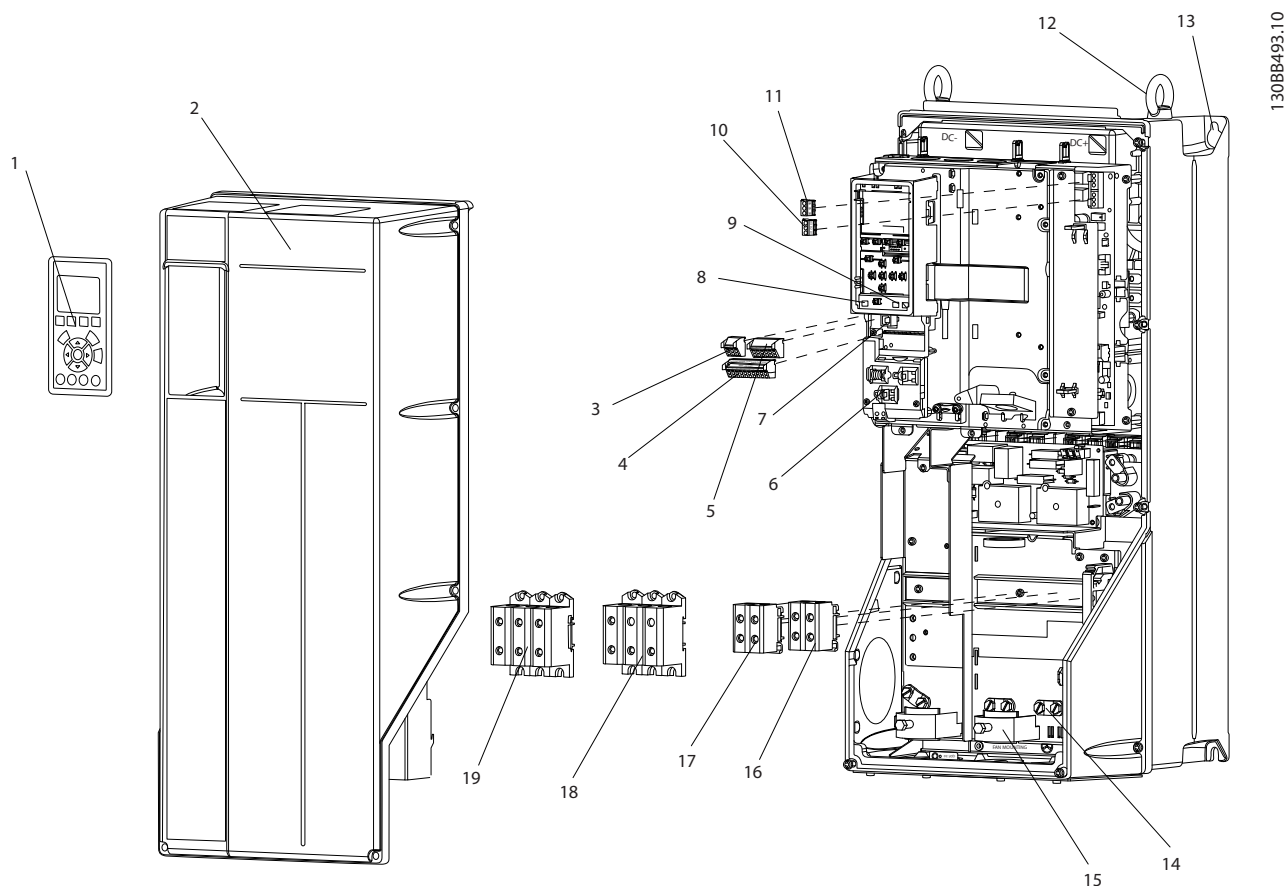


Illustration 1.2 Exploded View B and C Sizes, IP55/66

1	LCP	11	Relay 2 (04, 05, 06)
2	Cover	12	Lifting ring
3	RS-485 serial bus connector	13	Mounting slot
4	Digital I/O and 24 V power supply	14	Grounding clamp (PE)
5	Analog I/O connector	15	Cable strain relief/PE ground
6	Cable strain relief/PE ground	16	Brake terminal (-81, +82)
7	USB connector	17	Load sharing terminal (DC bus) (-88, +89)
8	Serial bus terminal switch	18	Motor output terminals 96 (U), 97 (V), 98 (W)
9	Analog switches (A53), (A54)	19	Mains input terminals 91 (L1), 92 (L2), 93 (L3)
10	Relay 1 (01, 02, 03)		

Table 1.2 Legend to Illustration 1.2

1.1 Purpose of the Manual

This manual is intended to provide detailed information for the installation and start up of the frequency converter. provides requirements for mechanical and electrical installation, including input, motor, control and serial communications wiring and control terminal functions. provides detailed procedures for start up, basic operational programming, and functional testing. The remaining chapters provide supplementary details. These details include user interface, detailed programming, application examples, start-up troubleshooting, and specifications.

1.2 Additional Resources

Other resources are available to understand advanced frequency converter functions and programming.

- The *VLT® Programming Guide* provides greater detail on working with parameters and many application examples.
- The *VLT® Design Guide* is intended to provide detailed capabilities and functionality to design motor control systems.
- Supplemental publications and manuals are available from Danfoss.
See <http://www.danfoss.com/BusinessAreas/DrivesSolutions/Documentations/Technical+Documentation.htm> for listings.
- Optional equipment is available that may change some of the procedures described. Reference the instructions supplied with those options for specific requirements. Contact the local Danfoss supplier or visit the Danfoss website: <http://www.danfoss.com/BusinessAreas/DrivesSolutions/Documentations/Technical+Documentation.htm>, for downloads or additional information.

1.3 Product Overview

A frequency converter is an electronic motor controller that converts AC mains input into a variable AC waveform output. The frequency and voltage of the output are regulated to control the motor speed or torque. The frequency converter can vary the speed of the motor in response to system feedback, such as position sensors on a conveyor belt. The frequency converter can also regulate the motor by responding to remote commands from external controllers.

In addition, the frequency converter monitors the system and motor status, issues warnings or alarms for fault conditions, starts and stops the motor, optimizes energy efficiency, and offers many more control, monitoring, and efficiency functions. Operation and monitoring functions are available as status indications to an outside control system or serial communication network.

1.4 Internal Controller Functions

Illustration 1.3 is a block diagram of the frequency converter's internal components. See *Table 1.3* for their functions.

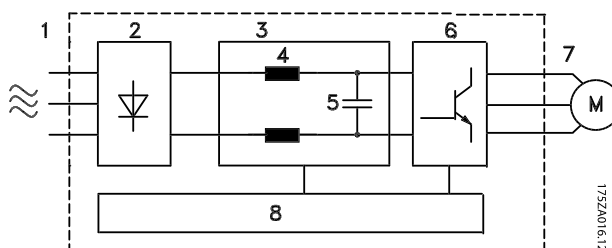


Illustration 1.3 Frequency Converter Block Diagram

Area	Title	Functions
1	Mains input	Three-phase AC mains power supply to the frequency converter
2	Rectifier	The rectifier bridge converts the AC input to DC current to supply inverter power
3	DC bus	Intermediate DC-bus circuit handles the DC current
4	DC reactors	- Filter the intermediate DC circuit voltage - Provide line transient protection - Reduce RMS current - Raise the power factor reflected back to the line - Reduce harmonics on the AC input
5	Capacitor bank	- Stores the DC power - Provides ride-through protection for short power losses
6	Inverter	Converts the DC into a controlled PWM AC waveform for a controlled variable output to the motor
7	Output to motor	Regulated three-phase output power to the motor
8	Control circuitry	- Input power, internal processing, output, and motor current are monitored to provide efficient operation and control - User interface and external commands are monitored and performed - Status output and control can be provided

Table 1.3 Legend to *Illustration 1.3*

1.5 Frame Sizes and Power Ratings

1

	Frame size [kW]										
[Volts]	A1	A2	A3	A4	A5	B1	B2	C1	C2	C3	C4
200-240	0.25-1.5	0.25-2.2	3.0-3.7	0.25-2.2	0.25-3.7	5.5-7.5	11	15-22	30-37	18.5-22	30-37
380-480	0.37-1.5	0.37-4.0	5.5-7.5	0.37-4.0	0.37-7.5	11-15	18.5-22	30-45	55-75	37-45	55-75
525-600	N/A	N/A	0.75-7.5	N/A	0.75-7.5	11-15	18.5-22	30-45	55-90	37-45	55-90
525-690	N/A	N/A	1.1-7.5	N/A	N/A	N/A	11-22	N/A	30-75	37-45	N/A

Table 1.4 Frames Sizes and Power Ratings

2 Installation

2.1 Installation Site Check List

- The frequency converter relies on the ambient air for cooling. Observe the limitations on ambient air temperature for optimal operation
- Ensure that the installation location has sufficient support strength to mount the frequency converter
- Keep the manual, drawings, and diagrams accessible for detailed installation and operation instructions. It is important that the manual is available for equipment operators.
- Locate equipment as near to the motor as possible. Keep motor cables as short as possible. Check the motor characteristics for actual tolerances. Do not exceed
 - 300 m (1000 ft) for unshielded motor leads
 - 150 m (500 ft) for shielded cable.
- Ensure that the ingress protection rating of the frequency converter is suitable for the installation environment. IP55 (NEMA 12) or IP66 (NEMA 4) enclosures may be necessary.

⚠ CAUTION

Ingress protection

IP54, IP55 and IP66 ratings can only be guaranteed if the unit is properly closed.

- Ensure that all cable glands and unused holes for glands are properly sealed.
- Ensure that the unit cover is properly closed

⚠ CAUTION

Device damage through contamination

Do not leave the frequency converter uncovered.

For "spark-free" installations according to European Agreement concerning International Carriage of Dangerous Goods by Inland Waterways (ADN_2011 ###), refer to VLT® AutomationDrive FC 300 Design Guide.

2.2 Frequency Converter and Motor Pre-installation Check List

- Compare the model number of unit on the nameplate to what was ordered to verify the proper equipment
- Ensure each of the following are rated for same voltage:
 - Mains (power)
 - Frequency converter
 - Motor
- Ensure that the frequency converter output current rating is equal to or greater than motor full load current for peak motor performance
 - Motor size and frequency converter power must match for proper overload protection
 - If frequency converter rating is less than motor, full motor output cannot be achieved

2.3 Mechanical Installation

2.3.1 Cooling

- To provide cooling airflow, mount the unit to a solid flat surface or to the optional back plate (see 2.3.3 *Mounting*)
- Top and bottom clearance for air cooling must be provided. Generally, 100-225 mm (4-10 in) is required. See *Illustration 2.1* for clearance requirements
- Improper mounting can result in over heating and reduced performance
- Derating for temperatures starting between 40 °C (104 °F) and 50 °C (122 °F) and elevation 1000 m (3300 ft) above sea level must be considered. See the equipment Design Guide for detailed information.

2

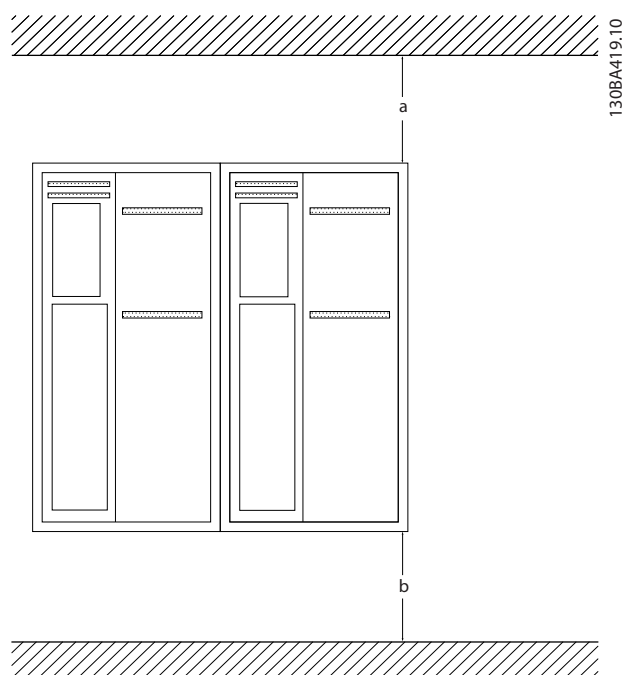


Illustration 2.1 Top and Bottom Cooling Clearance

Enclosure	A1-A5	B1-B4	C1, C3	C2, C4
a/b [mm]	100	200	200	225

Table 2.1 Minimum Airflow Clearance Requirements

2.3.2 Lifting

- Check the weight of the unit to determine a safe lifting method
- Ensure that the lifting device is suitable for the task
- If necessary, plan for a hoist, crane, or forklift with the appropriate rating to move the unit
- For lifting, use hoist rings on the unit, when provided

2.3.3 Mounting

- Mount the unit vertically
- The frequency converter allows side by side installation
- Ensure that the strength of the mounting location will support the unit weight
- Mount the unit to a solid flat surface or to the optional back plate to provide cooling airflow (see *Illustration 2.2* and *Illustration 2.3*)
- Improper mounting can result in over heating and reduced performance
- Use the slotted mounting holes on the unit for wall mounting, when provided

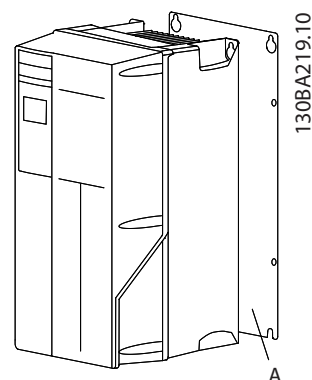


Illustration 2.2 Proper Mounting with Back Plate

Item A is a back plate properly installed for required airflow to cool the unit.

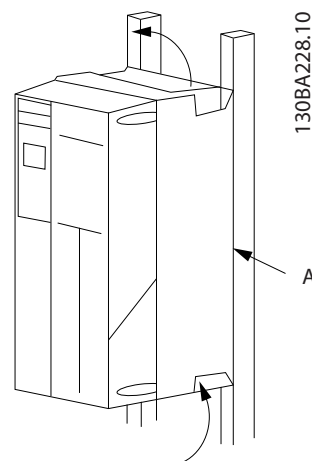


Illustration 2.3 Proper Mounting with Railings

NOTE

Back plate is needed when mounted on railings.

2.3.4 Tightening Torques

See *10.4 Connection Tightening Torques* for proper tightening specifications.

2.4 Electrical Installation

This section contains detailed instructions for wiring the frequency converter. The following tasks are described.

- Wiring the motor to the frequency converter output terminals
- Wiring the AC mains to the frequency converter input terminals
- Connecting control and serial communication wiring
- After power has been applied, checking input and motor power; programming control terminals for their intended functions

2

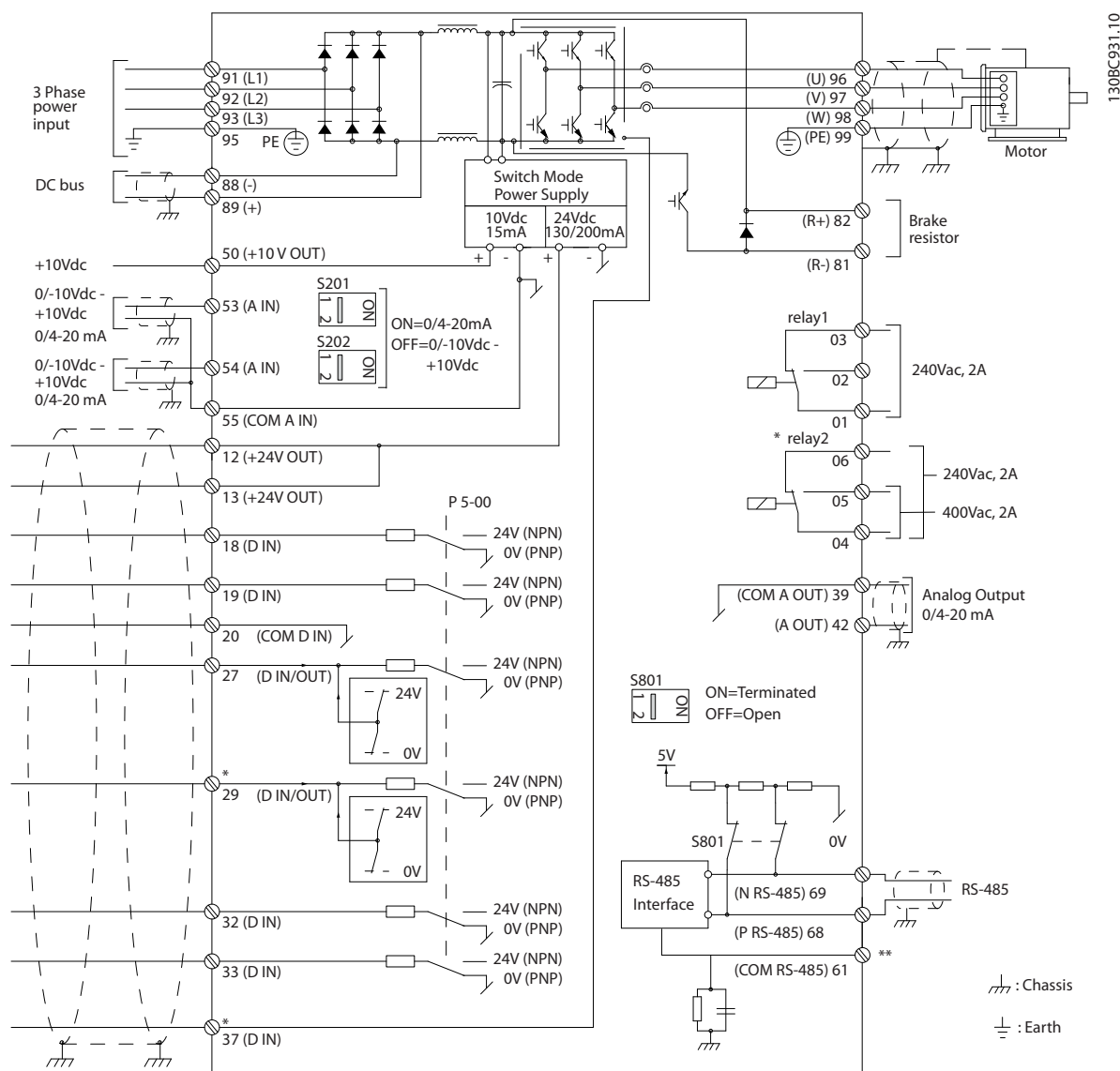


Illustration 2.4 Basic Wiring Schematic Drawing

A=Analog, D=Digital

Terminal 37 is used for Safe Stop. For Safe Stop installation instructions, refer to the Design Guide.

* Terminal 37 is not included in FC 301 (except frame size A1). Relay 2 and terminal 29 have no function in FC 301.

** Do not connect cable screen.

2

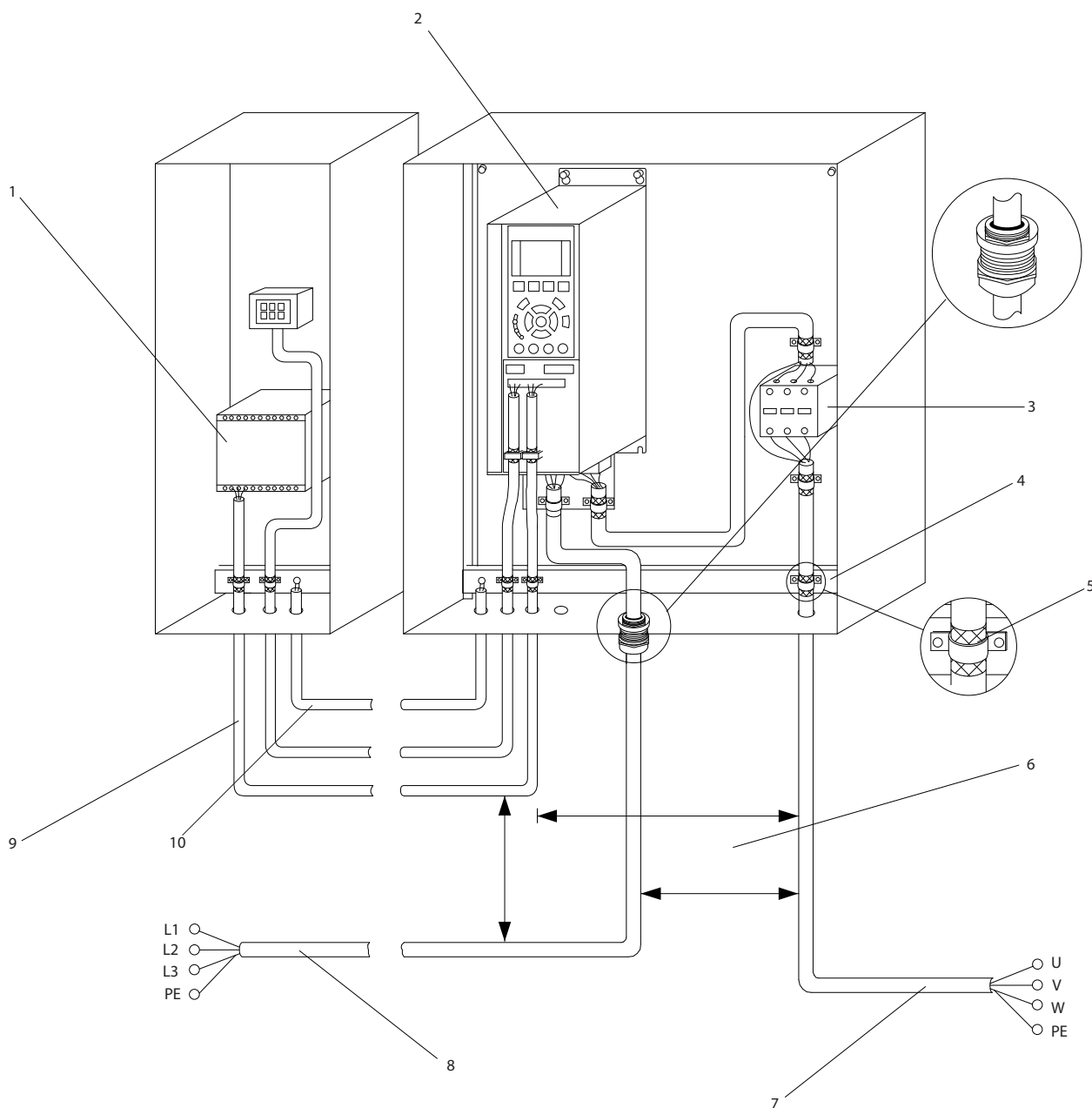


Illustration 2.5 Typical Electrical Connection

1	PLC	6	Min. 200 mm (7.9 in) between control cables, motor and mains
2	Frequency converter	7	Motor, 3-phase and PE
3	Output contactor (Generally not recommended)	8	Mains, 3-phase and reinforced PE
4	Earth (grounding) rail (PE)	9	Control wiring
5	Cable insulation (stripped)	10	Equalising min. 16 mm ² (0.025 in)

Table 2.2 Legend to *Illustration 2.5*

2.4.1 Requirements

⚠ WARNING

EQUIPMENT HAZARD!

Rotating shafts and electrical equipment can be hazardous. All electrical work must conform to national and local electrical codes. It is strongly recommended that installation, start up, and maintenance be performed only by trained and qualified personnel. Failure to follow these guidelines could result in death or serious injury.

CAUTION

WIRING ISOLATION!

Run input power, motor wiring and control wiring in three separate metallic conduits or use separated shielded cable for high frequency noise isolation. Failure to isolate power, motor and control wiring could result in less than optimum frequency converter and associated equipment performance.

For your safety, comply with the following requirements.

- Electronic controls equipment is connected to hazardous mains voltage. Extreme care should be taken to protect against electrical hazards when applying power to the unit.
- Run motor cables from multiple frequency converters separately. Induced voltage from output motor cables run together can charge equipment capacitors even with the equipment turned off and locked out.

Overload and Equipment Protection

- An electronically activated function within the frequency converter provides overload protection for the motor. The overload calculates the level of increase to activate timing for the trip (controller output stop) function. The higher the current draw, the quicker the trip response. The overload provides Class 20 motor protection. See *8 Warnings and Alarms* for details on the trip function.
- Because the motor wiring carries high frequency current, it is important that wiring for mains, motor power, and control are run separately. Use metallic conduit or separated shielded wire. Failure to isolate power, motor, and control wiring could result in less than optimum equipment performance.
- All frequency converters must be provided with short-circuit and over-current protection. Input fusing is required to provide this protection, see *Illustration 2.6*. If not factory supplied, fuses must be provided by the installer as part of installation.

See maximum fuse ratings in *10.3 Fuse Specifications*.

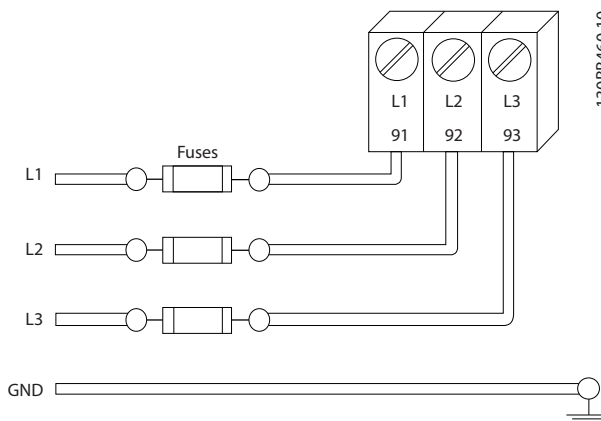


Illustration 2.6 Frequency Converter Fuses

Wire Type and Ratings

- All wiring must comply with local and national regulations regarding cross-section and ambient temperature requirements.
- Danfoss recommends that all power connections be made with a minimum 75 °C rated copper wire.
- See *10.1 Power-dependent Specifications* for recommended wire sizes.

2.4.2 Earth (Grounding) Requirements

⚠ WARNING

GROUNDING HAZARD!

For operator safety, it is important to ground the frequency converter properly in accordance with national and local electrical codes as well as instructions contained within these instructions. Ground currents are higher than 3,5 mA. Failure to ground the frequency converter properly could result in death or serious injury.

NOTE

It is the responsibility of the user or certified electrical installer to ensure correct grounding (earthing) of the equipment in accordance with national and local electrical codes and standards.

- Follow all local and national electrical codes to ground electrical equipment properly
- Proper protective grounding for equipment with ground currents higher than 3,5 mA must be established, see *Leakage Current (>3,5 mA)*
- A dedicated ground wire is required for input power, motor power and control wiring

- Use the clamps provided with on the equipment for proper ground connections
- Do not ground one frequency converter to another in a “daisy chain” fashion
- Keep the ground wire connections as short as possible
- Use of high-strand wire to reduce electrical noise is recommended
- Follow motor manufacturer wiring requirements

2.4.2.1 Leakage Current (>3.5 mA)

Follow national and local codes regarding protective earthing of equipment with a leakage current > 3.5 mA. Frequency converter technology implies high frequency switching at high power. This will generate a leakage current in the earth connection. A fault current in the frequency converter at the output power terminals might contain a DC component which can charge the filter capacitors and cause a transient earth current. The earth leakage current depends on various system configurations including RFI filtering, screened motor cables, and frequency converter power.

EN/IEC61800-5-1 (Power Drive System Product Standard) requires special care if the leakage current exceeds 3.5 mA. Earth grounding must be reinforced in one of the following ways:

- Earth ground wire of at least 10 mm²
- Two separate earth ground wires both complying with the dimensioning rules

See EN 60364-5-54 § 543.7 for further information.

Using RCDs

Where residual current devices (RCDs), also known as earth leakage circuit breakers (ELCBs), are used, comply with the following:

- Use RCDs of type B only which are capable of detecting AC and DC currents
- Use RCDs with an inrush delay to prevent faults due to transient earth currents
- Dimension RCDs according to the system configuration and environmental considerations

2.4.2.2 Grounding Using Shielded Cable

Earthing (grounding) clamps are provided for motor wiring (see *Illustration 2.7*).

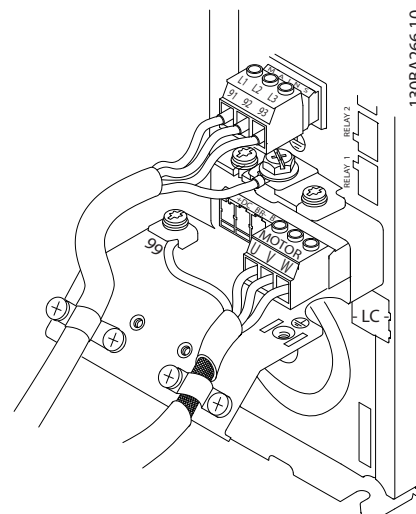


Illustration 2.7 Grounding with Shielded Cable

2.4.3 Motor Connection

⚠ WARNING

INDUCED VOLTAGE!

Run output motor cables from multiple frequency converters separately. Induced voltage from output motor cables run together can charge equipment capacitors even with the equipment turned off and locked out. Failure to run output motor cables separately could result in death or serious injury.

- For maximum wire sizes see *10.1 Power-dependent Specifications*
- Comply with local and national electrical codes for cable sizes
- Motor wiring knockouts or access panels are provided at the base of IP21 and higher (NEMA1/12) units
- Do not install power factor correction capacitors between the frequency converter and the motor
- Do not wire a starting or pole-changing device between the frequency converter and the motor
- Connect the 3-phase motor wiring to terminals 96 (U), 97 (V), and 98 (W)
- Ground the cable in accordance with grounding instructions provided
- Torque terminals in accordance with the information provided in
- Follow motor manufacturer wiring requirements

Illustration 2.8 represents mains input, motor, and earth grounding for basic frequency converters. Actual configurations vary with unit types and optional equipment.

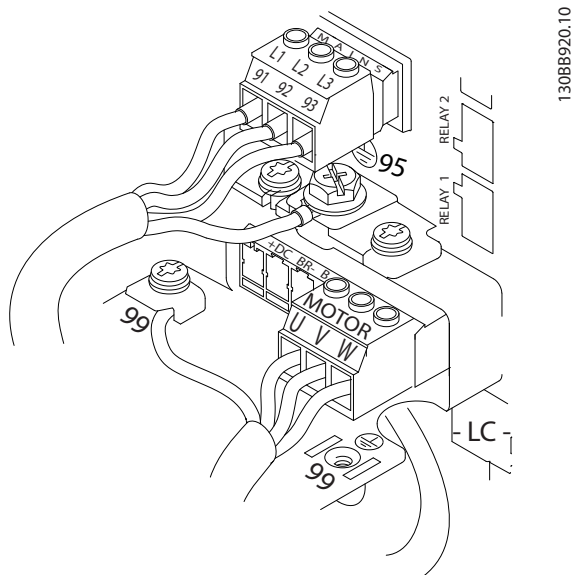


Illustration 2.8 Example of Motor, Mains and Earth Wiring

2.4.4 AC Mains Connection

- Size wiring based upon the input current of the frequency converter. For maximum wire sizes see 10.1 Power-dependent Specifications.
- Comply with local and national electrical codes for cable sizes.
- Connect 3-phase AC input power wiring to terminals L1, L2, and L3 (see Illustration 2.8).
- Depending on the configuration of the equipment, input power will be connected to the mains input power or the input disconnect.
- Ground the cable in accordance with grounding instructions provided in 2.4.2 Earth (Grounding) Requirements
- All frequency converters may be used with an isolated input source as well as with ground reference power lines. When supplied from an isolated mains source (IT mains or floating delta) or TT/TN-S mains with a grounded leg (grounded delta), set 14-50 RFI Filter to [0] Off. When off, the internal RFI filter capacitors between the chassis and the intermediate circuit are isolated to avoid damage to the intermediate circuit and to reduce earth capacity currents in accordance with IEC 61800-3.

2.4.5 Control Wiring

- Isolate control wiring from high power components in the frequency converter.
- If the frequency converter is connected to a thermistor, for PELV isolation, optional thermistor control wiring must be reinforced/double insulated. A 24 V DC supply voltage is recommended.

2.4.5.1 Access

- Remove access cover plate with a screw driver. See Illustration 2.9.
- Or remove front cover by loosening attaching screws. See Illustration 2.10.

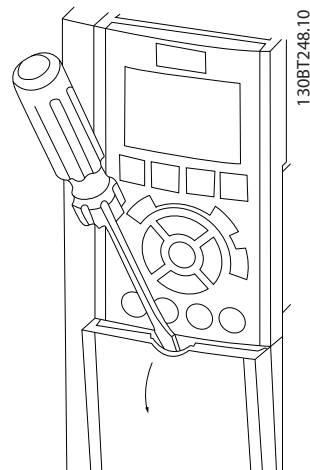


Illustration 2.9 Control Wiring Access for A2, A3, B3, B4, C3 and C4 Enclosures

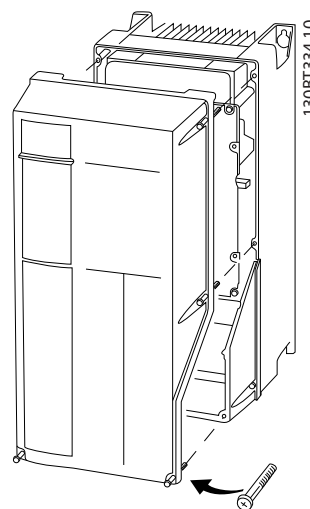


Illustration 2.10 Control Wiring Access for A4, A5, B1, B2, C1 and C2 Enclosures

See Table 2.3 before tightening the covers.

Frame	IP20	IP21	IP55	IP66
A3/A4/A5	-	-	2	2
B1/B2	-	*	2.2	2.2
C1/C2/C3/C4	-	*	2.2	2.2

* No screws to tighten
- Does not exist

Table 2.3 Tightening Torques for Covers (Nm)

2.4.5.2 Control Terminal Types

Illustration 2.11 and shows the removable frequency converter connectors. Terminal functions and default settings are summarized in Table 2.5.

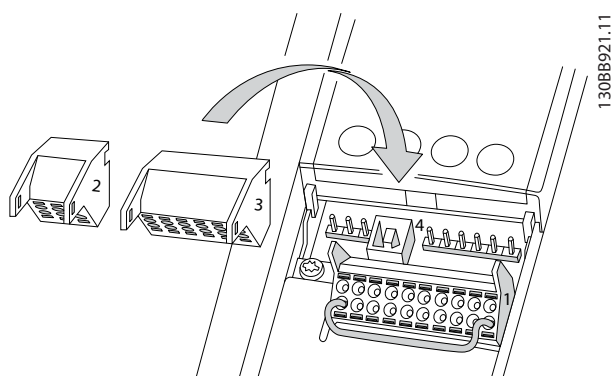


Illustration 2.11 Control Terminal Locations

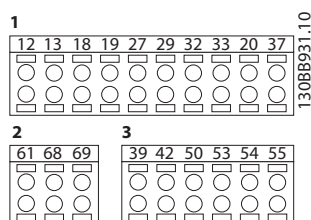


Illustration 2.12 Terminal Numbers

- **Connector 1** provides four programmable digital inputs terminals, two additional digital terminals programmable as either input or output, a 24 V DC terminal supply voltage, and a common for optional customer supplied 24 V DC voltage. FC 302 and FC 301 (optional in A1 enclosure) also provide a digital input for STO (Safe Torque Off) function.
- **Connector 2** terminals (+)68 and (-)69 are for an RS-485 serial communications connection
- **Connector 3** provides two analog inputs, one analog output, 10 V DC supply voltage, and commons for the inputs and output
- **Connector 4** is a USB port available for use with the MCT 10 Set-up Software

- Also provided are two Form C relay outputs that are in various locations depending upon the frequency converter configuration and size
- Some options available for ordering with the unit may provide additional terminals. See the manual provided with the equipment option.

See 10.2 General Technical Data for terminal ratings details.

Terminal description			
Terminal	Parameter	Default setting	Description
Digital inputs/outputs			
12, 13	-	+24 V DC	24 V DC supply voltage. Maximum output current is 200 mA total (130 mA for FC 301) for all 24 V loads. Useable for digital inputs and external transducers.
18	5-10	[8] Start	Digital inputs.
19	5-11	[10] Reversing	
32	5-14	[0] No operation	
33	5-15	[0] No operation	
27	5-12	[2] Coast inverse	Selectable for either digital input or output. Default setting is input.
29	5-13	[14] JOG	
20	-		Common for digital inputs and 0 V potential for 24 V supply.
37	-	Safe Torque Off (STO)	Safe input. Used for STO.
Analog inputs/outputs			
39	-		Common for analog output
42	6-50	[0] No operation	Programmable analog output. The analog signal is 0-20 mA or 4-20 mA at a maximum of 500 Ω
50	-	+10 V DC	10 V DC analog supply voltage. 15 mA maximum commonly used for potentiometer or thermistor.
53	6-1*	Reference	Analog input. Selectable for voltage or current. Switches A53 and A54 select mA or V.
54	6-2*	Feedback	

Terminal description			
Terminal	Parameter	Default setting	Description
55	-		Common for analog input

Table 2.4 Terminal Description Digital Inputs/Outputs, Analog Inputs/Outputs

Terminal description			
Terminal	Parameter	Default setting	Description
Serial communication			
61	-		Integrated RC-Filter for cable screen. ONLY for connecting the screen when experiencing EMC problems.
68 (+)	8-3*		RS-485 Interface. A control card switch is provided for termination resistance.
69 (-)	8-3*		
Relays			
01, 02, 03	5-40 [0]	[0] No operation	Form C relay output. Usable for AC or DC
04, 05, 06	5-40 [1]	[0] No operation	voltage and resistive or inductive loads.

Table 2.5 Terminal Description Serial Communication

2.4.5.3 Wiring to Control Terminals

Control terminal connectors can be unplugged from the frequency converter for ease of installation, as shown in *Illustration 2.11*.

1. Open the contact by inserting a small screwdriver into the slot above or below the contact, as shown in *Illustration 2.13*.
2. Insert the bared control wire into the contact.
3. Remove the screwdriver to fasten the control wire into the contact.
4. Ensure the contact is firmly established and not loose. Loose control wiring can be the source of equipment faults or less than optimal operation.

See 10.1 Power-dependent Specifications for control terminal wiring sizes.

See 6 Application Examples for typical control wiring connections.

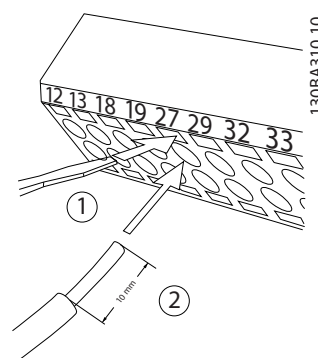


Illustration 2.13 Connecting Control Wiring

2.4.5.4 Using Screened Control Cables

Correct screening

The preferred method in most cases is to secure control and serial communication cables with screening clamps provided at both ends to ensure best possible high frequency cable contact.

If the earth potential between the frequency converter and the PLC is different, electric noise may occur that will disturb the entire system. Solve this problem by fitting an equalizing cable next to the control cable. Minimum cable cross section: 16 mm².

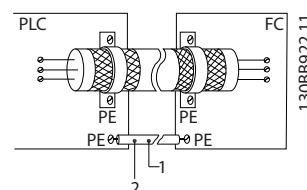


Illustration 2.14 Correct Screening

1	Min. 16 mm ²
2	Equalizing cable

Table 2.6 Legend to *Illustration 2.14*

50/60 Hz ground loops

With very long control cables, ground loops may occur. To eliminate ground loops, connect one end of the screen-to-ground with a 100 nF capacitor (keeping leads short).

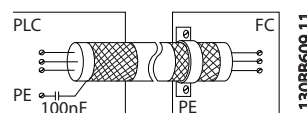


Illustration 2.15 50/60 Hz Ground Loops

Avoid EMC noise on serial communication

This terminal is connected to earth via an internal RC link. Use twisted-pair cables to reduce interference between conductors. The recommended method is shown below:

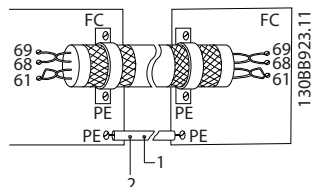


Illustration 2.16 Twisted-pair Cables

1	Min. 16 mm ²
2	Equalizing cable

Table 2.7 Legend to Illustration 2.16

Alternatively, the connection to terminal 61 can be omitted:

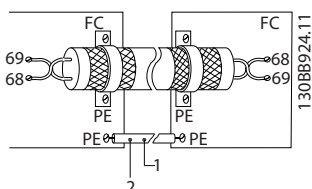


Illustration 2.17 Twisted-pair Cables without Terminal 61

1	Min. 16 mm ²
2	Equalizing cable

Table 2.8 Legend to Illustration 2.17

2.4.5.5 Control Terminal Functions

Frequency converter functions are commanded by receiving control input signals.

- Each terminal must be programmed for the function it will be supporting in the parameters associated with that terminal. See Table 2.5 for terminals and associated parameters.
- It is important to confirm that the control terminal is programmed for the correct function. See 4 User Interface for details on accessing parameters and 5 About Frequency Converter Programming for details on programming.
- The default terminal programming is intended to initiate frequency converter functioning in a typical operational mode.

2.4.5.6 Jumper Terminals 12 and 27

A jumper wire may be required between terminal 12 (or 13) and terminal 27 for the frequency converter to operate when using factory default programming values.

- Digital input terminal 27 is designed to receive an 24 V DC external interlock command. In many applications, the user wires an external interlock device to terminal 27
- When no interlock device is used, wire a jumper between control terminal 12 (recommended) or 13 to terminal 27. This provides an internal 24 V signal on terminal 27
- No signal present prevents the unit from operating
- When the status line at the bottom of the LCP reads AUTO REMOTE COAST, this indicates that the unit is ready to operate but is missing an input signal on terminal 27.
- When factory installed optional equipment is wired to terminal 27, do not remove that wiring

2.4.5.7 Terminal 53 and 54 Switches

- Analog input terminals 53 and 54 can select either voltage (-10 to 10 V) or current (0/4-20 mA) input signals
- Remove power to the frequency converter before changing switch positions
- Set switches A53 and A54 to select the signal type. U selects voltage, I selects current.
- The switches are accessible when the LCP has been removed (see Illustration 2.18).

NOTE

Some option cards available for the unit may cover these switches and must be removed to change switch settings. Always remove power to the unit before removing option cards.

- Terminal 53 default is for a speed reference signal in open loop set in 16-61 Terminal 53 Switch Setting
- Terminal 54 default is for a feedback signal in closed loop set in 16-63 Terminal 54 Switch Setting

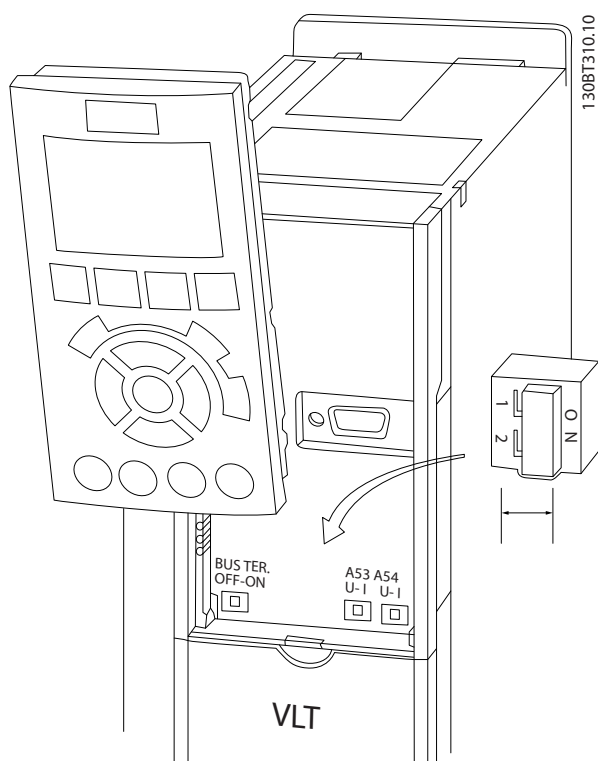


Illustration 2.18 Location of Terminals 53 and 54 Switches and Bus Termination Switch

frequency converter is not a safety device, the crane/lift designer (OEM) must decide on the type and number of safety devices (e.g. speed switch, emergency brakes etc.) to be used, in order to be able to stop the load in case of emergency or malfunction of the system, according to relevant national crane/lift regulations.

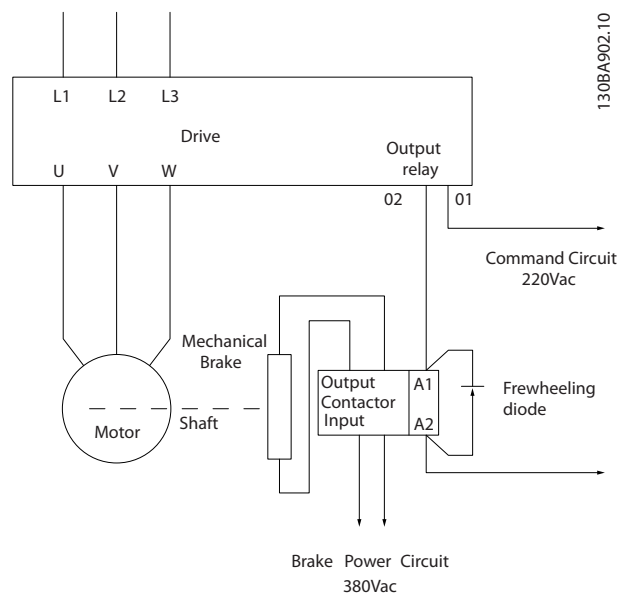


Illustration 2.19 Connecting the Mechanical Brake to the Frequency Converter

2.4.5.8 Mechanical Brake Control

In hoisting/lowering applications, it is necessary to be able to control an electro-mechanical brake:

- Control the brake using any relay output or digital output (terminal 27 or 29).
- Keep the output closed (voltage-free) as long as the frequency converter is unable to 'support' the motor, for example due to the load being too heavy.
- Select [32] *Mechanical brake control* in parameter group 5-4* *Relays* for applications with an electro-mechanical brake.
- The brake is released when the motor current exceeds the preset value in 2-20 *Release Brake Current*.
- The brake is engaged when the output frequency is less than the frequency set in 2-21 *Activate Brake Speed [RPM]* or 2-22 *Activate Brake Speed [Hz]*, and only if the frequency converter carries out a stop command.

If the frequency converter is in alarm mode or in an over-voltage situation, the mechanical brake immediately cuts in.

In the vertical movement, the key point is that the load must be held, stopped, controlled (raised, lowered) in a safe mode during the entire operation. Because the

2.4.6 Serial Communication

Connect RS-485 serial communication wiring to terminals (+)68 and (-)69.

- Screened serial communication cable is recommended
- See 2.4.2 *Earth (Grounding) Requirements* for proper grounding

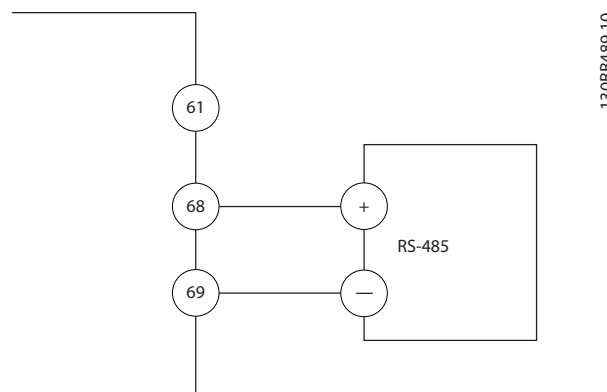


Illustration 2.20 Serial Communication Wiring Diagram

For basic serial communication set-up, select the following

1. Protocol type in *8-30 Protocol*.
2. Frequency converter address in *8-31 Address*.
3. Baud rate in *8-32 Baud Rate*.
- Two communication protocols are internal to the frequency converter. Follow motor manufacturer wiring requirements.
 - Danfoss FC
 - Modbus RTU
- Functions can be programmed remotely using the protocol software and RS-485 connection or in parameter group 8-** *Communications and Options*
- Selecting a specific communication protocol changes various default parameter settings to match that protocol's specifications along with making additional protocol-specific parameters available
- Option cards which install into the frequency converter are available to provide additional communication protocols. See the option-card documentation for installation and operation instructions

2.5 Safe Stop

The frequency converter can perform the safety function *Safe Torque Off* (STO, as defined by EN IEC 61800-5-2¹⁾) and *Stop Category 0* (as defined in EN 60204-1²⁾).

Danfoss has named this functionality *Safe Stop*. Before integration and use of Safe Stop in an installation, perform a thorough risk analysis to determine whether the Safe Stop functionality and safety levels are appropriate and sufficient. Safe Stop is designed and approved suitable for the requirements of:

- Safety Category 3 according to EN ISO 13849-1
- Performance Level "d" according to EN ISO 13849-1:2008
- SIL 2 Capability according to IEC 61508 and EN 61800-5-2
- SILCL 2 according to EN 62061

¹⁾ Refer to EN IEC 61800-5-2 for details of Safe torque off (STO) function.

²⁾ Refer to EN IEC 60204-1 for details of stop category 0 and 1.

Activation and Termination of Safe Stop

The Safe Stop (STO) function is activated by removing the voltage at Terminal 37 of the Safe Inverter. By connecting the Safe Inverter to external safety devices providing a safe delay, an installation for a safe Stop Category 1 can be obtained. The Safe Stop function can be used for

asynchronous, synchronous, and permanent magnet motors.

⚠ WARNING

After installation of Safe Stop (STO), a commissioning test as specified in 2.5.2 *Safe Stop Commissioning Test* must be performed. A passed commissioning test is mandatory after first installation and after each change to the safety installation.

Safe Stop Technical Data

The following values are associated to the different types of safety levels:

Reaction time for T37

- Maximum reaction time: 20 ms

Reaction time = delay between de-energizing the STO input and switching off the frequency converter output bridge.

Data for EN ISO 13849-1

- Performance Level "d"
- MTTF_d (Mean Time To Dangerous Failure): 14000 years
- DC (Diagnostic Coverage): 90%
- Category 3
- Lifetime 20 years

Data for EN IEC 62061, EN IEC 61508, EN IEC 61800-5-2

- SIL 2 Capability, SILCL 2
- PFH (Probability of Dangerous failure per Hour)=1E-10/h
- SFF (Safe Failure Fraction) >99%
- HFT (Hardware Fault Tolerance)=0 (1001 architecture)
- Lifetime 20 years

Data for EN IEC 61508 low demand

- PFDavg for one year proof test: 1E-10
- PFDavg for three year proof test: 1E-10
- PFDavg for five year proof test: 1E-10

No maintenance of the STO functionality is needed.

Security measures have to be taken by the user e.g. installation in a closed cabinet that is only accessible for skilled personnel.

SISTEMA Data

Functional safety data is available via a data library for use with the SISTEMA calculation tool from the IFA (Institute for Occupational Safety and Health of the German Social Accident Insurance), and data for manual calculation. The library is permanently completed and extended.

2.5.1 Terminal 37 Safe Stop Function

The frequency converter is available with safe stop functionality via control terminal 37. Safe stop disables the control voltage of the power semiconductors of the frequency converter output stage. This in turn prevents generating the voltage required to rotate the motor. When the Safe Stop (T37) is activated, the frequency converter issues an alarm, trips the unit, and coasts the motor to a stop. Manual restart is required. The safe stop function can be used as an emergency stop for the frequency converter. In normal operating mode when safe stop is not required, use the regular stop function instead. When automatic restart is used, ensure the requirements of ISO 12100-2 paragraph 5.3.2.5 are fulfilled.

Liability Conditions

It is the responsibility of the user to ensure that qualified personnel installs and operates the safe stop function:

- Read and understand the safety regulations concerning health and safety/accident prevention
- Understand the generic and safety guidelines given in this description and the extended description in the relevant *Design Guide*
- Have a good knowledge of the generic and safety standards applicable to the specific application

User is defined as: integrator, operator, service technician, maintenance technician.

Standards

Use of safe stop on terminal 37 requires that the user satisfies all provisions for safety including relevant laws, regulations and guidelines. The optional safe stop function complies with the following standards.

- IEC 60204-1: 2005 category 0 – uncontrolled stop
- IEC 61508: 1998 SIL2
- IEC 61800-5-2: 2007 – safe torque off (STO) function
- IEC 62061: 2005 SIL CL2
- ISO 13849-1: 2006 Category 3 PL d
- ISO 14118: 2000 (EN 1037) – prevention of unexpected startup

The information and instructions of the instruction manual are not sufficient for a proper and safe use of the safe stop functionality. The related information and instructions of the relevant *Design Guide* must be followed.

Protective Measures

- Qualified and skilled personnel are required for installation and commissioning of safety engineering systems
- The unit must be installed in an IP54 cabinet or in an equivalent environment. In special applications a higher IP degree is required
- The cable between terminal 37 and the external safety device must be short circuit protected according to ISO 13849-2 table D.4
- When external forces influence the motor axis (for example, suspended loads), additional measures are required (for example, a safety holding brake) to eliminate potential hazards

Safe Stop Installation and Set-Up

⚠ WARNING

SAFE STOP FUNCTION!

The safe stop function does NOT isolate mains voltage to the frequency converter or auxiliary circuits. Perform work on electrical parts of the frequency converter or the motor only after isolating the mains voltage supply and waiting the length of time specified in Table 1.1. Failure to isolate the mains voltage supply from the unit and waiting the time specified could result in death or serious injury.

- It is not recommended to stop the frequency converter by using the Safe Torque Off function. If a running frequency converter is stopped by using the function, the unit trips and stops by coasting. If unacceptable or dangerous, use another stopping mode to stop the frequency converter and machinery, before using this function. Depending on the application, a mechanical brake can be required.
- For synchronous and permanent magnet motor frequency converters, in a multiple IGBT power semiconductor failure: In spite of the activation of the Safe Torque Off function, the system can produce an alignment torque which maximally rotates the motor shaft by 180/p degrees. p denotes the pole pair number.
- This function is suitable for performing mechanical work on the system or affected area of a machine only. It does not provide electrical safety. Do not use this function as a control for starting and/or stopping the frequency converter.

Follow these steps to perform a safe installation of the frequency converter:

1. Remove the jumper wire between control terminals 37 and 12 or 13. Cutting or breaking

the jumper is not sufficient to avoid short-circuiting. (See jumper on *Illustration 2.21*.)

2. Connect an external Safety monitoring relay via a NO safety function to terminal 37 (safe stop) and either terminal 12 or 13 (24 V DC). Follow the instruction for the safety device. The Safety monitoring relay must comply with Category 3 /PL "d" (ISO 13849-1) or SIL 2 (EN 62061).

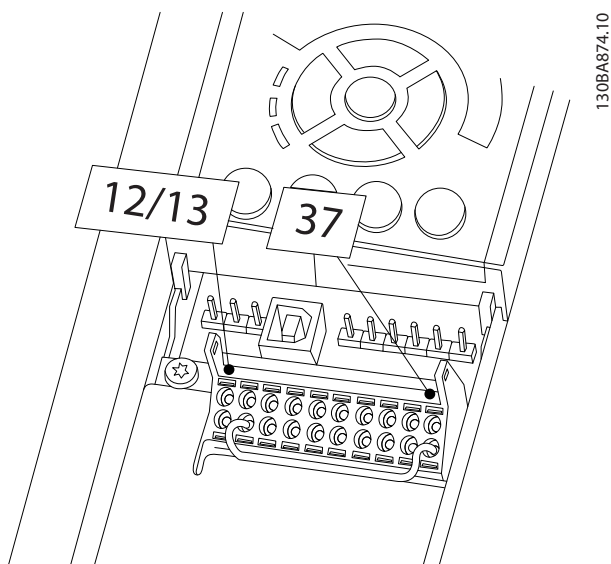


Illustration 2.21 Jumper between Terminal 12/13 (24 V) and 37

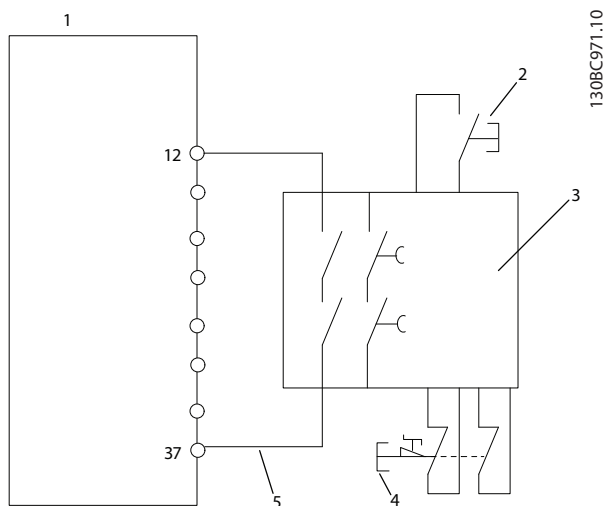


Illustration 2.22 Installation to Achieve a Stopping Category 0 (EN 60204-1) with Cat. 3 /PL "d" (ISO 13849-1) or SIL 2 (EN 62061).

1	Frequency converter
2	[Reset] key
3	Safety relay (cat. 3, PL d or SIL2)
4	Emergency stop button
5	Short-circuit protected cable (if not inside installation IP54 cabinet)

Table 2.9 Legend to *Illustration 2.22*

Safe Stop Commissioning Test

After installation and before first operation, perform a commissioning test of the installation using safe stop. Moreover, perform the test after each modification of the installation.

WARNING

Safe Stop activation (that is removal of 24 V DC voltage supply to terminal 37) does not provide electrical safety. The Safe Stop function itself is therefore not sufficient to implement the Emergency-Off function as defined by EN 60204-1. Emergency-Off requires measures of electrical isolation, for example, by switching off mains via an additional contactor.

1. Activate the Safe Stop function by removing the 24 V DC voltage supply to the terminal 37.
2. After activation of Safe Stop (that is, after the response time), the frequency converter coasts (stops creating a rotational field in the motor). The response time is typically less than 10 ms.

The frequency converter is guaranteed not to restart creation of a rotational field by an internal fault (in accordance with Cat. 3 PL d acc. EN ISO 13849-1 and SIL 2 acc. EN 62061). After activation of Safe Stop, the display shows the text "Safe Stop activated". The associated help text says, "Safe Stop has been activated". This means that the Safe Stop has been activated, or that normal operation has not been resumed yet after Safe Stop activation.

NOTE

The requirements of Cat. 3 /PL "d" (ISO 13849-1) are only fulfilled while 24 V DC supply to terminal 37 is kept removed or low by a safety device which itself fulfills Cat. 3 PL "d" (ISO 13849-1). If external forces act on the motor, it must not operate without additional measures for fall protection. External forces can arise for example, in the event of vertical axis (suspended loads) where an unwanted movement, for example caused by gravity, could cause a hazard. Fall protection measures can be additional mechanical brakes.

By default the Safe Stop function is set to an Unintended Restart Prevention behaviour. Therefore, to resume operation after activation of Safe Stop,

1. reapply 24 V DC voltage to terminal 37 (text Safe Stop activated is still displayed)
2. create a reset signal (via bus, Digital I/O, or [Reset] key).

The Safe Stop function can be set to an Automatic Restart behaviour. Set the value of *5-19 Terminal 37 Safe Stop* from default value [1] to value [3].

Automatic Restart means that Safe Stop is terminated, and normal operation is resumed, as soon as the 24 V DC are applied to Terminal 37. No Reset signal is required.

⚠ WARNING

Automatic Restart Behaviour is permitted in one of the two situations:

1. The Unintended Restart Prevention is implemented by other parts of the Safe Stop installation.
2. A presence in the dangerous zone can be physically excluded when Safe Stop is not activated. In particular, paragraph 5.3.2.5 of ISO 12100-2 2003 must be observed

2.5.2 Safe Stop Commissioning Test

After installation and before first operation, perform a commissioning test of an installation or application, using Safe Stop.

Perform the test again after each modification of the installation or application involving the Safe Stop.

NOTE

A passed commissioning test is mandatory after first installation and after each change to the safety installation.

The commissioning test (select one of cases 1 or 2 as applicable):

Case 1: Restart prevention for Safe Stop is required (that is Safe Stop only where *5-19 Terminal 37 Safe Stop* is set to default value [1], or combined Safe Stop and MCB 112 where *5-19 Terminal 37 Safe Stop* is set to [6] PTC 1 & Relay A or [9] PTC 1 & Relay W/A):

1.1 Remove the 24 V DC voltage supply to terminal 37 using the interrupt device while the frequency converter drives the motor (that is mains supply is not interrupted). The test step is passed when

- the motor reacts with a coast, and
- the mechanical brake is activated (if connected)

- the alarm "Safe Stop [A68]" is displayed in the LCP, if mounted

1.2 Send Reset signal (via Bus, Digital I/O, or [Reset] key). The test step is passed if the motor remains in the Safe Stop state, and the mechanical brake (if connected) remains activated.

1.3 Reapply 24 V DC to terminal 37. The test step is passed if the motor remains in the coasted state, and the mechanical brake (if connected) remains activated.

1.4 Send Reset signal (via Bus, Digital I/O, or [Reset] key). The test step is passed when the motor becomes operational again.

The commissioning test is passed if all four test steps 1.1, 1.2, 1.3 and 1.4 are passed.

Case 2: Automatic Restart of Safe Stop is wanted and allowed (that is, Safe Stop only where *5-19 Terminal 37 Safe Stop* is set to [3], or combined Safe Stop and MCB 112 where *5-19 Terminal 37 Safe Stop* is set to [7] PTC 1 & Relay W or [8] PTC 1 & Relay A/W):

2.1 Remove the 24 V DC voltage supply to terminal 37 by the interrupt device while the frequency converter drives the motor (that is mains supply is not interrupted). The test step is passed when

- the motor reacts with a coast, and
- the mechanical brake is activated (if connected)
- the alarm "Safe Stop [A68]" is displayed in the LCP, if mounted

2.2 Reapply 24 V DC to terminal 37.

The test step is passed if the motor becomes operational again. The commissioning test is passed if both test steps 2.1 and 2.2 are passed.

NOTE

See warning on the restart behaviour in *2.5.1 Terminal 37 Safe Stop Function*

⚠ WARNING

The Safe Stop function can be used for asynchronous, synchronous and permanent magnet motors. Two faults can occur in the power semiconductor of the frequency converter. When using synchronous or permanent magnet motors a residual rotation can result from the faults. The rotation can be calculated to $\text{Angle} = 360 / (\text{Number of Poles})$. The application using synchronous or permanent magnet motors must take this residual rotation into consideration and ensure that it does not pose a safety risk. This situation is not relevant for asynchronous motors.

3 Start Up and Functional Testing

3.1 Pre-start

3.1.1 Safety Inspection

⚠ WARNING

HIGH VOLTAGE!

If input and output connections have been connected improperly, there is potential for high voltage on these terminals. If power leads for multiple motors are improperly run in same conduit, there is potential for leakage current to charge capacitors within the frequency converter, even when disconnected from mains input. For initial start up, make no assumptions about power components. Follow pre-start procedures. Failure to follow pre-start procedures could result in personal injury or damage to equipment.

1. Input power to the unit must be OFF and locked out. Do not rely on the frequency converter disconnect switches for input power isolation.
2. Verify that there is no voltage on input terminals L1 (91), L2 (92), and L3 (93), phase-to-phase and phase-to-ground,
3. Verify that there is no voltage on output terminals 96 (U), 97 (V), and 98 (W), phase-to-phase and phase-to-ground.
4. Confirm continuity of the motor by measuring ohm values on U-V (96-97), V-W (97-98), and W-U (98-96).
5. Check for proper grounding of the frequency converter as well as the motor.
6. Inspect the frequency converter for loose connections on terminals.
7. Record the following motor-nameplate data: power, voltage, frequency, full load current, and nominal speed. These values are needed to program motor nameplate data later.
8. Confirm that the supply voltage matches voltage of frequency converter and motor.

CAUTION

Before applying power to the unit, inspect the entire installation as detailed in *Table 3.1*. Check mark those items when completed.

Inspect for	Description	☒
Auxiliary equipment	- Look for auxiliary equipment, switches, disconnects, or input fuses/circuit breakers that may reside on the input power side of the frequency converter or output side to the motor. Ensure that they are ready for full speed operation. - Check function and installation of any sensors used for feedback to the frequency converter - Remove power factor correction caps on motor(s), if present	
Cable routing	Ensure that input power, motor wiring and control wiring are separated or in three separate metallic conduits for high frequency noise isolation	
Control wiring	- Check for broken or damaged wires and loose connections - Check that control wiring is isolated from power and motor wiring for noise immunity - Check the voltage source of the signals, if necessary - The use of shielded cable or twisted pair is recommended. Ensure that the shield is terminated correctly	
Cooling clearance	Measure that top and bottom clearance is adequate to ensure proper air flow for cooling	
EMC considerations	Check for proper installation regarding electromagnetic compatibility	
Environmental considerations	- See equipment label for the maximum ambient operating temperature limits - Humidity levels must be 5-95% non-condensing	
Fusing and circuit breakers	- Check for proper fusing or circuit breakers - Check that all fuses are inserted firmly and in operational condition and that all circuit breakers are in the open position	
Earthing (Grounding)	- The unit requires an earth wire (ground wire) from its chassis to the building earth (ground) - Check for good earth connections (ground connections) that are tight and free of oxidation - Earthing (grounding) to conduit or mounting the back panel to a metal surface is not a suitable earth (ground)	
Input and output power wiring	- Check for loose connections - Check that motor and mains are in separate conduit or separated screened cables	
Panel interior	Inspect that the unit interior is free of dirt, metal chips, moisture, and corrosion	
Switches	Ensure that all switch and disconnect settings are in the proper positions	
Vibration	- Check that the unit is mounted solidly or that shock mounts are used, as necessary - Check for an unusual amount of vibration	

Table 3.1 Start Up Check List

3.2 Applying Power

⚠ WARNING

HIGH VOLTAGE!

Frequency converters contain high voltage when connected to AC mains. Installation, start-up and maintenance should be performed by qualified personnel only. Failure to perform installation, start-up and maintenance by qualified personnel could result in death or serious injury.

⚠ WARNING

UNINTENDED START!

When the frequency converter is connected to AC mains, the motor may start at any time. The frequency converter, motor, and any driven equipment must be in operational readiness. Failure to be in operational readiness when the frequency converter is connected to AC mains could result in death, serious injury, equipment, or property damage.

1. Confirm input voltage is balanced within 3%. If not, correct input voltage imbalance before proceeding. Repeat procedure after voltage correction.
2. Ensure optional equipment wiring, if present, matches installation application.
3. Ensure that all operator devices are in the OFF position. Panel doors closed or cover mounted.
4. Apply power to the unit. DO NOT start the frequency converter at this time. For units with a disconnect switch, turn to the ON position to apply power to the frequency converter.

NOTE

If the status line at the bottom of the LCP reads **AUTO REMOTE COAST**, this indicates that the unit is ready to operate but is missing an input signal on terminal 27.

3.3 Basic Operational Programming

Programming

Frequency converters require basic operational programming before running for best performance. Basic operational programming requires entering motor-nameplate data for the motor being operated and the minimum and maximum motor speeds. Parameter settings recommended are intended for start up and checkout purposes. Application settings may vary. See *4.1 Local Control Panel* for detailed instructions on entering data through the LCP.

Enter data with power ON, but before operating the frequency converter. There are two ways of programming

the frequency converter: either by using the Smart Application Set-up (SAS) or by using the procedure described further down. The SAS is a quick wizard for setting up the most commonly used applications. At first power-up and after a reset the SAS appears on the LCP. Follow the instructions that appear on the successive screens for setting-up the applications listed. SAS can also be found under the Quick Menu. [Info] can be used throughout the Smart Set-up to see help information for various selections, settings and messages.

NOTE

The start conditions will be ignored while in the wizard.

NOTE

If no action is taken after first power-up or reset, the SAS screen will automatically disappear after 10 minutes.

When not using the SAS, enter data in accordance with the following procedure.

1. Press [Main Menu] twice on the LCP.
2. Press the navigation keys to scroll to parameter group and press [OK].

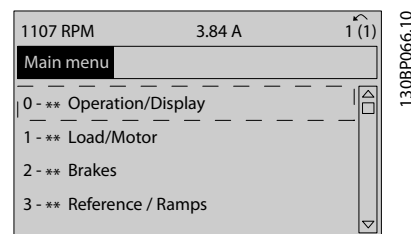


Illustration 3.1 0-** Operation/Display

3. Press the navigation keys to scroll to parameter group 0-0* Basic Settings and press [OK].

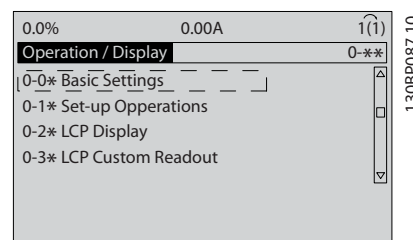


Illustration 3.2 0-0* Basic Settings

4. Press the navigation keys to scroll to *0-03 Regional Settings* and press [OK].

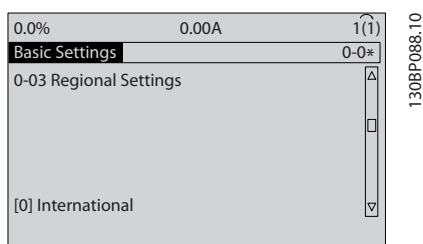


Illustration 3.3 0-03 Regional Settings

5. Press the navigation keys to select *International* or *North America* as appropriate and press [OK]. (This changes the default settings for a number of basic parameters. See for a complete list.)
6. Press [Quick Menu] on the LCP.
7. Press the navigation keys to scroll to parameter group *Q2 Quick Setup* and press [OK].

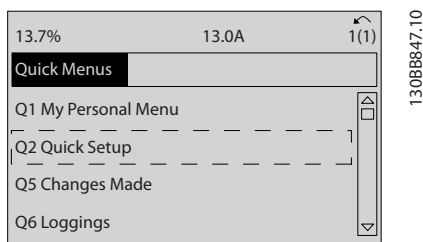


Illustration 3.4 Q2 Quick Setup

8. Select language and press [OK].

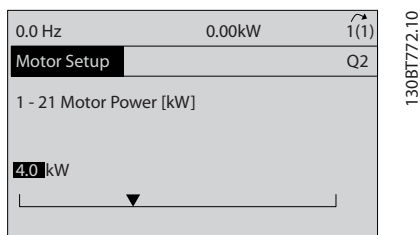


Illustration 3.5 Select Language

9. A jumper wire should be in place between control terminals 12 and 27. If this is the case, leave *5-12 Terminal 27 Digital Input* at factory default. Otherwise select *No Operation*. For frequency converters with an optional bypass, no jumper wire is required.
10. *3-02 Minimum Reference*
11. *3-03 Maximum Reference*
12. *3-41 Ramp 1 Ramp Up Time*
13. *3-42 Ramp 1 Ramp Down Time*

14. *3-13 Reference Site*. Linked to Hand/Auto* Local Remote.

3.4 Asynchronous Motor Setup

Enter the motor data in parameters 1-20/1-21 to 1-25. The information can be found on the motor nameplate.

1. *1-20 Motor Power [kW] or 1-21 Motor Power [HP]*
1-22 Motor Voltage
1-23 Motor Frequency
1-24 Motor Current
1-25 Motor Nominal Speed

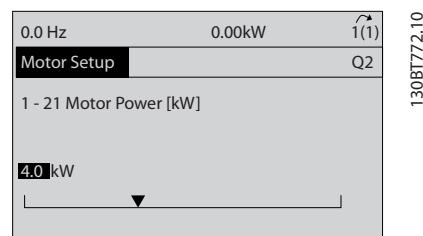


Illustration 3.6 Motor Setup

3.5 PM Motor Setup in VVC^{plus}

CAUTION

Do only use PM motor with fans and pumps.

Initial Programming Steps

1. Activate PM motor operation *1-10 Motor Construction*, select *(1) PM, non salient SPM*
2. Make sure to set *0-02 Motor Speed Unit* to *[0] RPM*

Programming motor data.

After selecting PM motor in *1-10 Motor Construction*, the PM motor-related parameters in parameter groups 1-2*, 1-3* and 1-4* are active.

The information can be found on the motor nameplate and in the motor data sheet.

Following parameters must be programmed in the listed order

1. *1-24 Motor Current*
2. *1-26 Motor Cont. Rated Torque*
3. *1-25 Motor Nominal Speed*
4. *1-39 Motor Poles*
5. *1-30 Stator Resistance (Rs)*
Enter line to common stator winding resistance (Rs). If only line-line data are available, divide the line-line value with 2 to achieve the line to common (starpoint) value.

6. **1-37 d-axis Inductance (Ld)**
Enter line to common direct axis inductance of the PM motor.
If only line-line data are available, divide the line-line value with 2 to achieve the line-common (starpoint) value.
7. **1-40 Back EMF at 1000 RPM**
Enter line to line back EMF of PM Motor at 1000 RPM mechanical speed (RMS value). Back EMF is the voltage generated by a PM motor when no drive is connected and the shaft is turned externally. Back EMF is normally specified for nominal motor speed or for 1000 RPM measured between two lines. If the value is not available for a motor speed of 1000 RPM, calculate the correct value as follows: If back EMF is eg. 320 V at 1800 RPM, it can be calculated at 1000 RPM as follows: Back EMF= (Voltage / RPM)*1000 = (320/1800)*1000 = 178. This is the value that must be programmed for **1-40 Back EMF at 1000 RPM**

Test Motor Operation

1. Start the motor at low speed (100 to 200 RPM). If the motor does not turn, check installation, general programming and motor data.
2. Check if start function in **1-70 PM Start Mode** fits the application requirements.

Rotor detection

This function is the recommended choice for applications where the motor starts from standstill e.g. pumps or conveyors. On some motors, an acoustic sound is heard when the impulse is sent out. This does not harm the motor.

Parking

This function is the recommended choice for applications where the motor is rotating at slow speed eg. windmilling in fan applications. **2-06 Parking Current** and **2-07 Parking Time** can be adjusted. Increase the factory setting of these parameters for applications with high inertia.

Start the motor at nominal speed. In case the application does not run well, check the VVC^{plus} PM settings. Recommendations in different applications can be seen in **Table 3.2**.

Application	Settings
Low inertia applications $I_{Load}/I_{Motor} < 5$	1-17 Voltage filter time const. to be increased by factor 5 to 10 1-14 Damping Gain should be reduced 1-66 Min. Current at Low Speed should be reduced (<100%)
Low inertia applications $50 > I_{Load}/I_{Motor} > 5$	Keep calculated values
High inertia applications $I_{Load}/I_{Motor} > 50$	1-14 Damping Gain, 1-15 Low Speed Filter Time Const. and 1-16 High Speed Filter Time Const. should be increased
High load at low speed <30% (rated speed)	1-17 Voltage filter time const. should be increased 1-66 Min. Current at Low Speed should be increased (>100% for longer time can overheat the motor)

Table 3.2 Recommendations in Different Applications

If the motor starts oscillating at a certain speed, increase **1-14 Damping Gain**. Increase the value in small steps. Depending on the motor, a good value for this parameter can be 10% or 100% higher than the default value.

Starting torque can be adjusted in **1-66 Min. Current at Low Speed**. 100% provides nominal torque as starting torque.

3.6 Automatic Motor Adaptation

Automatic motor adaptation (AMA) is a test procedure that measures the electrical characteristics of the motor to optimize compatibility between the frequency converter and the motor.

- The frequency converter builds a mathematical model of the motor for regulating output motor current. The procedure also tests the input phase balance of electrical power. It compares the motor characteristics with the data entered in parameters **1-20 Motor Power [kW]** to **1-25 Motor Nominal Speed**.
- It does not cause the motor to run or harm to the motor
- Some motors may be unable to run the complete version of the test. In that case, select **Enable reduced AMA**
- If an output filter is connected to the motor, select **Enable reduced AMA**
- If warnings or alarms occur, see **8 Warnings and Alarms**
- Run this procedure on a cold motor for best results

To run AMA

1. Press [Main Menu] to access parameters.
2. Scroll to parameter group 1-** *Load and Motor*.
3. Press [OK].
4. Scroll to parameter group 1-2* *Motor Data*.
5. Press [OK].
6. Scroll to 1-29 *Automatic Motor Adaptation (AMA)*.
7. Press [OK].
8. Select *Enable complete AMA*.
9. Press [OK].
10. Follow on-screen instructions.
11. The test will run automatically and indicate when it is complete.

3.7 Check Motor Rotation

Before running the frequency converter, check the motor rotation.

1. Press [Hand On].
2. Press [▶] for positive speed reference.
3. Check that the speed displayed is positive.

When 1-06 *Clockwise Direction* is set to [0] *Normal* (default clockwise):

- 4a. Verify that the motor turns clockwise.
- 5a. Verify that the LCP direction arrow is clockwise.

When 1-06 *Clockwise Direction* is set to [1] *Inverse* (counter-clockwise):

- 4b. Verify that the motor turns counter-clockwise.
- 5b. Verify that the LCP direction arrow is counter-clockwise.

3.8 Check Encoder Rotation

Check encoder rotation only if encoder feedback is used.
Check encoder rotation in default open loop control.

1. Verify that the encoder connection is according to *Illustration 3.7*:

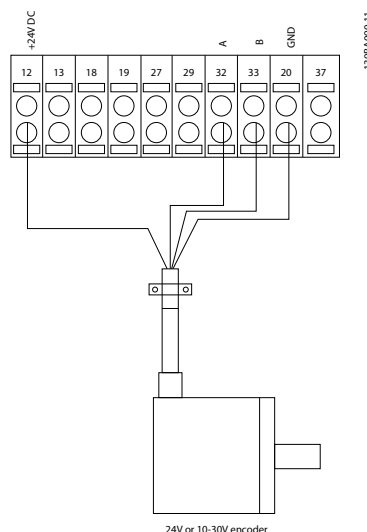


Illustration 3.7 Wiring Diagram

NOTE

When using an encoder option, refer to the option manual

2. Enter the Speed PID feed-back source in 7-00 *Speed PID Feedback Source*.
3. Press [Hand On]
4. Press [▶] for positive speed reference (1-06 *Clockwise Direction* at [0] *Normal*).
5. Check in 16-57 *Feedback [RPM]* that the feed-back is positive

NOTE

If the feedback is negative, the encoder connection is wrong!

3.9 Local-control Test

CAUTION

MOTOR START!

Ensure that the motor, system, and any attached equipment is ready for start. It is the responsibility of the user to ensure safe operation under any operational condition. Failure to ensure that the motor, system, and any attached equipment is ready for start could result in personal injury or equipment damage.

NOTE

The Hand on key on the LCP provides a local start command to the frequency converter. The [Off] key provides the stop function.

When operating in local mode, the up and down arrows on the LCP increase and decrease the speed output of the LCP. The left and right arrow keys move the display cursor in the numeric display.

1. Press [Hand On].
2. Accelerate the frequency converter by pressing [▲] to full speed. Moving the cursor left of the decimal point provides quicker input changes.
3. Note any acceleration problems.
4. Press [Off].
5. Note any deceleration problems.

If acceleration problems were encountered

- If warnings or alarms occur, see *8 Warnings and Alarms*
- Check that motor data is entered correctly
- Increase the ramp-up time in *3-41 Ramp 1 Ramp Up Time*
- Increase current limit in *4-18 Current Limit*
- Increase torque limit in *4-16 Torque Limit Motor Mode*

If deceleration problems were encountered

- If warnings or alarms occur, see *8 Warnings and Alarms*
- Check that motor data is entered correctly
- Increase the ramp-down time in *3-42 Ramp 1 Ramp Down Time*
- Enable overvoltage control in *2-17 Over-voltage Control*

See *8.4 Warning and Alarm Definitions* for resetting the frequency converter after a trip.

NOTE

3.1 Pre-start through *3.9 Local-control Test* in this chapter conclude the procedures for applying power to the frequency converter, basic programming, set-up, and functional testing.

3.10 System Start Up

The procedure in this section requires user-wiring and application programming to be completed. *6 Application Examples* is intended to help with this task. Other aids to application set-up are listed in *1.2 Additional Resources*. The following procedure is recommended after application set-up by the user is completed.

CAUTION

MOTOR START!

Ensure that the motor, system, and any attached equipment is ready for start. It is the responsibility of the user to ensure safe operation under any operational condition. Failure to ensure that the motor, system, and any attached equipment is ready for start could result in personal injury or equipment damage.

1. Press [Auto On].
2. Ensure that external control functions are properly wired to the frequency converter and all programming completed.
3. Apply an external run command.
4. Adjust the speed reference throughout the speed range.
5. Remove the external run command.
6. Note any problems.

If warnings or alarms occur, see *8 Warnings and Alarms*.

4 User Interface

4.1 Local Control Panel

The local control panel (LCP) is the combined display and keypad on the front of the unit. The LCP is the user interface to the frequency converter.

The LCP has several user functions.

- Start, stop, and control speed when in local control
- Display operational data, status, warnings and cautions
- Programming frequency converter functions
- Manually reset the frequency converter after a fault when auto-reset is inactive

An optional numeric LCP (NLCP) is also available. The NLCP operates in a manner similar to the LCP. See the Programming Guide for details on use of the NLCP.

NOTE

The display contrast can be adjusted by pressing [Status] and [▲]/[▼] key.

4.1.1 LCP Layout

The LCP is divided into four functional groups (see *Illustration 4.1*).

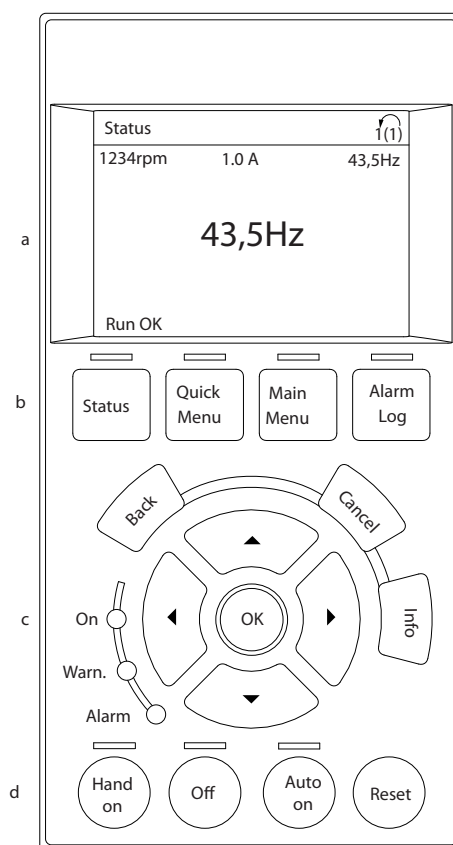


Illustration 4.1 LCP

- Display area.
- Display menu keys for changing the display to show status options, programming, or error message history.
- Navigation keys for programming functions, moving the display cursor, and speed control in local operation. Also included are the status indicator lights.
- Operational mode keys and reset.

4.1.2 Setting LCP Display Values

The display area is activated when the frequency converter receives power from mains voltage, a DC bus terminal, or an external 24 V supply.

The information displayed on the LCP can be customized for user application.

- Each display readout has a parameter associated with it.
- Options are selected in main menu 0-2* LCP Display
- The frequency converter status at the bottom line of the display is generated automatically and is not selectable. See 7 Status Messages for definitions and details.

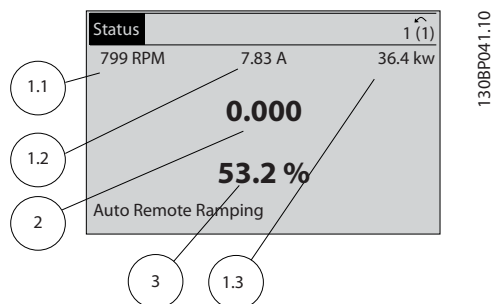


Illustration 4.2 Display Readouts

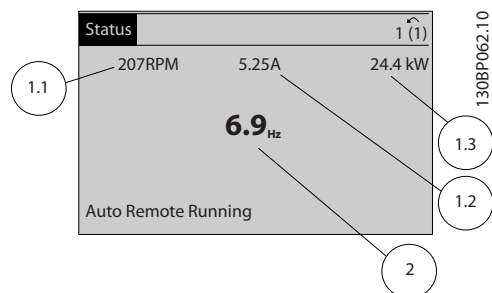


Illustration 4.3 Display Readouts

Display	Parameter number	Default setting
1.1	0-20	Speed [RPM]
1.2	0-21	Motor Current
1.3	0-22	Power [kW]
2	0-23	Frequency
3	0-24	Reference [%]

Table 4.1 Legend to Illustration 4.2 and Illustration 4.3

4.1.3 Display Menu Keys

Menu keys are used for menu access for parameter set-up, toggling through status display modes during normal operation, and viewing fault log data.



Illustration 4.4 Menu Keys

Key	Function
Status	Press to show operational information. • In Auto mode, press and hold to toggle between status read-out displays • Press repeatedly to scroll through each status display • Press and hold [Status] plus [▲] or [▼] to adjust the display brightness • The symbol in the upper right corner of the display shows the direction of motor rotation and which set-up is active. This is not programmable.
Quick Menu	Allows access to programming parameters for initial set up instructions and many detailed application instructions. • Press to access Q2 Quick Setup for sequenced instructions to program the basic frequency controller set up • Follow the sequence of parameters as presented for the function set-up
Main Menu	Allows access to all programming parameters. • Press twice to access top-level index • Press once to return to the last location accessed • Press and hold to enter a parameter number for direct access to that parameter
Alarm Log	Displays a list of current warnings, the last 5 alarms, and the maintenance log. • For details about the frequency converter before it entered the alarm mode, select the alarm number using the navigation keys and press [OK].

Table 4.2 Legend to Illustration 4.4

4.1.4 Navigation Keys

Navigation keys are used for programming functions and moving the display cursor. The navigation keys also provide speed control in local (hand) operation. Three frequency converter status indicator lights are also located in this area.

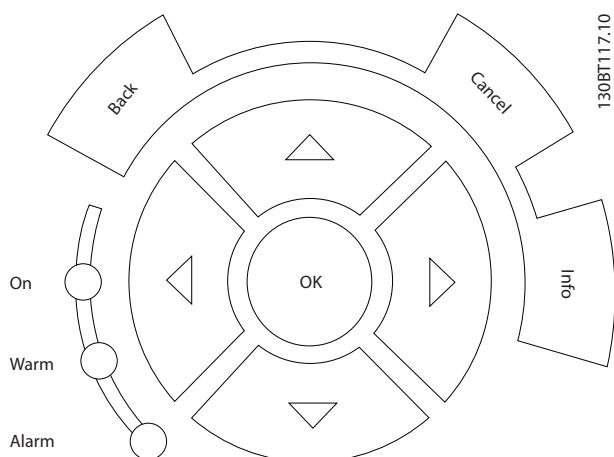


Illustration 4.5 Navigation Keys

Key	Function
Back	Reverts to the previous step or list in the menu structure.
Cancel	Cancels the last change or command as long as the display mode has not changed.
Info	Press for a definition of the function being displayed.
Navigation Keys	Use the four navigation keys to move between items in the menu.
OK	Use to access parameter groups or to enable a choice.

Table 4.3 Navigation Keys Functions

Light	Indicator	Function
Green	ON	The ON light activates when the frequency converter receives power from mains voltage, a DC bus terminal, or an external 24 V supply.
Yellow	WARN	When warning conditions are met, the yellow WARN light comes on and text appears in the display area identifying the problem.
Red	ALARM	A fault condition causes the red alarm light to flash and an alarm text is displayed.

Table 4.4 Indicator Lights Functions

4.1.5 Operation Keys

Operation keys are found at the bottom of the LCP.

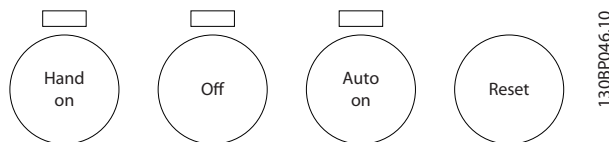


Illustration 4.6 Operation Keys

Key	Function
Hand On	Starts the frequency converter in local control. - Use the navigation keys to control frequency converter speed - An external stop signal by control input or serial communication overrides the local hand on
Off	Stops the motor but does not remove power to the frequency converter.
Auto On	Puts the system in remote operational mode. - Responds to an external start command by control terminals or serial communication - Speed reference is from an external source
Reset	Resets the frequency converter manually after a fault has been cleared.

Table 4.5 Operation Keys Functions

4.2 Back Up and Copying Parameter Settings

Programming data is stored internally in the frequency converter.

- The data can be uploaded into the LCP memory as a storage back up
- Once stored in the LCP, the data can be downloaded back into the frequency converter
- Data can also be downloaded into other frequency converters by connecting the LCP into those units and downloading the stored settings. (This is a quick way to program multiple units with the same settings).
- Initialisation of the frequency converter to restore factory default settings does not change data stored in the LCP memory

⚠ WARNING

UNINTENDED START!

When the frequency converter is connected to AC mains, the motor may start at any time. The frequency converter, motor, and any driven equipment must be in operational readiness. Failure to be in operational readiness when the frequency converter is connected to AC mains could result in death, serious injury, or equipment or property damage.

4

4.2.1 Uploading Data to the LCP

1. Press [Off] to stop the motor before uploading or downloading data.
2. Go to *0-50 LCP Copy*.
3. Press [OK].
4. Select *All to LCP*.
5. Press [OK]. A progress bar shows the uploading process.
6. Press [Hand On] or [Auto On] to return to normal operation.

4.2.2 Downloading Data from the LCP

1. Press [Off] to stop the motor before uploading or downloading data.
2. Go to *0-50 LCP Copy*.
3. Press [OK].
4. Select *All from LCP*.
5. Press [OK]. A progress bar shows the downloading process.
6. Press [Hand On] or [Auto On] to return to normal operation.

4.3 Restoring Default Settings

CAUTION

Initialisation restores the unit to factory default settings. Any programming, motor data, localization, and monitoring records will be lost. Uploading data to the LCP provides a backup before initialisation.

Restoring the frequency converter parameter settings back to default values is done by initialisation of the frequency converter. Initialisation can be through *14-22 Operation Mode* or manually.

- Initialisation using *14-22 Operation Mode* does not change frequency converter data such as operating hours, serial communication selections,

personal menu settings, fault log, alarm log, and other monitoring functions

- Using *14-22 Operation Mode* is generally recommended
- Manual initialisation erases all motor, programming, localization, and monitoring data and restores factory default settings

4.3.1 Recommended Initialisation

1. Press [Main Menu] twice to access parameters.
2. Scroll to *14-22 Operation Mode*.
3. Press [OK].
4. Scroll to *Initialisation*.
5. Press [OK].
6. Remove power to the unit and wait for the display to turn off.
7. Apply power to the unit.

Default parameter settings are restored during start up. This may take slightly longer than normal.

8. Alarm 80 is displayed.
9. Press [Reset] to return to operation mode.

4.3.2 Manual Initialisation

1. Remove power to the unit and wait for the display to turn off.
2. Press and hold [Status], [Main Menu], and [OK] at the same time and apply power to the unit.

Factory default parameter settings are restored during start up. This may take slightly longer than normal.

Manual initialisation does reset not the following frequency converter information

- *15-00 Operating hours*
- *15-03 Power Up's*
- *15-04 Over Temp's*
- *15-05 Over Volt's*

5 About Frequency Converter Programming

5.1 Introduction

The frequency converter is programmed for its application functions using parameters. Parameters are accessed by pressing either [Quick Menu] or [Main Menu] on the LCP. (See 4 *User Interface* for details on using the LCP function keys.) Parameters may also be accessed through a PC using the MCT 10 Set-up Software (see 5.6.1 *Remote Programming with MCT 10 Set-up Software*).

The quick menu is intended for initial start up (Q2-** *Quick Set Up*). Data entered in a parameter can change the options available in the parameters following that entry.

The main menu accesses all parameters and allows for advanced frequency converter applications.

5.2 Programming Example

Here is an example for programming the frequency converter for a common application in open loop using the quick menu.

- This procedure programs the frequency converter to receive a 0-10 V DC analog control signal on input terminal 53
- The frequency converter will respond by providing 6-60 Hz output to the motor proportional to the input signal (0-10 V DC = 6-60 Hz)

Select the following parameters using the navigation keys to scroll to the titles and press [OK] after each action.

1. 3-15 *Reference Resource 1*

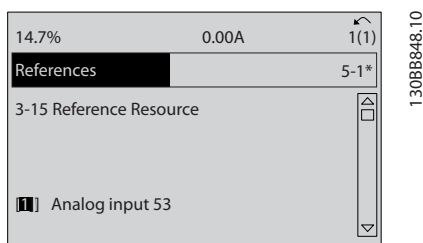


Illustration 5.1 3-15 *Reference Resource 1*

2. 3-02 *Minimum Reference*. Set minimum internal frequency converter reference to 0 Hz. (This sets the minimum frequency converter speed at 0 Hz.)

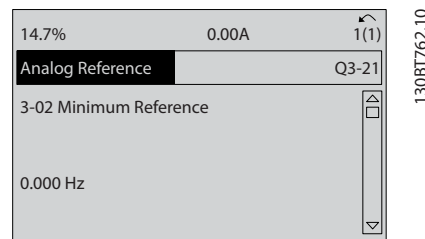


Illustration 5.2 3-02 *Minimum Reference*

3. 3-03 *Maximum Reference*. Set maximum internal frequency converter reference to 60 Hz. (This sets the maximum frequency converter speed at 60 Hz. Note that 50/60 Hz is a regional variation.)

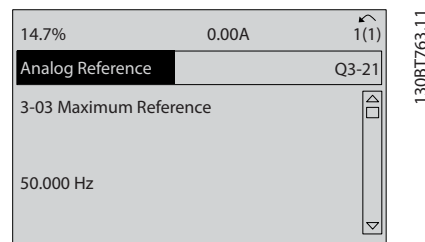


Illustration 5.3 3-03 *Maximum Reference*

4. 6-10 *Terminal 53 Low Voltage*. Set minimum external voltage reference on Terminal 53 at 0 V (this sets the minimum input signal at 0 V).

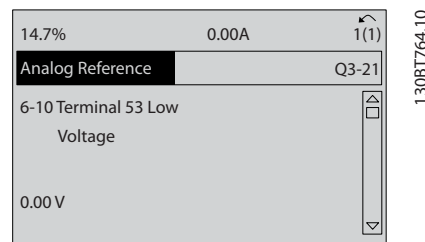


Illustration 5.4 6-10 *Terminal 53 Low Voltage*

5. 6-11 Terminal 53 High Voltage. Set maximum external voltage reference on Terminal 53 at 10 V (this sets the maximum input signal at 10 V).

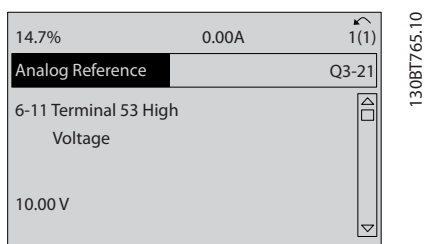


Illustration 5.5 6-11 Terminal 53 High Voltage

6. 6-14 Terminal 53 Low Ref./Feedb. Value. Set minimum speed reference on Terminal 53 at 6 Hz (this tells the frequency converter that the minimum voltage received on Terminal 53 (0 V) equals 6 Hz output).

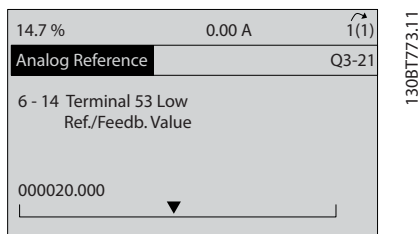


Illustration 5.6 6-14 Terminal 53 Low Ref./Feedb. Value

7. 6-15 Terminal 53 High Ref./Feedb. Value. Set maximum speed reference on Terminal 53 at 60 Hz (this tells the frequency converter that the maximum voltage received on Terminal 53 (10 V) equals 60 Hz output).

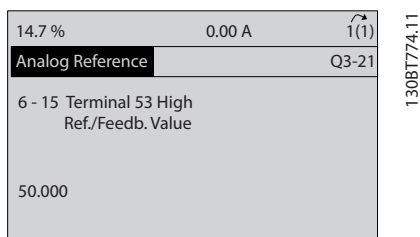


Illustration 5.7 6-15 Terminal 53 High Ref./Feedb. Value

With an external device providing a 0-10 V control signal connected to frequency converter terminal 53, the system is now ready for operation.

NOTE

When the procedure is complete, the scroll bar is at the bottom.

Illustration 5.8 shows the wiring connections used to enable this set up.

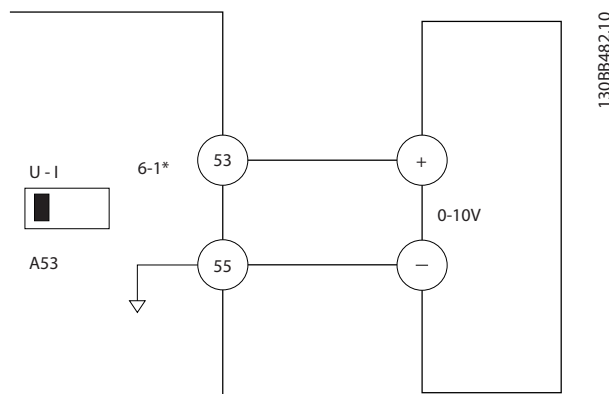


Illustration 5.8 Wiring Example for External Device Providing 0-10 V Control Signal (frequency converter left, external device right)

5.3 Control Terminal Programming Examples

Control terminals can be programmed.

- Each terminal has specified functions it is capable of performing
- Parameters associated with the terminal enable the function

See Table 2.5 for control terminal parameter number and default setting. (Default setting can change based on the selection in 0-03 Regional Settings.)

The following example shows accessing Terminal 18 to see the default setting.

1. Press [Main Menu] twice, scroll to parameter group 5-** Digital In/Out Parameter Data Set and press [OK].

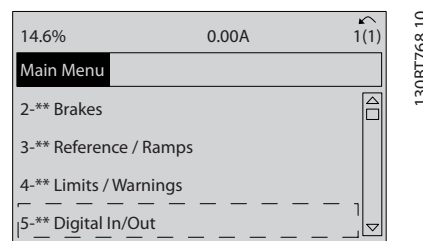


Illustration 5.9 6-15 Terminal 53 High Ref./Feedb. Value

2. Scroll to parameter group 5-1* *Digital Inputs* and press [OK].

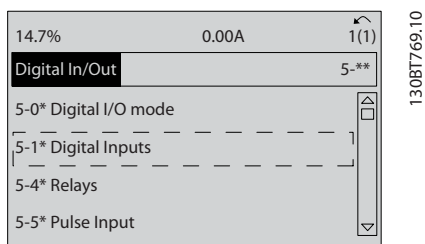


Illustration 5.10 Digital In/Out

3. Scroll to 5-10 *Terminal 18 Digital Input*. Press [OK] to access function choices. The default setting *Start* is shown.

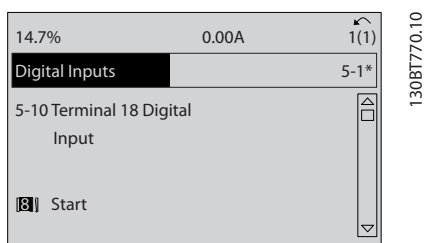


Illustration 5.11 Digital Inputs

5.4 International/North American Default Parameter Settings

Setting 0-03 *Regional Settings* to [0] *International* or [1] *North America* changes the default settings for some parameters. Table 5.1 lists those parameters that are effected.

Parameter	International default parameter value	North American default parameter value
0-03 Regional Settings	International	North America
1-20 Motor Power [kW]	See Note 1	See Note 1
1-21 Motor Power [HP]	See Note 2	See Note 2
1-22 Motor Voltage	230 V/400 V/575 V	208 V/460 V/575 V
1-23 Motor Frequency	50 Hz	60 Hz
3-03 Maximum Reference	50 Hz	60 Hz
3-04 Reference Function	Sum	External/Preset
4-13 Motor Speed High Limit [RPM] See Note 3 and 5	1500 RPM	1800 RPM

Parameter	International default parameter value	North American default parameter value
4-14 Motor Speed High Limit [Hz] See Note 4	50 Hz	60 Hz
4-19 Max Output Frequency	132 Hz	120 Hz
4-53 Warning Speed High	1500 RPM	1800 RPM
5-12 Terminal 27 Digital Input	Coast inverse	External interlock
5-40 Function Relay	No operation	No alarm
6-15 Terminal 53 High Ref./Feedb. Value	50	60
6-50 Terminal 42 Output	No operation	Speed 4-20 mA
14-20 Reset Mode	Manual reset	Infinite auto reset

Table 5.1 International/North American Default Parameter Settings

Note 1: 1-20 Motor Power [kW] is only visible when 0-03 *Regional Settings* is set to [0] *International*.

Note 2: 1-21 Motor Power [HP], is only visible when 0-03 *Regional Settings* is set to [1] *North America*.

Note 3: This parameter is only visible when 0-02 *Motor Speed Unit* is set to [0] *RPM*.

Note 4: This parameter is only visible when 0-02 *Motor Speed Unit* is set to [1] *Hz*.

Note 5: The default value depends on the number of motor poles. For a 4 poled motor the international default value is 1500 RPM and for a 2 poled motor 3000 RPM. The corresponding values for North America is 1800 and 3600 RPM, respectively.

Changes made to default settings are stored and available for viewing in the quick menu along with any programming entered into parameters.

1. Press [Quick Menu].
2. Scroll to Q5 *Changes Made* and press [OK].

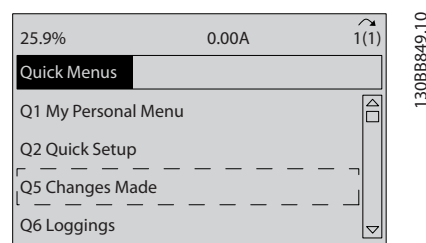


Illustration 5.12 Q5 Changes Made

3. Select *Q5-2 Since Factory Setting* to view all programming changes or *Q5-1 Last 10 Changes* for the most recent.

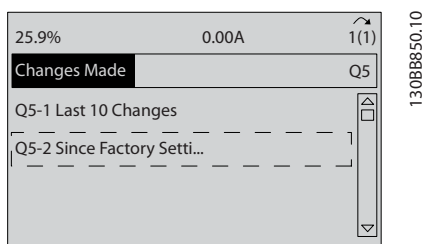


Illustration 5.13 *Q5-2 Since Factory Setting*

5

5.5 Parameter Menu Structure

Establishing the correct programming for applications often requires setting functions in several related parameters. These parameter settings provide the frequency converter with system details for the frequency converter to operate properly. System details may include such things as input and output signal types, programming terminals, minimum and maximum signal ranges, custom displays, automatic restart, and other features.

- See the LCP display to view detailed parameter programming and setting options.
- Press [Info] in any menu location to view additional details for that function.
- Press and hold [Main Menu] to enter a parameter number for direct access to that parameter.
- Details for common application set ups are provided in *6 Application Examples*.

5.5.1 Main Menu Structure

0-0* Operation / Display		1-06 Clockwise Direction		1-72 Start Function		3-04 References		4-10 Motor Speed Direction	
0-01 Basic Settings	1-07 Motor Angle Offset Adjust	1-10 Motor Construction	1-73 Flying Start	1-74 Start Speed [RPM]	3-10 Preset Reference	4-11 Motor Speed Low Limit [RPM]		4-12 Motor Speed Low Limit [Hz]	
0-02 Motor Speed Unit	1-11 Motor Model	1-12 Damping Gain	1-75 Start Speed [Hz]	1-76 Start Current	3-11 Jog Speed [Hz]	4-13 Motor Speed High Limit [RPM]		4-14 Motor Speed High Limit [Hz]	
0-03 Regional Settings	1-14 Low Speed Filter Time Const.	1-15 High Speed Filter Time Const.	1-80* Stop Adjustments	1-81 Min Speed for Function at Stop [RPM]	3-12 Catch up/slow Down Value	4-16 Torque Limit Motor Mode		4-17 Torque Limit Generator Mode	
0-04 Operating State at Power-up (Hand)	1-16 Voltage filter time const.	1-17 Motor Data	1-82 Min Speed for Function at Stop [Hz]	1-83 Precise Stop Function	3-13 Reference Site	4-18 Current Limit		4-19 Max Output Frequency	
0-09 Performance Monitor	1-18 Motor Power [kW]	1-19 Motor Power [HP]	1-84 Precise Stop Counter Value	1-85 Precise Stop Speed Compensation Delay	3-14 Preset Relative Reference	4-20 Torque Limit Factor Source		4-21 Speed Limit Factor Source	
0-1* Set-up Operations	1-20 Motor Voltage	1-21 Motor Frequency	1-86 Motor Temperature	1-87 Motor Thermal Protection	3-15 Reference Resource 1	4-22 Motor Speed Mon.		4-23 Motor Feedback Loss Function	
0-10 Active Set-up	1-22 Motor Current	1-23 Motor Nominal Speed	1-88 Motor External Fan	1-89 Thermistor Resource	3-16 Reference Resource 2	4-24 Motor Feedback Speed Error		4-25 Tracking Error Function	
0-11 Edit Set-up	1-24 Motor Cont. Rated Torque	1-25 Automatic Motor Adaptation (AMA)	1-90 KTY Thermistor Resource	1-91 KTY Threshold level	3-17 Reference Resource 3	4-26 Tracking Error Time		4-27 Tracking Error Ramping	
0-12 This Set-up Linked to	1-26 Rotor Resistance (Rs)	1-27 Rotor Resistance (Rr)	1-92 ATEX ETR interpol. points freq.	1-93 ATEX ETR interpol. points current	3-18 Relative Scaling Reference Resource	4-28 Tracking Error Ramping Timeout		4-29 Tracking Error After Ramping Timeout	
0-13 Readout: Linked Set-ups	1-28 Motor Inductance (Ld)	1-29 Motor Inductance (Lq)	2-00 DC Hold Current	2-01 DC Brake Current	3-19 Jog Speed [RPM]	4-30 Ramp 1		4-31 Ramp 2	
0-14 Readout: Edit Set-ups / Channel	1-30 Motor Poles	1-31 Motor Angle Offset	2-02 DC Braking Time	2-03 DC Brake Cut In Speed [RPM]	3-20 Ramp 1	4-32 Ramp 1 Ramp Up Time		4-33 Ramp 1 Ramp Down Time	
0-15 Readout: actual setup	1-32 Motor Angle Offset	1-33 d-axis Inductance (Ld)	2-04 DC Brake Cut In Speed [Hz]	2-05 Maximum Reference	3-21 Ramp 2	4-34 Ramp 1 S-ramp Ratio at Accel. Start		4-35 Ramp 1 S-ramp Ratio at Decel. End	
0-2* LCP Display	1-34 Rotor Leakage Reactance (Xl)	1-35 Main Reactance (Xh)	2-06 Parking Current	2-07 Brake Energy Funct.	3-22 Ramp 3	4-36 Ramp 1 S-ramp Ratio at Accel. Start		4-37 Ramp 1 S-ramp Ratio at Decel. End	
0-20 Display Line 1.1 Small	1-36 Iron Loss Resistance (Rfe)	1-37 d-axis Inductance (Ld)	2-10 Brake Function	2-11 Brake Resistor (ohm)	3-23 Ramp 4	4-38 Tracking Error Ramping Timeout		4-39 Tracking Error After Ramping Timeout	
0-21 Display Line 1.2 Small	1-38 Motor Poles	1-39 Motor Angle Offset	2-12 Brake Power Limit (kW)	2-13 Brake Power Monitoring	3-24 Ramp 4	4-40 Warning Current Low		4-41 Warning Current High	
0-22 Display Line 1.3 Small	1-40 Back EMF at 1000 RPM	1-41 d-axis Inductance Sat. (LdSat)	2-14 AC brake Max. Current	2-15 Over-voltage Control	3-25 Ramp 4	4-42 Warning Speed Low		4-43 Warning Speed High	
0-23 Display Line 2 Large	1-42 Motor Angle Offset	1-43 d-axis Inductance Sat. (LqSat)	2-16 Over-voltage Condition	2-17 Over-voltage Gain	3-26 Ramp 4	4-44 Warning Reference Low		4-45 Warning Reference High	
0-24 Display Line 3 Large	1-44 Position Detection Gain	1-45 Low Speed Torque Calibration	2-18 Torque Ref	2-19 Torque Ramp Time	3-27 Ramp 4	4-46 Warning Feedback Low		4-47 Warning Feedback High	
0-25 My Personal Menu	1-46 Inductance Sat. Point	1-47 Inductance Sat. Point	2-20 Release Brake Current	2-21 Activate Brake Speed [RPM]	3-28 Ramp 4	4-48 Missing Motor Phase Function		4-49 Speed Bypass	
0-3* LCP Custom Readout	1-48 Motor Magnetisation at Zero Speed	1-49 Min Speed Normal Magnetising [RPM]	2-22 Activate Brake Speed [Hz]	2-23 Activate Brake Delay	3-29 Ramp 4	4-50 Bypass Speed From [RPM]		4-51 Bypass Speed To [RPM]	
0-30 Unit for User-defined Readout	1-50 Min Speed Normal Magnetising [Hz]	1-51 Model Shift Frequency	2-24 Stop Delay	2-25 Brake Release Time	3-30 Ramp 4	4-52 Bypass Speed To [Hz]		4-53 Digital In/Out	
0-31 Min Value of User-defined Readout	1-52 Voltage reduction in fieldweakening	1-53 U/f Characteristic - U	2-26 Torque Ref	2-27 Torque Ramp Time	3-31 Ramp 4	4-54 Digital I/O Mode		4-55 Digital I/O Mode	
0-32 Max Value of User-defined Readout	1-54 Flystart Test Pulses Frequency	1-55 Load Depen. Setting	2-28 Gain Boost Factor	2-29 Reference Limits	3-32 Ramp 4	4-56 Terminal 19 Digital Input		4-57 Terminal 27 Digital Input	
0-33 Display Text 1	1-56 Flystart Test Pulses Frequency	1-57 Low Speed Load Compensation	3-00 Reference Range	3-01 Reference Feedback Unit	3-33 Ramp 4	4-58 Terminal 29 Digital Input		4-59 Terminal 32 Digital Input	
0-34 Display Text 2	1-58 High Speed Load Compensation	1-59 Slip Compensation Time Constant	3-02 Minimum Reference	3-03 Maximum Reference	3-34 Ramp 4	4-60 Terminal 33 Digital Input		4-61 Terminal 30/2 Digital Input	
0-35 Display Text 3	1-59 Slip Compensation Time Constant	1-60 Resonance Dampening	3-03 Reference Range	3-04 Reference Feedback Unit	3-35 Ramp 4	4-62 Terminal 30/3 Digital Input		4-63 Terminal 30/4 Digital Input	
0-4* LCP keypad	1-61 Resonance Dampening Time Constant	1-62 Min. Current at Low Speed	3-04 Reference Range	3-05 Reference Feedback Unit	3-36 Ramp 4	4-64 Terminal 37 Safe Stop		4-65 Terminal X46/1 Digital Input	
0-40 [Hand on] key on LCP	1-63 Load Type	1-64 Minimum Inertia	3-05 Reference Range	3-06 Reference Feedback Unit	3-37 Ramp 4	4-66 Terminal X46/5 Digital Input		4-67 Terminal X46/7 Digital Input	
0-41 [Off] key on LCP	1-65 Load Type	1-66 Minimum Inertia	3-06 Reference Range	3-07 Reference Feedback Unit	3-38 Ramp 4	4-68 Terminal X46/9 Digital Input		4-69 Terminal X46/11 Digital Input	
0-42 [Auto on] key on LCP	1-67 Load Type	1-68 Minimum Inertia	3-07 Reference Range	3-08 Reference Feedback Unit	3-39 Ramp 4	4-69 Terminal X46/11 Digital Input		4-70 Terminal X46/11 Digital Input	
0-43 [Reset] key on LCP	1-68 Load Type	1-69 Minimum Inertia	3-08 Reference Range	3-09 Reference Feedback Unit	3-40 Ramp 4	4-70 Terminal X46/11 Digital Input		4-71 Terminal X46/11 Digital Input	
0-44 [Off/Reset] key on LCP	1-69 Load Type	1-70 Minimum Inertia	3-09 Reference Range	3-10 Reference Feedback Unit	3-41 Ramp 4	4-71 Terminal X46/11 Digital Input		4-72 Terminal X46/11 Digital Input	
0-45 [Drive Bypass] key on LCP	1-70 Load Type	1-71 Minimum Inertia	3-10 Reference Range	3-11 Reference Feedback Unit	3-42 Ramp 4	4-72 Terminal X46/11 Digital Input		4-73 Terminal X46/11 Digital Input	
0-5* Copy/Save	1-71 Load Type	1-72 Minimum Inertia	3-11 Reference Range	3-12 Reference Feedback Unit	3-43 Ramp 4	4-73 Terminal X46/11 Digital Input		4-74 Terminal X46/11 Digital Input	
0-50 LCP Copy	1-72 Load Type	1-73 Minimum Inertia	3-12 Reference Range	3-13 Reference Feedback Unit	3-44 Ramp 4	4-74 Terminal X46/11 Digital Input		4-75 Terminal X46/11 Digital Input	
0-51 Set-up Copy	1-73 Load Type	1-74 Minimum Inertia	3-13 Reference Range	3-14 Reference Feedback Unit	3-45 Ramp 4	4-75 Terminal X46/11 Digital Input		4-76 Terminal X46/11 Digital Input	
0-6* Password	1-74 Load Type	1-75 Minimum Inertia	3-14 Reference Range	3-15 Reference Feedback Unit	3-46 Ramp 4	4-76 Terminal X46/11 Digital Input		4-77 Terminal X46/11 Digital Input	
0-60 Main Menu Password	1-75 Load Type	1-76 Minimum Inertia	3-15 Reference Range	3-16 Reference Feedback Unit	3-47 Ramp 4	4-77 Terminal X46/11 Digital Input		4-78 Terminal X46/11 Digital Input	
0-61 Access to Main Menu w/o Password	1-76 Load Type	1-77 Minimum Inertia	3-16 Reference Range	3-17 Reference Feedback Unit	3-48 Ramp 4	4-78 Terminal X46/11 Digital Input		4-79 Terminal X46/11 Digital Input	
0-65 Quick Menu Password	1-77 Load Type	1-78 Minimum Inertia	3-17 Reference Range	3-18 Reference Feedback Unit	3-49 Ramp 4	4-79 Terminal X46/11 Digital Input		4-80 Terminal X46/11 Digital Input	
0-66 Access to Quick Menu w/o Password	1-78 Load Type	1-79 Minimum Inertia	3-18 Reference Range	3-19 Reference Feedback Unit	3-50 Ramp 4	4-80 Terminal X46/11 Digital Input		4-81 Terminal X46/11 Digital Input	
0-67 Bus Password Access	1-79 Load Type	1-80 Minimum Inertia	3-19 Reference Range	3-20 Reference Feedback Unit	3-51 Ramp 4	4-81 Terminal X46/11 Digital Input		4-82 Terminal X46/11 Digital Input	
0-68 Safety Parameters Password	1-80 Load Type	1-81 Minimum Inertia	3-20 Reference Range	3-21 Reference Feedback Unit	3-52 Ramp 4	4-82 Terminal X46/11 Digital Input		4-83 Terminal X46/11 Digital Input	
0-69 Password Protection of Safety Parameters	1-81 Load Type	1-82 Minimum Inertia	3-21 Reference Range	3-22 Reference Feedback Unit	3-53 Ramp 4	4-83 Terminal X46/11 Digital Input		4-84 Terminal X46/11 Digital Input	
1-0* Load and Motor	1-82 Load Type	1-83 Minimum Inertia	3-22 Reference Range	3-23 Reference Feedback Unit	3-54 Ramp 4	4-84 Terminal X46/11 Digital Input		4-85 Terminal X46/11 Digital Input	
1-01 Configuration Mode	1-83 Load Type	1-84 Minimum Inertia	3-23 Reference Range	3-24 Reference Feedback Unit	3-55 Ramp 4	4-85 Terminal X46/11 Digital Input		4-86 Terminal X46/11 Digital Input	
1-02 Motor Control Principle	1-84 Load Type	1-85 Minimum Inertia	3-24 Reference Range	3-25 Reference Feedback Unit	3-56 Ramp 4	4-86 Terminal X46/11 Digital Input		4-87 Terminal X46/11 Digital Input	
1-01 Flux Motor Feedback Source	1-85 Load Type	1-86 Minimum Inertia	3-25 Reference Range	3-26 Reference Feedback Unit	3-57 Ramp 4	4-87 Terminal X46/11 Digital Input		4-88 Terminal X46/11 Digital Input	
1-03 Torque Characteristics	1-86 Load Type	1-87 Minimum Inertia	3-26 Reference Range	3-27 Reference Feedback Unit	3-58 Ramp 4	4-88 Terminal X46/11 Digital Input		4-89 Terminal X46/11 Digital Input	
1-04 Overload Mode	1-87 Load Type	1-88 Minimum Inertia	3-27 Reference Range	3-28 Reference Feedback Unit	3-59 Ramp 4	4-89 Terminal X46/11 Digital Input		4-90 Terminal X46/11 Digital Input	
1-05 Local Mode Configuration	1-88 Load Type	1-89 Minimum Inertia	3-28 Reference Range	3-29 Reference Feedback Unit	3-60 Ramp 4	4-90 Terminal X46/11 Digital Input		4-91 Terminal X46/11 Digital Input	

5-26	Terminal X46/13 Digital Input	6-25	Terminal 54 High Ref/Feedb. Value	7-32	Process PID Start Speed	8-54	Reversing Select	10-13	Warning Parameter
5-30	5-3* Digital Outputs	6-26	Terminal 54 Filter Time Constant	7-33	Process PID Proportional Gain	8-55	Set-up Select	10-14	Net Reference
5-31	Terminal 27 Digital Output	6-30	6-3* Analog Input 3	7-34	Process PID Integral Time	8-56	Preset Reference Select	10-15	Net Control
5-32	Terminal 29 Digital Output	6-31	Terminal X30/11 Low Voltage	7-35	Process PID Differentiation Time	8-57	Profidrive OFF2 Select	10-20*	COS Filters
5-33	Term X30/6 Digi Out (MCB 101)	6-32	Terminal X30/11 High Voltage	7-36	Process PID Diff. Gain Limit	8-58	Profidrive OFF3 Select	10-20	COS Filter 1
5-33	Term X30/7 Digi Out (MCB 101)	6-34	Term. X30/11 Low Ref/Feedb. Value	7-38	Process PID Feed Forward Factor	8-8*	FC Port Diagnostics	10-21	COS Filter 2
5-40	Relays	6-35	Term. X30/11 High Ref/Feedb. Value	7-39	On Reference Bandwidth	8-80	Bus Message Count	10-22	COS Filter 3
5-41	Function Relay	6-36	Term. X30/11 Filter Time Constant	7-40	7-4* Adv. Process PID 1	8-81	Bus Error Count	10-23	COS Filter 4
5-41	On Delay, Relay	6-40	6-4* Analog Input 4	7-40	Process PID I-part Reset	8-82	Slave Messages Rcvd	10-3*	Parameter Access
5-42	Off Delay, Relay	6-41	Terminal X30/12 Low Voltage	7-41	Process PID Output Neg. Clamp	8-83	Slave Error Count	10-30	Array Index
5-50	5-5* Pulse Input	6-42	Terminal X30/12 High Voltage	7-42	Process PID Output Pos. Clamp	8-9*	Bus Jog	10-31	Store Data Values
5-51	Term. 29 Low Frequency	6-44	Term. X30/12 Low Ref/Feedb. Value	7-43	Process PID Gain Scale at Min. Ref.	8-90	Bus Jog 1 Speed	10-32	DeviceNet Revision
5-52	Term. 29 High Frequency	6-45	Term. X30/12 High Ref/Feedb. Value	7-44	Process PID Gain Scale at Max. Ref.	8-91	Bus Jog 2 Speed	10-33	Store Always
5-53	Term. 29 High Ref/Feedb. Value	6-46	Term. X30/12 Filter Time Constant	7-45	Process PID Feed Fwd Resource	9-9*	PROFidrive	10-34	DeviceNet Product Code
5-54	Pulse Filter Time Constant #29	6-50	6-5* Analog Output 1	7-46	Process PID Feed Fwd Normal/ Inv. Ctrl.	9-00	Setpoint	10-39	DeviceNet F Parameters
5-55	Term. 33 Low Frequency	6-51	Terminal 42 Output	7-48	PCD Feed Forward	9-07	Actual Value	10-5*	CANopen
5-56	Term. 33 High Frequency	6-52	Terminal 42 Output Min Scale	7-49	Process PID Output Normal/ Inv. Ctrl.	9-15	PCD Write Configuration	10-50	Process Data Config Write.
5-57	Term. 33 Low Ref/Feedb. Value	6-53	Terminal 42 Output Max Scale	7-50	7-5* Adv. Process PID II	9-16	PCD Read Configuration	10-51	Process Data Config Read.
5-58	Term. 33 High Ref/Feedb. Value	6-54	Terminal 42 Output Timeout Preset	7-51	Process PID Extended PID	9-18	Node Address	12-0*	Ethernet
5-59	Pulse Filter Time Constant #33	6-55	Analog Output Filter	7-52	Process PID Feed Fwd Gain	9-22	Telegram Selection	12-0*	IP Settings
5-60	5-6* Pulse Output	6-60	Terminal X30/8 Output	7-53	Process PID Feed Fwd Ramp up	9-23	Parameters for Signals	12-00	IP Address Assignment
5-62	Pulse Output Max Freq #27	6-61	Terminal X30/8 Min. Scale	7-54	Process PID Feed Fwd Ramp down	9-27	Parameter Edit	12-01	IP Address
5-63	Terminal 29 Pulse Output Variable	6-62	Terminal X30/8 Max. Scale	7-55	Process PID Ref. Filter Time	9-28	Process Control	12-02	Subnet Mask
5-65	Pulse Output Max Freq #29	6-63	Terminal X30/8 Bus Control	7-57	Process PID Fb. Filter Time	9-44	Fault Message Counter	12-03	Default Gateway
5-66	Terminal X30/6 Pulse Output Variable	6-64	Terminal X30/8 Output Timeout Preset	8-2*	Comm. and Options	9-45	Fault Code	12-04	DHCP Server
5-68	Pulse Output Max Freq #X30/6	6-70	6-7* Analog Output 3	8-01	General Settings	9-52	Fault Number	12-05	Lease Expires
5-70	5-7* 24V Encoder Input	6-71	Terminal X45/1 Output	8-02	Control Site	9-53	Fault Situation Counter	12-06	Name Servers
5-71	Term 32/33 Pulses Per Revolution	6-72	Terminal X45/1 Min. Scale	8-03	Control Word Source	9-63	Profibus Warning Word	12-07	Domain Name
5-71	Term 32/33 Encoder Direction	6-73	Terminal X45/1 Max. Scale	8-04	Control Word Timeout Time	9-64	Actual Baud Rate	12-08	Host Name
5-80	5-8* I/O Options	6-74	Terminal X45/1 Bus Control	8-05	End-of-Timeout Function	9-65	Device Identification	12-09	Physical Address
5-80	AHF Cap Reconnect Delay	6-74	Terminal X45/1 Output Timeout Preset	8-06	Reset Control Word Timeout	9-67	Profile Number	12-10*	Ethernet Link Parameters
5-90	5-9* Bus Controlled	6-80	6-8* Analog Output 4	8-07	Diagnosis Trigger	9-68	Control Word 1	12-11	Link Status
5-90	Digital & Relay Bus Control	6-81	Terminal X45/3 Output	8-08	Readout Filtering	9-71	Status Word 1	12-12	Link Duration
5-93	Pulse Out #27 Bus Control	6-82	Terminal X45/3 Min. Scale	8-1*	Ctrl. Word Settings	9-72	Profibus Save Data Values	12-13	Auto Negotiation
5-94	Pulse Out #27 Timeout Preset	6-83	Terminal X45/3 Max. Scale	8-10	Control Word Profile	9-75	ProfibusDriveReset	12-14	Link Speed
5-95	Pulse Out #29 Bus Control	6-84	Terminal X45/3 Bus Control	8-13	Configurable Status Word STW	9-80	DO Identification	12-14	Link Duplex
5-96	Pulse Out #29 Timeout Preset	6-84	Terminal X45/3 Output Timeout Preset	8-14	Configurable Control Word CTW	9-81	Defined Parameters (1)	12-20*	Process Data
5-97	Pulse Out #X30/6 Bus Control	7-2*	Controllers	8-19	Product Code	9-82	Defined Parameters (2)	12-20	Control Instance
5-98	Pulse Out #X30/6 Timeout Preset	7-0*	Speed PID Ctrl.	8-3*	FC Port Settings	9-83	Defined Parameters (3)	12-21	Process Data Config Write
6-00	6-0* Analog I/O Mode	7-00	Speed PID Feedback Source	8-30	Protocol	9-84	Defined Parameters (4)	12-22	Process Data Config Read
6-00	Live Zero Timeout Time	7-02	Speed PID Proportional Gain	8-31	Address	9-90	Defined Parameters (5)	12-23	Process Data Config Write Size
6-01	Live Zero Timeout Function	7-03	Speed PID Integral Time	8-32	FC Port Baud Rate	9-91	Changed Parameters (1)	12-24	Process Data Config Read Size
6-1*	Analog Input 1	7-04	Speed PID Differentiation Time	8-33	Parity / Stop Bits	9-92	Changed Parameters (2)	12-27	Master Address
6-10	Terminal 53 Low Voltage	7-05	Speed PID Diff. Gain Limit	8-34	Estimated cycle time	9-93	Changed Parameters (3)	12-28	Store Data Values
6-11	Terminal 53 High Voltage	7-06	Speed PID Lowpass Filter Time	8-35	Minimum Response Delay	9-94	Changed Parameters (4)	12-29	Store Always
6-12	Terminal 53 High Voltage	7-07	Speed PID Feedback Gear Ratio	8-36	Max Response Delay	9-99	Changed Parameters (5)	12-3*	EtherNet/IP
6-13	Terminal 53 Low Current	7-08	Speed PID Feed Forward Factor	8-37	Max Inter-Char Delay	10-0*	Profibus Revision Counter	12-30	Warning Parameter
6-14	Terminal 53 High Current	7-09	Speed PID Error Correction w/ Ramp	8-4*	FC MC protocol set	10-0*	CAN Fields	12-31	Net Reference
6-15	Terminal 53 Low Ref/Feedb. Value	7-1*	Torque PI Ctrl.	8-40	Telegram Selection	10-00	Common Settings	12-32	Net Control
6-16	Terminal 53 High Ref/Feedb. Value	7-12	Torque PI Proportional Gain	8-41	Parameters for Signals	10-01	CAN Protocol	12-33	CIP Revision
6-20	6-2* Analog Input 2	7-13	Torque PI Integration Time	8-42	PCD Write Configuration	10-02	Baud Rate Select	12-34	CIP Product Code
6-21	Terminal 54 Low Voltage	7-2*	Process Ctrl. Feedb	8-43	PCD Read Configuration	10-05	MAC ID	12-35	EDS Parameter
6-22	Terminal 54 High Voltage	7-20	Process CL Feedback 1 Resource	8-5*	Digital/Bus	10-06	Readout Transmit Error Counter	12-37	COS Inhibit Timer
6-23	Terminal 54 Low Current	7-22	Process CL Feedback 2 Resource	8-50	Coasting Select	10-07	Readout Receive Error Counter	12-38	COS Filter
6-23	Terminal 54 High Current	7-3*	Process PID Ctrl.	8-51	Quick Select	10-1*	DeviceNet	12-4*	Modbus TCP
6-24	Terminal 54 Low Ref/Feedb. Value	7-30	Process PID Normal/ Inverse Control	8-52	DC Brake Select	10-10	Process Data Type Selection	12-40	Status Parameter
		7-31	Process PID Anti Windup	8-53	Start Select	10-11	Process Data Config Write	12-41	Slave Message Count
						10-12	Process Data Config Read	12-42	Slave Exception Message Count

12-5* EtherCAT	14-10 Mains Failure	15-14 Samples Before Trigger	16-13 Frequency	16-9* Diagnosis Readouts
12-50 Configured Station Alias	14-11 Mains Voltage at Mains Fault	15-2* Historic Log	16-14 Motor current	16-90 Alarm Word
12-51 Configured Station Address	14-12 Function at Mains Imbalance	15-20 Historic Log: Event	16-15 Frequency [%]	16-91 Alarm Word 2
12-5* EtherCAT Status	14-13 Mains Failure Step Factor	15-21 Historic Log: Value	16-16 Torque [Nm]	16-92 Warning Word
12-6* Ethernet PowerLink	14-14 Kin. Backup Time Out	15-22 Historic Log: Time	16-17 Speed [RPM]	16-93 Warning Word 2
12-60 Node ID	14-15 Kin. Backup Trip Recovery Level	15-3* Fault Log	16-18 Motor Thermal	16-94 Ext. Status Word
12-62 SDO Timeout	14-2* Trip Reset	15-30 Fault Log: Error Code	17-2** Feedback Option	
12-63 Basic Ethernet Timeout	14-20 Reset Mode	15-31 Fault Log: Value	17-1* Inc. Enc. Interface	
12-66 Threshold	14-21 Automatic Restart Time	15-32 Fault Log: Time	17-10 Signal Type	
12-67 Threshold Counters	14-22 Operation Mode	15-4* Drive Identification	17-11 Resolution (PPR)	
12-68 Cumulative Counters	14-23 Typecode Setting	15-40 FC Type	17-2* Abs. Enc. Interface	
12-69 Ethernet PowerLink Status	14-24 Trip Delay at Current Limit	15-41 Power Section	17-20 Protocol Selection	
12-8* Other Ethernet Services	14-25 Trip Delay at Torque Limit	15-42 Voltage	17-21 Resolution (Positions/Rev)	
12-80 FTP Server	14-26 Trip Delay at Inverter Fault	15-43 Software Version	17-24 SSL Data Length	
12-81 HTTP Server	14-28 Production Settings	15-44 Ordered Typecode String	17-25 Clock Rate	
12-82 SMTP Service	14-29 Service Code	15-45 Actual Typecode String	17-26 SSL Data Format	
12-89 Transparent Socket Channel Port	14-3* Current Limit Ctrl.	15-46 Frequency Converter Ordering No	17-34 HiPERFACE Baudrate	
12-9* Advanced Ethernet Services	14-30 Current Lim Ctrl, Proportional Gain	15-47 Power Card Ordering No	17-5* Resolver Interface	
12-90 Cable Diagnostic	14-31 Current Lim Ctrl, Integration Time	15-48 LCP Id No	17-50 Poles	
12-91 Auto Cross Over	14-32 Current Lim Ctrl, Filter Time	15-49 SW ID Control Card	17-51 Input Voltage	
12-92 IGMP Snooping	14-35 Stall Protection	15-50 SW ID Power Card	17-52 Input Frequency	
12-93 Cable Error Length	14-4* Energy Optimising	15-51 Frequency Converter Serial Number	17-53 Transformation Ratio	
12-94 Broadcast Storm Protection	14-40 VT Level	15-53 Power Card Serial Number	17-56 Encoder Sim. Resolution	
12-95 Broadcast Storm Filter	14-41 AEO Minimum Magnetisation	15-58 Smart Setup Filename	17-59 Resolver Interface	
12-96 Port Config	14-42 Minimum AEO Frequency	15-59 CSV Filename	17-6* Monitoring and App.	
12-98 Interface Counters	14-43 Motor Cosphi	15-6* Option Ident	17-60 Feedback Direction	
12-99 Media Counters	14-5* Environment	15-60 Option Mounted	17-61 Feedback Signal Monitoring	
13-3* Smart Logic	14-50 RFI Filter	15-61 Option SW Version	18-2** Data Readouts 2	
13-0* SL Settings	14-51 DC Link Compensation	15-62 Option Ordering No	18-3* Analog Readouts	
13-00 SL Controller Mode	14-52 Fan Control	15-63 Option Serial No	18-36 Analog Input X48/2 [mA]	
13-01 Start Event	14-53 Fan Monitor	15-70 Option in Slot A	18-37 Temp. Input X48/4	
13-02 Stop Event	14-55 Output Filter	15-71 Slot A Option SW Version	18-38 Temp. Input X48/7	
13-03 Reset SL	14-56 Capacitance Output Filter	15-72 Option in Slot B	18-39 Temp. Input X48/10	
13-1* Comparators	14-57 Inductance Output Filter	15-73 Slot B Option SW Version	18-6* Inputs & Outputs 2	
13-10 Comparator Operand	14-59 Actual Number of Inverter Units	15-74 Option in Slot C0/E0	18-60 Digital Input 2	
13-11 Comparator Operator	14-7* Compatibility	15-75 Slot C0/E0 Option SW Version	18-9* PID Readouts	
13-12 Comparator Value	14-72 Legacy Alarm Word	15-76 Option in Slot C1/E1	18-90 Process PID Error	
13-1* RS Flip Flops	14-73 Legacy Warning Word	15-77 Slot C1/E1 Option SW Version	18-91 Process PID Output	
13-15 RS-FF Operand S	14-8* Options	15-8* Operating Data II	18-92 Process PID Clamped Output	
13-16 RS-FF Operand R	14-74 Leg. Ext. Status Word	15-80 Fan Running Hours	18-93 Process PID Gain Scaled Output	
13-2* Timers	14-80 Option Supplied by External 24VDC	15-81 Preset Fan Running Hours	30-0** Special Features	
13-20 SL Controller Timer	14-89 Option Detection	15-89 Configuration Change Counter	30-0* Wobbler	
13-4* Logic Rules	14-9* Fault Settings	15-9* Parameter Info	30-00 Wobble Mode	
13-40 Logic Rule Boolean 1	14-90 Fault Level	15-92 Defined Parameters	30-01 Wobble Delta Frequency [Hz]	
13-41 Logic Rule Operator 1	15-2** Drive Information	15-93 Modified Parameters	30-02 Wobble Delta Frequency [%]	
13-42 Logic Rule Boolean 2	15-0* Operating Data	15-98 Drive Identification	30-03 Wobble Delta Freq. Scaling Resource	
13-43 Logic Rule Operator 2	15-00 Operating hours	15-99 Parameter Metadata	30-04 Wobble Jump Frequency [Hz]	
13-44 Logic Rule Boolean 3	15-01 Running Hours	16-0** Data Readouts	30-05 Wobble Jump Frequency [%]	
13-5* States	15-02 kWh Counter	16-0* General Status	30-06 Wobble Jump Time	
13-51 SL Controller Event	15-03 Power Up's	16-00 Control Word	30-07 Wobble Sequence Time	
13-52 SL Controller Action	15-04 Over Temp's	16-01 Reference [Unit]	30-08 Wobble Up/ Down Time	
14-2** Special Functions	15-05 Over Volt's	16-02 Reference %	30-09 Wobble Random Function	
14-0* Inverter Switching	15-06 Reset kWh Counter	16-03 Status Word	30-10 Wobble Ratio	
14-00 Switching Pattern	15-07 Reset Running Hours Counter	16-05 Main Actual Value [%]	30-11 Wobble Random Ratio Max.	
14-01 Switching Frequency	15-1* Data Log Settings	16-09 Custom Readout	30-12 Wobble Random Ratio Min.	
14-03 Overmodulation	15-10 Logging Source	16-1* Motor Status	30-19 Wobble Delta Freq. Scaled	
14-04 PWM Random	15-11 Logging Interval	16-10 Power [kW]	30-2* Adv. Start Adjust	
14-06 Dead Time Compensation	15-12 Trigger Event	16-11 Power [hp]	30-20 High Starting Torque Time [s]	
14-1* Mains On/Off	15-13 Logging Mode	16-12 Motor Voltage	30-21 High Starting Torque Current [%]	

30-22	Locked Rotor Protection	32-67	Max. Tolerated Position Error	33-43	Negative Software End Limit Active	34-25	PCD 5 Read from MCO	42-1*	Speed Monitoring
30-23	Locked Rotor Detection Time [s]	32-68	Reverse Behavior for Slave	33-44	Positive Software End Limit Active	34-26	PCD 6 Read from MCO	42-10	Measured Speed Source
30-8*	Compatibility (I)	32-69	Sampling Time for PID Control	33-45	Time in Target Window	34-27	PCD 7 Read from MCO	42-11	Encoder Resolution
30-80	d-axis Inductance (Ld)	32-70	Scan Time for Profile Generator	33-46	Target Window Limit/Value	34-28	PCD 8 Read from MCO	42-12	Encoder Direction
30-81	Brake Resistor (ohm)	32-71	Size of the Control Window (Activation)	33-47	Size of Target Window	34-29	PCD 9 Read from MCO	42-13	Gear Ratio
30-83	Speed PID Proportional Gain	32-72	Size of the Control Window (Deactiv.)	33-5*	I/O Configuration	34-30	PCD 10 Read from MCO	42-14	Feedback Type
30-84	Process PID Proportional Gain	32-73	Integral limit filter time	33-50	Terminal X57/1 Digital Input	34-31	PCD 11 Read from MCO	42-15	Feedback Filter
31-*	Bypass Option	32-74	Position error filter time	33-51	Terminal X57/2 Digital Input	34-32	PCD 12 Read from MCO	42-16	Feedback Filter
31-00	Bypass Mode	32-75	Position error filter time	33-52	Terminal X57/3 Digital Input	34-33	PCD 13 Read from MCO	42-17	Tolerance Error
31-01	Bypass Start Time Delay	32-76	Position error filter time	33-53	Terminal X57/4 Digital Input	34-34	PCD 14 Read from MCO	42-18	Zero Speed Timer
31-02	Bypass Trip Time Delay	32-77	Position error filter time	33-54	Terminal X57/5 Digital Input	34-35	PCD 15 Read from MCO	42-19	Zero Speed Limit
31-03	Test Mode Activation	32-78	Position error filter time	33-55	Terminal X57/6 Digital Input	34-36	PCD 16 Read from MCO	42-2*	Safe Input
31-10	Bypass Status Word	32-79	Position error filter time	33-56	Terminal X57/7 Digital Input	34-37	PCD 17 Read from MCO	42-20	Safe Function
31-11	Bypass Running Hours	32-80	Position error filter time	33-57	Terminal X57/8 Digital Input	34-38	PCD 18 Read from MCO	42-21	Type
31-19	Remote Bypass Activation	32-81	Position error filter time	33-58	Terminal X57/9 Digital Input	34-39	PCD 19 Read from MCO	42-22	Discrepancy Time
32-*	MCO Basic Settings	32-82	Position error filter time	33-59	Terminal X57/10 Digital Input	34-40	PCD 20 Read from MCO	42-23	Stable Signal Time
32-0*	Encoder 2	32-83	Position error filter time	33-60	Terminal X59/1 and X59/2 Mode	34-41	PCD 21 Read from MCO	42-24	Restart Behaviour
32-00	Incremental Signal Type	32-84	Position error filter time	33-61	Terminal X59/1 Digital Input	34-42	PCD 22 Read from MCO	42-3*	General
32-01	Incremental Resolution	32-85	Position error filter time	33-62	Terminal X59/2 Digital Input	34-43	PCD 23 Read from MCO	42-30	External Failure Reaction
32-02	Absolute Protocol	32-86	Position error filter time	33-63	Terminal X59/3 Digital Input	34-44	PCD 24 Read from MCO	42-31	Reset Source
32-03	Absolute Resolution	32-87	Position error filter time	33-64	Terminal X59/4 Digital Input	34-45	PCD 25 Read from MCO	42-32	Parameter Set Name
32-04	Absolute Encoder Baudrate X55	32-88	Position error filter time	33-65	Terminal X59/5 Digital Input	34-46	PCD 26 Read from MCO	42-35	S-CRC Value
32-05	Absolute Encoder Data Length	32-89	Position error filter time	33-66	Terminal X59/6 Digital Input	34-47	PCD 27 Read from MCO	42-36	Level 1 Password
32-06	Absolute Encoder Clock Frequency	32-90	Position error filter time	33-67	Terminal X59/7 Digital Input	34-48	PCD 28 Read from MCO	42-4*	SS1
32-07	Absolute Encoder Clock Generation	32-91	Position error filter time	33-68	Terminal X59/8 Digital Input	34-49	PCD 29 Read from MCO	42-40	Type
32-08	Absolute Encoder Cable Length	32-92	Position error filter time	33-69	Terminal X59/9 Digital Input	34-50	PCD 30 Read from MCO	42-41	Ramp Profile
32-09	Encoder Monitoring	32-93	Position error filter time	33-70	Terminal X59/10 Digital Input	34-51	PCD 31 Read from MCO	42-42	Delay Time
32-10	Rotational Direction	32-94	Position error filter time	33-71	Terminal X59/11 Digital Input	34-52	PCD 32 Read from MCO	42-43	Delta T
32-11	User Unit Denominator	32-95	Position error filter time	33-72	Terminal X59/12 Digital Input	34-53	PCD 33 Read from MCO	42-44	Deceleration Rate
32-12	User Unit Numerator	32-96	Position error filter time	33-73	Terminal X59/13 Digital Input	34-54	PCD 34 Read from MCO	42-45	Delta V
32-13	Enc.2 Control	32-97	Position error filter time	33-74	Terminal X59/14 Digital Input	34-55	PCD 35 Read from MCO	42-46	Zero Speed
32-14	Enc.2 mode ID	32-98	Position error filter time	33-75	Terminal X59/15 Digital Input	34-56	PCD 36 Read from MCO	42-47	Ramp Time
32-15	Enc.2 CAN guard	32-99	Position error filter time	33-76	Terminal X59/16 Digital Input	34-57	PCD 37 Read from MCO	42-48	S-ramp Ratio at Decel. Start
32-3*	Encoder 1	32-100	Position error filter time	33-77	Terminal X59/17 Digital Input	34-58	PCD 38 Read from MCO	42-49	S-ramp Ratio at Decel. End
32-30	Incremental Signal Type	32-101	Position error filter time	33-78	Terminal X59/18 Digital Input	34-59	PCD 39 Read from MCO	42-5*	SLS
32-31	Incremental Resolution	32-102	Position error filter time	33-79	Terminal X59/19 Digital Input	34-60	PCD 40 Read from MCO	42-50	Cut Off Speed
32-32	Absolute Protocol	32-103	Position error filter time	33-80	Terminal X59/20 Digital Input	34-61	PCD 41 Read from MCO	42-51	Speed Limit
32-33	Absolute Resolution	32-104	Position error filter time	33-81	Terminal X59/21 Digital Input	34-62	PCD 42 Read from MCO	42-52	Fail Safe Reaction
32-34	Absolute Encoder Data Length	32-105	Position error filter time	33-82	Terminal X59/22 Digital Input	34-63	PCD 43 Read from MCO	42-53	Start Ramp
32-35	Absolute Encoder Clock Frequency	32-106	Position error filter time	33-83	Terminal X59/23 Digital Input	34-64	PCD 44 Read from MCO	42-54	Ramp Down Time
32-36	Absolute Encoder Clock Generation	32-107	Position error filter time	33-84	Terminal X59/24 Digital Input	34-65	PCD 45 Read from MCO	42-5*	Status
32-37	Absolute Encoder Cable Length	32-108	Position error filter time	33-85	Terminal X59/25 Digital Input	34-66	PCD 46 Read from MCO	42-80	Safe Option Status
32-38	Absolute Encoder Clock Frequency	32-109	Position error filter time	33-86	Terminal X59/26 Digital Input	34-67	PCD 47 Read from MCO	42-81	Safe Option Status 2
32-39	Absolute Encoder Clock Generation	32-110	Position error filter time	33-87	Terminal X59/27 Digital Input	34-68	PCD 48 Read from MCO	42-85	Active Safe Func.
32-40	Encoder Monitoring	32-111	Position error filter time	33-88	Terminal X59/28 Digital Input	34-69	PCD 49 Read from MCO	42-86	Safe Option Info
32-41	Encoder Termination	32-112	Position error filter time	33-89	Terminal X59/29 Digital Input	34-70	PCD 50 Read from MCO	42-89	Customization File Version
32-42	Enc.1 Control	32-113	Position error filter time	33-90	Terminal X59/30 Digital Input	34-71	PCD 51 Read from MCO	42-9*	Special
32-43	Enc.1 mode ID	32-114	Position error filter time	33-91	Terminal X59/31 Digital Input	34-72	PCD 52 Read from MCO	42-90	Restart Safe Option
32-44	Enc.1 CAN guard	32-115	Position error filter time	33-92	Terminal X59/32 Digital Input	34-73	PCD 53 Read from MCO		
32-45	Enc.1 CAN guard	32-116	Position error filter time	33-93	Terminal X59/33 Digital Input	34-74	PCD 54 Read from MCO		
32-5*	Feedback Source	32-117	Position error filter time	33-94	Terminal X59/34 Digital Input	34-75	PCD 55 Read from MCO		
32-50	Source Slave	32-118	Position error filter time	33-95	Terminal X59/35 Digital Input	34-76	PCD 56 Read from MCO		
32-51	MCO 302 Last Will	32-119	Position error filter time	33-96	Terminal X59/36 Digital Input	34-77	PCD 57 Read from MCO		
32-52	Source Master	32-120	Position error filter time	33-97	Terminal X59/37 Digital Input	34-78	PCD 58 Read from MCO		
32-6*	PID Controller	32-121	Position error filter time	33-98	Terminal X59/38 Digital Input	34-79	PCD 59 Read from MCO		
32-60	Proportional factor	32-122	Position error filter time	33-99	Terminal X59/39 Digital Input	34-80	PCD 60 Read from MCO		
32-61	Derivative factor	32-123	Position error filter time	34-0*	PCD Write Par.	34-81	PCD 61 Read from MCO		
32-62	Integral factor	32-124	Position error filter time	34-01	PCD 1 Write to MCO	34-82	PCD 62 Read from MCO		
32-63	Limit Value for Integral Sum	32-125	Position error filter time	34-02	PCD 2 Write to MCO	34-83	PCD 63 Read from MCO		
32-64	PID Bandwidth	32-126	Position error filter time	34-03	PCD 3 Write to MCO	34-84	PCD 64 Read from MCO		
32-65	Velocity Feed-Forward	32-127	Position error filter time	34-04	PCD 4 Write to MCO	34-85	PCD 65 Read from MCO		
32-66	Acceleration Feed-Forward	32-128	Position error filter time	34-05	PCD 5 Write to MCO	34-86	PCD 66 Read from MCO		
		32-129	Position error filter time	34-06	PCD 6 Write to MCO	34-87	PCD 67 Read from MCO		
		32-130	Position error filter time	34-07	PCD 7 Write to MCO	34-88	PCD 68 Read from MCO		
		32-131	Position error filter time	34-08	PCD 8 Write to MCO	34-89	PCD 69 Read from MCO		
		32-132	Position error filter time	34-09	PCD 9 Write to MCO	34-90	PCD 70 Read from MCO		
		32-133	Position error filter time	34-10	PCD 10 Write to MCO	34-91	PCD 71 Read from MCO		
		32-134	Position error filter time	34-11	PCD 11 Write to MCO	34-92	PCD 72 Read from MCO		
		32-135	Position error filter time	34-12	PCD 12 Write to MCO	34-93	PCD 73 Read from MCO		
		32-136	Position error filter time	34-13	PCD 13 Write to MCO	34-94	PCD 74 Read from MCO		
		32-137	Position error filter time	34-14	PCD 14 Write to MCO	34-95	PCD 75 Read from MCO		
		32-138	Position error filter time	34-15	PCD 15 Write to MCO	34-96	PCD 76 Read from MCO		
		32-139	Position error filter time	34-16	PCD 16 Write to MCO	34-97	PCD 77 Read from MCO		
		32-140	Position error filter time	34-17	PCD 17 Write to MCO	34-98	PCD 78 Read from MCO		
		32-141	Position error filter time	34-18	PCD 18 Write to MCO	34-99	PCD 79 Read from MCO		
		32-142	Position error filter time	34-19	PCD 19 Write to MCO	35-00	PCD 80 Read from MCO		
		32-143	Position error filter time	34-20	PCD 20 Write to MCO	35-01	PCD 81 Read from MCO		
		32-144	Position error filter time	34-21	PCD 21 Write to MCO	35-02	PCD 82 Read from MCO		
		32-145	Position error filter time	34-22	PCD 22 Write to MCO	35-03	PCD 83 Read from MCO		
		32-146	Position error filter time	34-23	PCD 23 Write to MCO	35-04	PCD 84 Read from MCO		
		32-147	Position error filter time	34-24	PCD 24 Write to MCO	35-05	PCD 85 Read from MCO		
		32-148	Position error filter time	34-25	PCD 25 Write to MCO	35-06	PCD 86 Read from MCO		
		32-149	Position error filter time	34-26	PCD 26 Write to MCO	35-07	PCD 87 Read from MCO		
		32-150	Position error filter time	34-27	PCD 27 Write to MCO	35-08	PCD 88 Read from MCO		
		32-151	Position error filter time	34-28	PCD 28 Write to MCO	35-09	PCD 89 Read from MCO		
		32-152	Position error filter time	34-29	PCD 29 Write to MCO	35-10	PCD 90 Read from MCO		
		32-153	Position error filter time	34-30	PCD 30 Write to MCO	35-11	PCD 91 Read from MCO		
		32-154	Position error filter time	34-31	PCD 31 Write to MCO	35-12	PCD 92 Read from MCO		
		32-155	Position error filter time	34-32	PCD 32 Write to MCO	35-13	PCD 93 Read from MCO		
		32-156	Position error filter time	34-33	PCD 33 Write to MCO	35-14	PCD 94 Read from MCO		
		32-157	Position error filter time	34-34	PCD 34 Write to MCO	35-15	PCD 95 Read from MCO		
		32-158	Position error filter time	34-35	PCD 35 Write to MCO	35-16	PCD 96 Read from MCO		
		32-159	Position error filter time	34-36	PCD 36 Write to MCO	35-17	PCD 97 Read from MCO		
		32-160	Position error filter time	34-37	PCD 37 Write to MCO	35-18	PCD 98 Read from MCO		
		32-161	Position error filter time	34-38	PCD 38 Write to MCO	35-19	PCD 99 Read from MCO		
		32-162	Position error filter time	34-39	PCD 39 Write to MCO	35-20	PCD 100 Read from MCO		
		32-163	Position error filter time	34-40	PCD 40 Write to MCO	35-21	PCD 101 Read from MCO		
		32-164	Position error filter time	34-41	PCD 41 Write to MCO	35-22	PCD 102 Read from MCO		
		32-165	Position error filter time	34-42	PCD 42 Write to MCO	35-23	PCD 103 Read from MCO		
		32-166	Position error filter time	34-43	PCD 43 Write to MCO	35-24	PCD 104 Read from MCO		
		32-167	Position error filter time	34-44	PCD 44 Write to MCO	35-25	PCD 105 Read from MCO		
		32-168	Position error filter time	34-45	PCD 45 Write to MCO	35-26	PCD 106 Read from MCO		
		32-169	Position error filter time	34-46	PCD 46 Write to MCO	35-27	PCD 107 Read from MCO		
		32-170	Position error filter time	34-47	PCD 47 Write to MCO	35-28	PCD 108 Read from MCO		
		32-171	Position error filter time	34-48	PCD 48 Write to MCO	35-29	PCD 109 Read from MCO		
		32-172	Position error filter time	34-49	PCD 49 Write to MCO	35-30	PCD 110 Read from MCO		
		32-173	Position error filter time	34-50	PCD 50 Write to MCO	35-31	PCD 111 Read from MCO		
		32-174	Position error filter time	34-51	PCD 51 Write to MCO	35-32	PCD 112 Read from MCO		
		32-175	Position error filter time	34-52	PCD 52 Write to MCO	35-33	PCD 113 Read from MCO		
		32-176	Position error filter time	34-53	PCD 53 Write to MCO	35-34	PCD 114 Read from MCO		
		32-177	Position error filter time	34-54	PCD 54 Write to MCO	35-35	PCD 115 Read from MCO		
		32-178	Position error filter time	34-55	PCD 55 Write to MCO	35-36	PCD 116 Read from MCO		
		32-179	Position error filter time	34-56	PCD 56 Write to MCO	35-37	PCD 117 Read from MCO		
		32-180	Position error filter time	34-57	PCD 57 Write to MCO	35-38	PCD 118 Read from MCO		
		32-181	Position error filter time	34-58	PCD 58 Write to MCO	35-39	PCD 119 Read from MCO		
		32-182	Position error filter time	34-59	PCD 59 Write to MCO	35-40	PCD 120 Read from MCO		
		32-183	Position error filter time	34-60	PCD 60 Write to MCO	35-41	PCD 121 Read from MCO		
		32-184	Position error filter time	34-61	PCD 61 Write to MCO	35-42	PCD 122 Read from MCO		
		32-185	Position error filter time	34-62	PCD 62 Write to MCO	35-43	PCD 123 Read from MCO		
		32-186	Position error filter time	34-63	PCD 63 Write to MCO	35-44	PCD 124 Read from MCO		
		32-187	Position error filter time	34-64	PCD 64 Write to MCO	35-45	PCD 125 Read from MCO		
		32-188	Position error filter time	34-65	PCD 65 Write to MCO	35-46	PCD 126 Read from MCO		
		32-189	Position error filter time	34-66	PCD 66 Write to MCO	35-47	PCD 127 Read from MCO		
		32-190	Position error filter time	34-67	PCD 67 Write to MCO	35-48	PCD		

5.6 Remote Programming with MCT 10 Set-up Software

Danfoss has a software program available for developing, storing, and transferring frequency converter programming. The MCT 10 Set-up Software allows the user to connect a PC to the frequency converter and perform live programming rather than using the LCP. Additionally, all frequency converter programming can be done off-line and simply downloaded to the frequency converter. Or the entire frequency converter profile can be loaded onto the PC for back up storage or analysis.

The USB connector or RS-485 terminal is available for connecting to the frequency converter.

MCT 10 Set-up Software is available for free download at www.VLT-software.com. A CD is also available by requesting part number 130B1000. For further information, see the Operating Instructions.

6 Application Examples

6.1 Introduction

NOTE

A jumper wire may be required between terminal 12 (or 13) and terminal 37 for the frequency converter to operate when using factory default programming values.

The examples in this section are intended as a quick reference for common applications.

- Parameter settings are the regional default values unless otherwise indicated (selected in 0-03 Regional Settings)
- Parameters associated with the terminals and their settings are shown next to the drawings
- Where switch settings for analog terminals A53 or A54 are required, these are also shown

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6.2 Application Examples

CAUTION

Thermistors must use reinforced or double insulation to meet PELV insulation requirements.

Parameters	
Function	Setting
1-29 Automatic Motor Adaptation (AMA)	[1] Enable complete AMA
5-12 Terminal 27 Digital Input	[2]* Coast inverse
*=Default Value	
Notes/comments: Parameter group 1-2* Motor Data must be set according to motor	

Table 6.1 AMA with T27 Connected

Parameters	
Function	Setting
1-29 Automatic Motor Adaptation (AMA)	[1] Enable complete AMA
5-12 Terminal 27 Digital Input	[0] No operation
*=Default Value	
Notes/comments: Parameter group 1-2* Motor Data must be set according to motor	

Table 6.2 AMA without T27 Connected

Parameters	
Function	Setting
6-10 Terminal 53 Low Voltage	0.07 V*
6-11 Terminal 53 High Voltage	10 V*
6-14 Terminal 53 Low Ref./Feedb. Value	0 RPM
6-15 Terminal 53 High Ref./Feedb. Value	1500 RPM
*=Default Value	
Notes/comments:	

Table 6.3 Analog Speed Reference (Voltage)

		Parameters	
FC		Function	Setting
+24 V	12	6-12 Terminal 53 Low Current	4 mA*
+24 V	13		
D IN	18	6-13 Terminal 53 High Current	20 mA*
D IN	19		
COM	20	6-14 Terminal 53 Low Ref./Feedb. Value	0 RPM
D IN	27		
D IN	29	6-15 Terminal 53 High Ref./Feedb. Value	1500 RPM
D IN	32		
D IN	33	*=Default Value	
D IN	37		
+10 V	50	Notes/comments:	
A IN	53		
A IN	54	Notes/comments:	
COM	55		
A OUT	42	Notes/comments:	
COM	39		
U - I		Notes/comments:	
A53			

Table 6.4 Analog Speed Reference (Current)

		Parameters	
FC		Function	Setting
+24 V	12		
+24 V	13		
D IN	18	5-10 Terminal 18	[8] Start*
D IN	19	Digital Input	
COM	20	5-12 Terminal 27	[0] No
D IN	27	Digital Input	operation
D IN	29	5-19 Terminal 37	[1] Safe Stop
D IN	32	Safe Stop	Alarm
D IN	33		
D IN	37		
		*=Default Value	
		Notes/comments:	
		If 5-12 Terminal 27 Digital Input	
		is set to [0] No operation, a	
		jumper wire to terminal 27 is	
		not needed.	
+10	50		
A IN	53		
A IN	54		
COM	55		
A OUT	42		
COM	39		

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Parameters	
Function	Setting
5-10 Terminal 18 Digital Input	[8] Start
5-11 Terminal 19 Digital Input	[10] Reversing*
5-12 Terminal 27 Digital Input	[0] No operation
5-14 Terminal 32 Digital Input	[16] Preset ref bit 0
5-15 Terminal 33 Digital Input	[17] Preset ref bit 1
3-10 Preset Reference	
Preset ref. 0	25%
Preset ref. 1	50%
Preset ref. 2	75%
Preset ref. 3	100%
*=Default Value	
Notes/comments:	

Table 6.7 Start/Stop with Reversing and 4 Preset Speeds

Parameters	
Function	Setting
5-11 Terminal 19 Digital Input	[1] Reset
*=Default Value	
Notes/comments:	

Table 6.8 External Alarm Reset

Parameters	
Function	Setting
6-10 Terminal 53 Low Voltage	0.07 V*
6-11 Terminal 53 High Voltage	10 V*
6-14 Terminal 53 Low Ref./Feedb. Value	0 RPM
6-15 Terminal 53 High Ref./Feedb. Value	1500 RPM
*=Default Value	
Notes/comments:	

Table 6.9 Speed Reference (using a Manual Potentiometer)

Parameters	
Function	Setting
5-10 Terminal 18 Digital Input	[8] Start*
5-12 Terminal 27 Digital Input	[19] Freeze Reference
5-13 Terminal 29 Digital Input	[21] Speed Up
5-14 Terminal 32 Digital Input	[22] Speed Down
*=Default Value	
Notes/comments:	

Table 6.10 Speed Up/Down

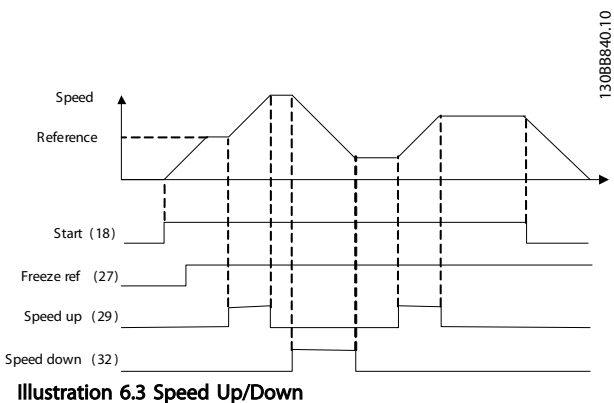


Illustration 6.3 Speed Up/Down

Parameters	
Function	Setting
FC	
+24 V 12	
+24 V 13	
D IN 18	
D IN 19	
COM 20	
D IN 27	
D IN 29	
D IN 32	
D IN 33	
D IN 37	
+10 V 50	
A IN 53	
A IN 54	
COM 55	
A OUT 42	
COM 39	
01	
02	
03	
04	
05	
06	
61	
68	
69	
RS-485	

Table 6.11 RS-485 Network Connection

Parameters	
Function	Setting
FC	
+24 V 12	
+24 V 13	
D IN 18	
D IN 19	
COM 20	
D IN 27	
D IN 29	
D IN 32	
D IN 33	
D IN 37	
+10 V 50	
A IN 53	
A IN 54	
COM 55	
A OUT 42	
COM 39	
U - I	
A53	

Table 6.12 Motor Thermistor

6

		Parameters		
FC		Function	Setting	
+24 V	12	4-30 Motor Feedback Loss Function	[1] Warning	
+24 V	13			
D IN	18	4-31 Motor Feedback Speed Error	100 RPM	
D IN	19			
COM	20	4-32 Motor Feedback Loss Timeout	5 s	
D IN	27			
D IN	29	7-00 Speed PID Feedback Source	[2] MCB 102	
D IN	32			
D IN	33	17-11 Resolution (PPR)	1024*	
D IN	37			
+10 V	50	13-00 SL Controller Mode	[1] On	
A IN	53			
A IN	54	13-01 Start Event	[19] Warning	
COM	55			
A OUT	42	13-02 Stop Event	[44] Reset key	
COM	39			
R1	01	13-10 Comparat or Operand	[21] Warning no.	
	02			
R2	04	13-11 Comparat or Operator	[1] ≈*	
	05			
	06	13-12 Comparat or Value	90	
		13-51 SL Controller Event	[22]	
		13-52 SL Controller Action	[32] Set digital out A low	
		5-40 Function Relay	[80] SL digital output A	
		*=Default Value		
		Notes/comments:		
		If the limit in the feedback monitor is exceeded, Warning 90 will be issued. The SLC monitors Warning 90 and in the case that Warning 90 becomes TRUE then Relay 1 is triggered. External equipment may then indicate that service may be required. If the feedback error goes below the limit again within 5 s then the frequency converter continues and the warning disappears. But Relay 1 will still be triggered until [Reset] on the LCP.		

Table 6.13 Using SLC to Set a Relay

		Parameters	
FC		Function	Setting
+24 V	12	5-40 Function Relay	[32] Mech. brake ctrl.
+24 V	13		
D IN	18	5-10 Terminal 18 Digital Input	[8] Start*
D IN	19		
COM	20	5-11 Terminal 19 Digital Input	[11] Start reversing
D IN	27		
D IN	29	1-71 Start Delay	0.2
D IN	32		
D IN	33	1-72 Start Function	[5] VVC ^{plus} /FLUX Clockwise
D IN	37		
+10 V	50	1-76 Start Current	I _{m,n}
A IN	53		
A IN	54	2-20 Release Brake Current	App. dependent
COM	55		
A OUT	42	2-21 Activate Brake Speed [RPM]	Half of nominal slip of the motor
COM	39		
R1		*=Default Value	
R2		Notes/comments:	

Table 6.14 Mechanical Brake Control

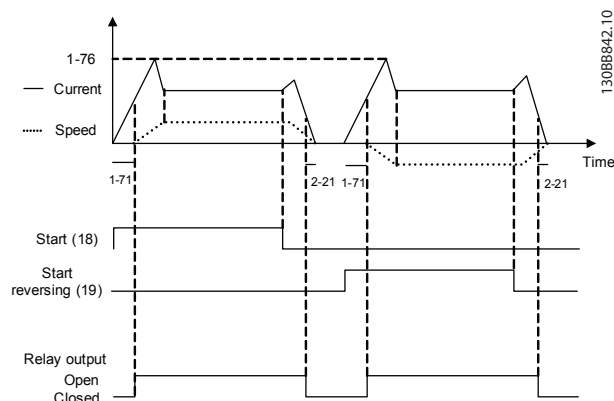


Illustration 6.4 Mechanical Brake Control

7 Status Messages

7.1 Status Display

When the frequency converter is in status mode, status messages are generated automatically from within the frequency converter and appear in the bottom line of the display (see *Illustration 7.1*.)

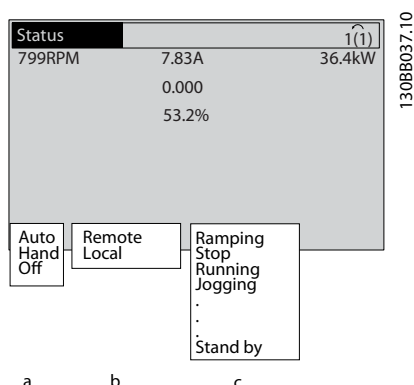


Illustration 7.1 Status Display

- The first part of the status line indicates where the stop/start command originates.
- The second part of the status line indicates where the speed control originates.
- The last part of the status line gives the present frequency converter status. These show the operational mode the frequency converter is in.

NOTE

In auto/remote mode, the frequency converter requires external commands to execute functions.

7.2 Status Message Definitions Table

Table 7.1, Table 7.2 and Table 7.3 define the meaning of the status message display words.

Off	The frequency converter does not react to any control signal until [Auto On] or [Hand On] is pressed.
Auto on	The frequency converter is controlled from the control terminals and/or the serial communication.
Hand on	The frequency converter can be controlled by the navigation keys on the LCP. Stop commands, reset, reversing, DC brake, and other signals applied to the control terminals can override local control.

Table 7.1 Operation Mode

Remote	The speed reference is given from external signals, serial communication, or internal preset references.
Local	The frequency converter uses [Hand On] control or reference values from the LCP.

Table 7.2 Reference Site

AC Brake	AC Brake was selected in 2-10 Brake Function. The AC brake over-magnetizes the motor to achieve a controlled slow down.
AMA finish OK	Automatic motor adaptation (AMA) was carried out successfully.
AMA ready	AMA is ready to start. Press [Hand On] to start.
AMA running	AMA process is in progress.
Braking	The brake chopper is in operation. Generative energy is absorbed by the brake resistor.
Braking max.	The brake chopper is in operation. The power limit for the brake resistor defined in 2-12 Brake Power Limit (kW) is reached.
Coast	- Coast inverse was selected as a function for a digital input (parameter group 5-1* Digital Inputs). The corresponding terminal is not connected. - Coast activated by serial communication

Ctrl. Ramp-down	Control Ramp-down was selected in <i>14-10 Mains Failure</i> . - The mains voltage is below the value set in <i>14-11 Mains Voltage at Mains Fault</i> at mains fault - The frequency converter ramps down the motor using a controlled ramp down
Current High	The frequency converter output current is above the limit set in <i>4-51 Warning Current High</i> .
Current Low	The frequency converter output current is below the limit set in <i>4-52 Warning Speed Low</i>
DC Hold	DC hold is selected in <i>1-80 Function at Stop</i> and a stop command is active. The motor is held by a DC current set in <i>2-00 DC Hold/ Preheat Current</i> .
DC Stop	The motor is held with a DC current (<i>2-01 DC Brake Current</i>) for a specified time (<i>2-02 DC Braking Time</i>). - DC Brake is activated in <i>2-03 DC Brake Cut In Speed [RPM]</i> and a Stop command is active - DC Brake (inverse) is selected as a function for a digital input (parameter group <i>5-1* Digital Inputs</i>). The corresponding terminal is not active. - The DC Brake is activated via serial communication
Feedback high	The sum of all active feedbacks is above the feedback limit set in <i>4-57 Warning Feedback High</i> .
Feedback low	The sum of all active feedbacks is below the feedback limit set in <i>4-56 Warning Feedback Low</i> .
Freeze output	The remote reference is active, which holds the present speed. - Freeze output was selected as a function for a digital input (parameter group <i>5-1* Digital Inputs</i>). The corresponding terminal is active. Speed control is only possible via the terminal functions speed up and speed down. - Hold ramp is activated via serial communication
Freeze output request	A freeze output command has been given, but the motor will remain stopped until a run permissive signal is received.
Freeze ref.	<i>Freeze Reference</i> was chosen as a function for a digital input (parameter group <i>5-1* Digital Inputs</i>). The corresponding terminal is active. The frequency converter saves the actual reference. Changing the reference is now only possible via terminal functions speed up and speed down.

Jog request	A jog command has been given, but the motor will be stopped until a run permissive signal is received via a digital input.
Jogging	The motor is running as programmed in <i>3-19 Jog Speed [RPM]</i> . <i>Jog</i> was selected as function for a digital input (parameter group <i>5-1* Digital Inputs</i>). The corresponding terminal (e.g. Terminal 29) is active. - The Jog function is activated via the serial communication - The Jog function was selected as a reaction for a monitoring function (e.g. No signal). The monitoring function is active
Motor check	In <i>1-80 Function at Stop, Motor Check</i> was selected. A stop command is active. To ensure that a motor is connected to the frequency converter, a permanent test current is applied to the motor.
OVC control	<i>Overvoltage</i> control was activated in <i>2-17 Overvoltage Control</i> . The connected motor is supplying the frequency converter with generative energy. The overvoltage control adjusts the V/Hz ratio to run the motor in controlled mode and to prevent the frequency converter from tripping.
PowerUnit Off	(For frequency converters with an external 24 V power supply installed only). Mains supply to the frequency converter is removed, but the control card is supplied by the external 24 V.
Protection md	Protection mode is active. The unit has detected a critical status (an overcurrent or overvoltage). - To avoid tripping, switching frequency is reduced to 4 kHz - If possible, protection mode ends after approximately 10 s - Protection mode can be restricted in <i>14-26 Trip Delay at Inverter Fault</i>
QStop	The motor is decelerating using <i>3-81 Quick Stop Ramp Time</i> . <i>Quick stop inverse</i> was chosen as a function for a digital input (parameter group <i>5-1* Digital Inputs</i>). The corresponding terminal is not active. - The quick stop function was activated via serial communication
Ramping	The motor is accelerating/decelerating using the active Ramp Up/Down. The reference, a limit value or a standstill is not yet reached.
Ref. high	The sum of all active references is above the reference limit set in <i>4-55 Warning Reference High</i> .

Ref. low	The sum of all active references is below the reference limit set in <i>4-54 Warning Reference Low</i> .
Run on ref.	The frequency converter is running in the reference range. The feedback value matches the setpoint value.
Run request	A start command has been given, but the motor is stopped until a run permissive signal is received via digital input.
Running	The motor is driven by the frequency converter.
Speed high	Motor speed is above the value set in <i>4-53 Warning Speed High</i> .
Speed low	Motor speed is below the value set in <i>4-52 Warning Speed Low</i> .
Standby	In Auto On Auto mode, the frequency converter will start the motor with a start signal from a digital input or serial communication.
Start delay	In <i>1-71 Start Delay</i> , a delay starting time was set. A start command is activated and the motor will start after the start delay time expires.
Start fwd/rev	Start forward and start reverse were selected as functions for two different digital inputs (parameter group <i>5-1* Digital Inputs</i>). The motor will start in forward or reverse depending on which corresponding terminal is activated.
Stop	The frequency converter has received a stop command from the LCP, digital input or serial communication.
Trip	An alarm occurred and the motor is stopped. Once the cause of the alarm is cleared, the frequency converter can be reset manually by pressing [Reset] or remotely by control terminals or serial communication.
Trip lock	An alarm occurred and the motor is stopped. Once the cause of the alarm is cleared, power must be cycled to the frequency converter. The frequency converter can then be reset manually by pressing [Reset] or remotely by control terminals or serial communication.

Table 7.3 Operation Status

8 Warnings and Alarms

8.1 System Monitoring

The frequency converter monitors the condition of its input power, output, and motor factors as well as other system performance indicators. A warning or alarm may not necessarily indicate a problem internal to the frequency converter itself. In many cases, it indicates failure conditions from input voltage, motor load or temperature, external signals, or other areas monitored by the frequency converter's internal logic. Be sure to investigate those areas exterior to the frequency converter as indicated in the alarm or warning.

8.2 Warning and Alarm Types

Warnings

A warning is issued when an alarm condition is impending or when an abnormal operating condition is present and may result in the frequency converter issuing an alarm. A warning clears by itself when the abnormal condition is removed.

Alarms

Trip

An alarm is issued when the frequency converter is tripped, that is, the frequency converter suspends operation to prevent frequency converter or system damage. The motor will coast to a stop. The frequency converter logic will continue to operate and monitor the frequency converter status. After the fault condition is remedied, the frequency converter can be reset. It will then be ready to start operation again.

A trip can be reset in any of 4 ways

- Press [Reset] on the LCP
- Digital reset input command
- Serial communication reset input command
- Auto reset

An alarm that causes the frequency converter to trip-lock requires that input power is cycled. The motor will coast to a stop. The frequency converter logic will continue to operate and monitor the frequency converter status. Remove input power to the frequency converter and correct the cause of the fault, then restore power. This action puts the frequency converter into a trip condition as described above and may be reset in any of those 4 ways.

8.3 Warning and Alarm Displays

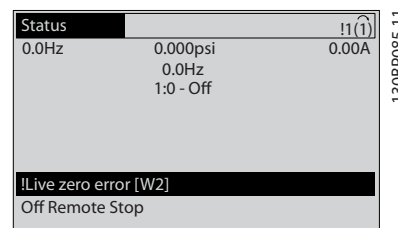


Illustration 8.1 Warning Display

An alarm or trip-lock alarm will flash on display along with the alarm number.

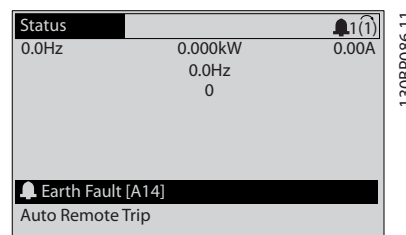


Illustration 8.2 Alarm Display

In addition to the text and alarm code on the frequency converter LCP, there are three status indicator lights.

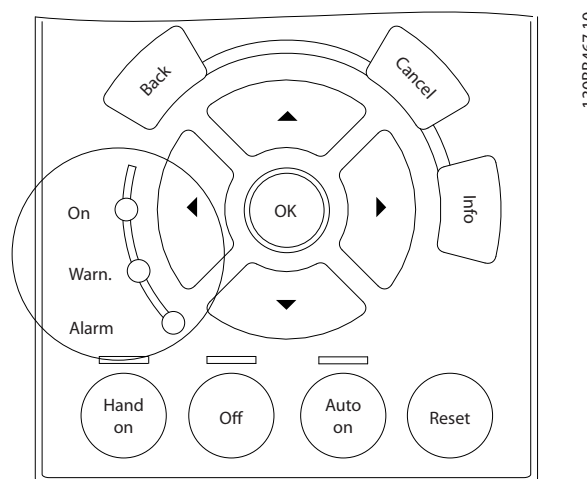


Illustration 8.3 Status Indicator Lights

	Warning LED	Alarm LED
Warning	On	Off
Alarm	Off	On (Flashing)
Trip-Lock	On	On (Flashing)

Table 8.1 Status Indicator Lights Explanations

8.4 Warning and Alarm Definitions

The warning/alarm information below defines each warning/alarm condition, provides the probable cause for the condition, and details a remedy or troubleshooting procedure.

WARNING 1, 10 Volts low

The control card voltage is below 10 V from terminal 50. Remove some of the load from terminal 50, as the 10 V supply is overloaded. Max. 15 mA or minimum 590 Ω.

This condition can be caused by a short in a connected potentiometer or improper wiring of the potentiometer.

Troubleshooting

Remove the wiring from terminal 50. If the warning clears, the problem is with the customer wiring. If the warning does not clear, replace the control card.

WARNING/ALARM 2, Live zero error

This warning or alarm only appears if programmed by the user in *6-01 Live Zero Timeout Function*. The signal on one of the analog inputs is less than 50% of the minimum value programmed for that input. Broken wiring or faulty device sending the signal can cause this condition.

Troubleshooting

Check connections on all the analog input terminals. Control card terminals 53 and 54 for signals, terminal 55 common. MCB 101 terminals 11 and 12 for signals, terminal 10 common. MCB 109 terminals 1, 3, 5 for signals, terminals 2, 4, 6 common).

Check that the frequency converter programming and switch settings match the analog signal type.

Perform Input Terminal Signal Test.

WARNING/ALARM 3, No motor

No motor has been connected to the output of the frequency converter.

WARNING/ALARM 4, Mains phase loss

A phase is missing on the supply side, or the mains voltage imbalance is too high. This message also appears for a fault in the input rectifier on the frequency converter. Options are programmed at *14-12 Function at Mains Imbalance*.

Troubleshooting

Check the supply voltage and supply currents to the frequency converter.

WARNING 5, DC link voltage high

The intermediate circuit voltage (DC) is higher than the high voltage warning limit. The limit is dependent on the frequency converter voltage rating. The unit is still active.

WARNING 6, DC link voltage low

The intermediate circuit voltage (DC) is lower than the low voltage warning limit. The limit is dependent on the frequency converter voltage rating. The unit is still active.

WARNING/ALARM 7, DC overvoltage

If the intermediate circuit voltage exceeds the limit, the frequency converter trips after a time.

Troubleshooting

Connect a brake resistor

Extend the ramp time

Change the ramp type

Activate the functions in *2-10 Brake Function*

Increase *14-26 Trip Delay at Inverter Fault*

If the alarm/warning occurs during a power sag the solution is to use kinetic back-up (*14-10 Mains Failure*)

WARNING/ALARM 8, DC under voltage

If the intermediate circuit voltage (DC link) drops below the under voltage limit, the frequency converter checks if a 24 V DC backup supply is connected. If no 24 V DC backup supply is connected, the frequency converter trips after a fixed time delay. The time delay varies with unit size.

Troubleshooting

Check that the supply voltage matches the frequency converter voltage.

Perform input voltage test.

Perform soft charge circuit test.

WARNING/ALARM 9, Inverter overload

The frequency converter is about to cut out because of an overload (too high current for too long). The counter for electronic, thermal inverter protection issues a warning at 98% and trips at 100%, while giving an alarm. The frequency converter *cannot* be reset until the counter is below 90%.

The fault is that the frequency converter has run with more than 100% overload for too long.

Troubleshooting

Compare the output current shown on the LCP with the frequency converter rated current.

Compare the output current shown on the LCP with measured motor current.

Display the Thermal Drive Load on the LCP and monitor the value. When running above the frequency converter continuous current rating, the counter increases. When running below the

frequency converter continuous current rating, the counter decreases.

WARNING/ALARM 10, Motor overload temperature

According to the electronic thermal protection (ETR), the motor is too hot. Select whether the frequency converter issues a warning or an alarm when the counter reaches 100% in *1-90 Motor Thermal Protection*. The fault occurs when the motor runs with more than 100% overload for too long.

Troubleshooting

Check for motor overheating.

Check if the motor is mechanically overloaded

Check that the motor current set in *1-24 Motor Current* is correct.

Ensure that Motor data in parameters 1-20 through 1-25 are set correctly.

If an external fan is in use, check in *1-91 Motor External Fan* that it is selected.

Running AMA in *1-29 Automatic Motor Adaptation (AMA)* tunes the frequency converter to the motor more accurately and reduces thermal loading.

WARNING/ALARM 11, Motor thermistor over temp

The thermistor might be disconnected. Select whether the frequency converter gives a warning or an alarm in *1-90 Motor Thermal Protection*.

Troubleshooting

Check for motor overheating.

Check if the motor is mechanically overloaded.

Check that the thermistor is connected correctly between either terminal 53 or 54 (analog voltage input) and terminal 50 (+10 V supply) and that the terminal switch for 53 or 54 is set for voltage. Check *1-93 Thermistor Source* selects terminal 53 or 54.

When using digital inputs 18 or 19, check that the thermistor is connected correctly between either terminal 18 or 19 (digital input PNP only) and terminal 50.

If a KTY sensor is used, check for correct connection between terminals 54 and 55

If using a thermal switch or thermistor, check that the programming if *1-93 Thermistor Resource* matches sensor wiring.

If using a KTY sensor, check the programming of *1-95 KTY Sensor Type*, *1-96 KTY Thermistor Resource*, and *1-97 KTY Threshold level* match sensor wiring.

WARNING/ALARM 12, Torque limit

The torque has exceeded the value in *4-16 Torque Limit Motor Mode* or the value in *4-17 Torque Limit Generator Mode*. *14-25 Trip Delay at Torque Limit* can change this from a warning only condition to a warning followed by an alarm.

Troubleshooting

If the motor torque limit is exceeded during ramp up, extend the ramp up time.

If the generator torque limit is exceeded during ramp down, extend the ramp down time.

If torque limit occurs while running, possibly increase the torque limit. Make sure that the system can operate safely at a higher torque.

Check the application for excessive current draw on the motor.

WARNING/ALARM 13, Over current

The inverter peak current limit (approximately 200% of the rated current) is exceeded. The warning lasts about 1.5 s, then the frequency converter trips and issues an alarm. This fault can be caused by shock loading or quick acceleration with high inertia loads. It can also appear after kinetic back-up if the acceleration during ramp up is quick. If extended mechanical brake control is selected, trip can be reset externally.

Troubleshooting

Remove power and check if the motor shaft can be turned.

Check that the motor size matches the frequency converter.

Check parameters 1-20 to 1-25 for correct motor data.

ALARM 14, Earth (ground) fault

There is current from the output phases to earth, either in the cable between the frequency converter and the motor or in the motor itself.

Troubleshooting

Remove power to the frequency converter and repair the earth fault.

Check for earth faults in the motor by measuring the resistance to ground of the motor leads and the motor with a megohmmeter.

Perform current sensor test.

ALARM 15, Hardware mismatch

A fitted option is not operational with the present control board hardware or software.

Record the value of the following parameters and contact your Danfoss supplier:

15-40 FC Type

15-41 Power Section

15-42 Voltage

- 15-43 Software Version
- 15-45 Actual Typecode String
- 15-49 SW ID Control Card
- 15-50 SW ID Power Card
- 15-60 Option Mounted
- 15-61 Option SW Version (for each option slot)

ALARM 16, Short circuit

There is short-circuiting in the motor or motor wiring.

Remove power to the frequency converter and repair the short circuit.

WARNING/ALARM 17, Control word timeout

There is no communication to the frequency converter. The warning will only be active when *8-04 Control Word Timeout Function* is NOT set to [Off].

If *8-04 Control Word Timeout Function* is set to *Stop* and *Trip*, a warning appears and the frequency converter ramps down until it trips then displays an alarm.

Troubleshooting:

- Check connections on the serial communication cable.
- Increase *8-03 Control Word Timeout Time*
- Check the operation of the communication equipment.
- Verify a proper installation based on EMC requirements.

WARNING/ALARM 22, Hoist mechanical brake

Report value shows what kind it is.

0 = The torque ref. was not reached before timeout.

1 = There was no brake feedback before timeout.

WARNING 23, Internal fan fault

The fan warning function is an extra protective function that checks if the fan is running/mounted. The fan warning can be disabled in *14-53 Fan Monitor ([0] Disabled)*.

Troubleshooting

- Check fan resistance.
- Check soft charge fuses.

WARNING 24, External fan fault

The fan warning function is an extra protective function that checks if the fan is running/mounted. The fan warning can be disabled in *14-53 Fan Monitor ([0] Disabled)*.

Troubleshooting

- Check fan resistance.
- Check soft charge fuses.

WARNING 25, Brake resistor short circuit

The brake resistor is monitored during operation. If a short circuit occurs, the brake function is disabled and the warning appears. The frequency converter is still operational but without the brake function. Remove power to the frequency converter and replace the brake resistor (see *2-15 Brake Check*).

WARNING/ALARM 26, Brake resistor power limit

The power transmitted to the brake resistor is calculated as a mean value over the last 120 s of run time. The calculation is based on the intermediate circuit voltage and the brake resistance value set in *2-16 AC brake Max. Current*. The warning is active when the dissipated braking is higher than 90% of the brake resistance power. If *[2] Trip* is selected in *2-13 Brake Power Monitoring*, the frequency converter will trip when the dissipated braking power reaches 100%.

WARNING

There is a risk of substantial power being transmitted to the brake resistor if the brake transistor is short-circuited.

WARNING/ALARM 27, Brake chopper fault

The brake transistor is monitored during operation and if a short circuit occurs, the brake function is disabled and a warning is issued. The frequency converter is still operational but, since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive.

Remove power to the frequency converter and remove the brake resistor.

This alarm/warning could also occur should the brake resistor overheat. Terminals 104 and 106 are available as brake resistors Klaxon ininputs, see section *Brake Resistor Temperature Switch* in the Design Guide.

WARNING/ALARM 28, Brake check failed

The brake resistor is not connected or not working. Check *2-15 Brake Check*.

ALARM 29, Heatsink temp

The maximum temperature of the heatsink has been exceeded. The temperature fault will not reset until the temperature falls below a defined heatsink temperature. The trip and reset points are different based on the frequency converter power size.

Troubleshooting

Check for the following conditions.

- Ambient temperature too high.
- Motor cable too long.
- Incorrect airflow clearance above and below the frequency converter
- Blocked airflow around the frequency converter.
- Damaged heatsink fan.
- Dirty heatsink.

For the D, E, and F Frame sizes, this alarm is based on the temperature measured by the heatsink sensor mounted inside the IGBT modules. For the F Frame sizes, this alarm can also be caused by the thermal sensor in the Rectifier module.

Troubleshooting

Check fan resistance.

Check soft charge fuses.

IGBT thermal sensor.

ALARM 30, Motor phase U missing

Motor phase U between the frequency converter and the motor is missing.

Remove power from the frequency converter and check motor phase U.

ALARM 31, Motor phase V missing

Motor phase V between the frequency converter and the motor is missing.

Remove power from the frequency converter and check motor phase V.

ALARM 32, Motor phase W missing

Motor phase W between the frequency converter and the motor is missing.

Remove power from the frequency converter and check motor phase W.

ALARM 33, Inrush fault

Too many power-ups have occurred within a short time period. Let the unit cool to operating temperature.

WARNING/ALARM 34, Fieldbus communication fault

The fieldbus on the communication option card is not working.

WARNING/ALARM 36, Mains failure

This warning/alarm is only active if the supply voltage to the frequency converter is lost and *14-10 Mains Failure* is NOT set to [0] No Function. Check the fuses to the frequency converter and mains power supply to the unit.

ALARM 38, Internal fault

When an internal fault occurs, a code number defined in Table 8.2 is displayed.

Troubleshooting

Cycle power

Check that the option is properly installed

Check for loose or missing wiring

It may be necessary to contact your Danfoss supplier or service department. Note the code number for further troubleshooting directions.

No.	Text
0	Serial port cannot be initialised. Contact your Danfoss supplier or Danfoss Service Department.
256-258	Power EEPROM data is defective or too old
512	Control board EEPROM data is defective or too old.
513	Communication time out reading EEPROM data
514	Communication time out reading EEPROM data
515	Application oriented control cannot recognize the EEPROM data.

No.	Text
516	Cannot write to the EEPROM because a write command is on progress.
517	Write command is under time out
518	Failure in the EEPROM
519	Missing or invalid barcode data in EEPROM
783	Parameter value outside of min/max limits
1024-1279	A centelegram that has to be sent couldn't be sent.
1281	Digital signal processor flash timeout
1282	Power micro software version mismatch
1283	Power EEPROM data version mismatch
1284	Cannot read digital signal processor software version
1299	Option SW in slot A is too old
1300	Option SW in slot B is too old
1301	Option SW in slot C0 is too old
1302	Option SW in slot C1 is too old
1315	Option SW in slot A is not supported (not allowed)
1316	Option SW in slot B is not supported (not allowed)
1317	Option SW in slot C0 is not supported (not allowed)
1318	Option SW in slot C1 is not supported (not allowed)
1379	Option A did not respond when calculating platform version
1380	Option B did not respond when calculating platform version
1381	Option C0 did not respond when calculating platform version.
1382	Option C1 did not respond when calculating platform version.
1536	An exception in the application oriented control is registered. Debug information written in LCP
1792	DSP watchdog is active. Debugging of power part data, motor oriented control data not transferred correctly.
2049	Power data restarted
2064-2072	H081x: option in slot x has restarted
2080-2088	H082x: option in slot x has issued a powerup-wait
2096-2104	H983x: option in slot x has issued a legal powerup-wait
2304	Could not read any data from power EEPROM
2305	Missing SW version from power unit
2314	Missing power unit data from power unit
2315	Missing SW version from power unit
2316	Missint lo_statepage from power unit
2324	Power card configuration is determined to be incorrect at power up
2325	A power card has stopped communicating while main power is applied
2326	Power card configuration is determined to be incorrect after the delay for power cards to register.

No.	Text
2327	Too many power card locations have been registered as present.
2330	Power size information between the power cards does not match.
2561	No communication from DSP to ATACD
2562	No communication from ATACD to DSP (state running)
2816	Stack overflow control board module
2817	Scheduler slow tasks
2818	Fast tasks
2819	Parameter thread
2820	LCP stack overflow
2821	Serial port overflow
2822	USB port overflow
2836	cflistMempool too small
3072-5122	Parameter value is outside its limits
5123	Option in slot A: Hardware incompatible with control board hardware
5124	Option in slot B: Hardware incompatible with Control board hardware.
5125	Option in slot C0: Hardware incompatible with control board hardware.
5126	Option in slot C1: Hardware incompatible with control board hardware.
5376-6231	Out of memory

Table 8.2 Internal Fault, Code Numbers
ALARM 39, Heatsink sensor

No feedback from the heatsink temperature sensor.

The signal from the IGBT thermal sensor is not available on the power card. The problem could be on the power card, on the gate drive card, or the ribbon cable between the power card and gate drive card.

WARNING 40, Overload of digital output terminal 27

Check the load connected to terminal 27 or remove short-circuit connection. Check *5-00 Digital I/O Mode* and *5-01 Terminal 27 Mode*.

WARNING 41, Overload of digital output terminal 29

Check the load connected to terminal 29 or remove short-circuit connection. Check *5-00 Digital I/O Mode* and *5-02 Terminal 29 Mode*.

WARNING 42, Overload of digital output on X30/6 or overload of digital output on X30/7

For X30/6, check the load connected to X30/6 or remove the short-circuit connection. Check *5-32 Term X30/6 Digi Out (MCB 101)*.

For X30/7, check the load connected to X30/7 or remove the short-circuit connection. Check *5-33 Term X30/7 Digi Out (MCB 101)*.

ALARM 46, Power card supply

The supply on the power card is out of range.

There are three power supplies generated by the switch mode power supply (SMPS) on the power card: 24 V, 5 V, ± 18 V. When powered with 24 V DC with the MCB 107 option, only the 24 V and 5 V supplies are monitored. When powered with three phase mains voltage, all three supplies are monitored.

WARNING 47, 24 V supply low

The 24 V DC is measured on the control card. The external 24 V DC backup power supply may be overloaded, otherwise contact the Danfoss supplier.

WARNING 48, 1.8 V supply low

The 1.8 V DC supply used on the control card is outside of allowable limits. The power supply is measured on the control card. Check for a defective control card. If an option card is present, check for an overvoltage condition.

WARNING 49, Speed limit

When the speed is not within the specified range in *4-11 Motor Speed Low Limit [RPM]* and *4-13 Motor Speed High Limit [RPM]*, the frequency converter shows a warning. When the speed is below the specified limit in *1-86 Trip Speed Low [RPM]* (except when starting or stopping) the frequency converter will trip.

ALARM 50, AMA calibration failed

Contact your Danfoss supplier or Danfoss Service Department.

ALARM 51, AMA check U_{nom} and I_{nom}

The settings for motor voltage, motor current and motor power are wrong. Check the settings in parameters 1-20 to 1-25.

ALARM 52, AMA low I_{nom}

The motor current is too low. Check the settings.

ALARM 53, AMA motor too big

The motor is too big for the AMA to operate.

ALARM 54, AMA motor too small

The motor is too small for the AMA to operate.

ALARM 55, AMA Parameter out of range

The parameter values of the motor are outside of the acceptable range. AMA will not run.

ALARM 56, AMA interrupted by user

The user has interrupted the AMA.

ALARM 57, AMA internal fault

Try to restart AMA again a number of times, until the AMA is carried out. Note that repeated runs may heat the motor to a level where the resistance R_s and R_r are increased. In most cases, however, this is not critical.

ALARM 58, AMA internal fault

Contact your Danfoss supplier.

WARNING 59, Current limit

The current is higher than the value in *4-18 Current Limit*. Ensure that Motor data in parameters 1-20 to 1-25 are set correctly. Possibly increase the current limit. Be sure that the system can operate safely at a higher limit.

WARNING 60, External interlock

External interlock has been activated. To resume normal operation, apply 24 V DC to the terminal programmed for external interlock and reset the frequency converter (via serial communication, digital I/O, or by pressing [Reset]).

WARNING/ALARM 61, Tracking error

An error between calculated motor speed and speed measurement from feedback device. The function Warning/Alarm/Disable is set in *4-30 Motor Feedback Loss Function*. Accepted error setting in *4-31 Motor Feedback Speed Error* and the allowed time the error occur setting in *4-32 Motor Feedback Loss Timeout*. During a commissioning procedure the function may be effective.

WARNING 62, Output frequency at maximum limit

The output frequency is higher than the value set in *4-19 Max Output Frequency*.

ALARM 64, Voltage Limit

The load and speed combination demands a motor voltage higher than the actual DC link voltage.

WARNING/ALARM 65, Control card over temperature

The cutout temperature of the control card is 80 °C.

Troubleshooting

- Check that the ambient operating temperature is within limits
- Check for clogged filters
- Check fan operation
- Check the control card

WARNING 66, Heatsink temperature low

The frequency converter is too cold to operate. This warning is based on the temperature sensor in the IGBT module.

Increase the ambient temperature of the unit. Also, a trickle amount of current can be supplied to the frequency converter whenever the motor is stopped by setting *2-00 DC Hold/Preheat Current* at 5% and *1-80 Function at Stop*

Troubleshooting

The heatsink temperature measured as 0° C could indicate that the temperature sensor is defective, causing the fan speed to increase to the maximum. If the sensor wire between the IGBT and the gate drive card is disconnected, this warning would result. Also, check the IGBT thermal sensor.

ALARM 67, Option module configuration has changed

One or more options have either been added or removed since the last power-down. Check that the configuration change is intentional and reset the unit.

ALARM 68, Safe Stop activated

Safe stop has been activated. To resume normal operation, apply 24 V DC to terminal 37, then send a reset signal (via Bus, Digital I/O, or by pressing the reset key).

ALARM 69, Power card temperature

The temperature sensor on the power card is either too hot or too cold.

Troubleshooting

Check the operation of the door fans.

Check that the filters for the door fans are not blocked.

Check that the gland plate is properly installed on IP21/IP 54 (NEMA 1/12) frequency converters.

ALARM 70, Illegal frequency converter configuration

The control card and power card are incompatible. Contact your supplier with the type code of the unit from the nameplate and the part numbers of the cards to check compatibility.

ALARM 71, PTC 1 safe stop

Safe Stop has been activated from the MCB 112 PTC Thermistor Card (motor too warm). Normal operation can be resumed when the MCB 112 applies 24 V DC to T-37 again (when the motor temperature reaches an acceptable level) and when the Digital Input from the MCB 112 is deactivated. When that happens, a reset signal must be sent (via Bus, Digital I/O, or by pressing [Reset]). Note that if automatic restart is enabled, the motor may start when the fault is cleared.

ALARM 72, Dangerous failure

Safe Stop with Trip Lock. Unexpected signal levels on safe stop and digital input from the MCB 112 PTC thermistor card.

WARNING 73, Safe stop auto restart

Safe stopped. With automatic restart enabled, the motor may start when the fault is cleared.

WARNING 76, Power unit setup

The required number of power units does not match the detected number of active power units.

WARNING 77, Reduced power mode

This warning indicates that the frequency converter is operating in reduced power mode (i.e. less than the allowed number of inverter sections). This warning will be generated on power cycle when the frequency converter is set to run with fewer inverters and will remain on.

ALARM 79, Illegal power section configuration

The scaling card is the incorrect part number or not installed. Also MK102 connector on the power card could not be installed.

ALARM 80, Drive initialised to default value

Parameter settings are initialised to default settings after a manual reset. Reset the unit to clear the alarm.

ALARM 81, CSIV corrupt

CSIV file has syntax errors.

ALARM 82, CSIV parameter error

CSIV failed to init a parameter.

ALARM 85, Dang fail PB:

Profibus/Profisafe Error.

WARNING/ALARM 104, Mixing fan fault

The fan monitor checks that the fan is spinning at power-up or whenever the mixing fan is turned on. If the fan is not operating, then the fault is annunciated. The mixing-fan fault can be configured as a warning or an alarm trip by *14-53 Fan Monitor*.

Troubleshooting Cycle power to the frequency converter to determine if the warning/alarm returns.

ALARM 243, Brake IGBT

This alarm is only for F Frame frequency converters. It is equivalent to Alarm 27. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.
- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left intverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

ALARM 244, Heatsink temperature

This alarm is only for F Frame frequency converters. It is equivalent to Alarm 29. The report value in the alarm log indicates which power module generated the alarm.

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.
- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left intverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

ALARM 245, Heatsink sensor

This alarm is only for F Frame frequency converters. It is equivalent to Alarm 39. The report value in the alarm log indicates which power module generated the alarm

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.
- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left intverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

ALARM 246, Power card supply

This alarm is only for F Frame frequency converter. It is equivalent to Alarm 46. The report value in the alarm log indicates which power module generated the alarm

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.
- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left intverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

ALARM 247, Power card temperature

This alarm is only for F Frame frequency converter. It is equivalent to Alarm 69. The report value in the alarm log indicates which power module generated the alarm

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.

- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left inverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

ALARM 248, Illegal power section configuration

This alarm is only for F Frame frequency converters. It is equivalent to Alarm 79. The report value in the alarm log indicates which power module generated the alarm:

- 1 = left most inverter module.
- 2 = middle inverter module in F12 or F3 frame sizes.
- 2 = right inverter module in F10 or F11 frame sizes.
- 2 = second frequency converter from the left inverter module in F14 frame size.
- 3 = right inverter module in F12 or F13 frame sizes.
- 3 = third from the left inverter module in F14 frame size.
- 4 = far right inverter module in F14 frame size.
- 5 = rectifier module.
- 6 = right rectifier module in F14 frame size.

WARNING 250, New spare part

A component in the frequency converter has been replaced. Reset the frequency converter for normal operation.

WARNING 251, New typecode

The power card or other components have been replaced and the typecode changed. Reset to remove the warning and resume normal operation.

9 Basic Troubleshooting

9.1 Start Up and Operation

NOTE

See *Alarm Log* in *Table 4.2*.

Symptom	Possible Cause	Test	Solution
Display dark/No function	Missing input power	See <i>Table 3.1</i> .	Check the input power source.
	Missing or open fuses or circuit breaker tripped	See open fuses and tripped circuit breaker in this table for possible causes.	Follow the recommendations provided.
	No power to the LCP	Check the LCP cable for proper connection or damage.	Replace the faulty LCP or connection cable.
	Shortcut on control voltage (terminal 12 or 50) or at control terminals	Check the 24 V control voltage supply for terminal 12/13 to 20-39 or 10 V supply for terminal 50 to 55.	Wire the terminals properly.
	Wrong LCP (LCP from VLT® 2800 or 5000/6000/8000/ FCD or FCM)		Use only LCP 101 (P/N 130B1124) or LCP 102 (P/N. 130B1107).
	Wrong contrast setting		Press [Status] + ▲/▼ to adjust the contrast.
	Display (LCP) is defective	Test using a different LCP.	Replace the faulty LCP or connection cable.
	Internal voltage supply fault or SMPS is defective		Contact supplier.
Intermittent display	Overloaded power supply (SMPS) due to improper control wiring or a fault within the frequency converter	To rule out a problem in the control wiring, disconnect all control wiring by removing the terminal blocks.	If the display stays lit, then the problem is in the control wiring. Check the wiring for shorts or incorrect connections. If the display continues to cut out, follow the procedure for display dark.

Symptom	Possible Cause	Test	Solution
Motor not running	Service switch open or missing motor connection	Check if the motor is connected and the connection is not interrupted (by a service switch or other device).	Connect the motor and check the service switch.
	No mains power with 24 V DC option card	If the display is functioning but no output, check that mains power is applied to the frequency converter.	Apply mains power to run the unit.
	LCP Stop	Check if [Off] has been pressed.	Press [Auto On] or [Hand On] (depending on your operation mode) to run the motor.
	Missing start signal (Standby)	Check 5-10 <i>Terminal 18 Digital Input</i> for correct setting for terminal 18 (use default setting).	Apply a valid start signal to start the motor.
	Motor coast signal active (Coasting)	Check 5-12 <i>Terminal 27 Digital Input</i> for correct setting for terminal 27 (use default setting).	Apply 24 V on terminal 27 or programm this terminal to <i>No operation</i> .
	Wrong reference signal source	Check reference signal: Local, remote or bus reference? Preset reference active? Terminal connection correct? Scaling of terminals correct? Reference signal available?	Program correct settings Check 3-13 <i>Reference Site</i> Set preset reference active in parameter group 3-1* <i>References</i> . Check for correct wiring. Check scaling of terminals. Check reference signal.
Motor running in wrong direction	Motor rotation limit	Check that 4-10 <i>Motor Speed Direction</i> is programmed correctly.	Program correct settings.
	Active reversing signal	Check if a reversing command is programmed for the terminal in parameter group 5-1* <i>Digital inputs</i> .	Deactivate reversing signal.
	Wrong motor phase connection		See 3.7 <i>Check Motor Rotation</i> in this manual.
Motor is not reaching maximum speed	Frequency limits set wrong	Check output limits in 4-13 <i>Motor Speed High Limit [RPM]</i> , 4-14 <i>Motor Speed High Limit [Hz]</i> , and 4-19 <i>Max Output Frequency</i>	Program correct limits.
	Reference input signal not scaled correctly	Check reference input signal scaling in parameter group 6-* <i>Analog I/O mode</i> and parameter group 3-1* <i>References</i> .	Program correct settings.
Motor speed unstable	Possible incorrect parameter settings	Check the settings of all motor parameters, including all motor compensation settings. For closed loop operation, check PID settings.	Check settings in parameter group 1-6* <i>Analog I/O mode</i> . For closed loop operation check settings in parameter group 20-0* <i>Feedback</i> .
Motor runs rough	Possible over-magnetization	Check for incorrect motor settings in all motor parameters.	Check motor settings in parameter groups 1-2* <i>Motor data</i> 1-3* <i>Adv motor data</i> , and 1-5* <i>Load indep. setting</i> .
Motor will not brake	Possible incorrect settings in the brake parameters. Possible too short ramp down times.	Check brake parameters. Check ramp time settings.	Check parameter group 2-0* <i>DC brake</i> and 3-0* <i>Reference limits</i> .

Symptom	Possible Cause	Test	Solution
Open power fuses or circuit breaker trip	Phase to phase short	Motor or panel has a short phase to phase. Check motor and panel phase to for shorts.	Eliminate any shorts detected.
	Motor overload	Motor is overloaded for the application.	Perform startup test and verify motor current is within specifications. If motor current is exceeding nameplate full load current, motor may run only with reduced load. Review the specifications for the application.
	Loose connections	Perform pre-startup check for loose connections.	Tighten loose connections.
Mains current imbalance greater than 3%	Problem with mains power (See <i>Alarm 4 Mains phase loss</i> description)	Rotate input power leads into the drive one position: A to B, B to C, C to A.	If imbalanced leg follows the wire, it is a power problem. Check mains power supply.
	Problem with the frequency converter unit	Rotate input power leads into the frequency converter one position: A to B, B to C, C to A.	If imbalance leg stays on same input terminal, it is a problem with the unit. Contact supplier.
Motor current imbalance greater than 3%	Problem with motor or motor wiring	Rotate output motor leads one position: U to V, V to W, W to U.	If imbalanced leg follows the wire, the problem is in the motor or motor wiring. Check motor and motor wiring.
	Problem with frequency converter unit	Rotate output motor leads one position: U to V, V to W, W to U.	If imbalance leg stays on same output terminal, it is a problem with the unit. Contact supplier.

Table 9.1 Troubleshooting

10 Specifications

10.1 Power-dependent Specifications

	PK25	PK37	PK55	PK75	P1K1	P1K5	P2K2	P3K0	P3K7
Typical Shaft Output [kW]	0.25	0.37	0.55	0.75	1.1	1.5	2.2	3	3.7
Enclosure IP20/IP21	A2	A2	A2	A2	A2	A2	A2	A3	A3
Enclosure IP20 (FC 301 only)	A1	A1	A1	A1	A1	A1	-	-	-
Enclosure IP55, IP66	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A5	A5
Output current									
Continuous (3x200-240 V) [A]	1.8	2.4	3.5	4.6	6.6	7.5	10.6	12.5	16.7
Intermittent (3x200-240 V) [A]	2.9	3.8	5.6	7.4	10.6	12.0	17.0	20.0	26.7
Continuous kVA (208 V AC) [kVA]	0.65	0.86	1.26	1.66	2.38	2.70	3.82	4.50	6.00
Max. input current									
Continuous (3x200-240 V) [A]	1.6	2.2	3.2	4.1	5.9	6.8	9.5	11.3	15.0
Intermittent (3x200-240 V) [A]	2.6	3.5	5.1	6.6	9.4	10.9	15.2	18.1	24.0
Additional specifications									
IP20, IP21 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)] ²⁾	4,4,4 (12,12,12) (min. 0.2 (24))								
IP55, IP66 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)]	4,4,4 (12,12,12)								
Max. cable cross section ⁵⁾ with disconnect	6,4,4 (10,12,12)								
Estimated power loss at rated max. load [W] ⁴⁾	21	29	42	54	63	82	116	155	185
Weight, enclosure IP20 [kg]	4.7	4.7	4.8	4.8	4.9	4.9	4.9	6.6	6.6
A1 (IP20)	2.7	2.7	2.7	2.7	2.7	2.7	-	-	-
A5 (IP55, IP66)	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5
Efficiency ⁴⁾	0.94	0.94	0.95	0.95	0.96	0.96	0.96	0.96	0.96
0.25-3.7 kW only available as 160% high overload.									

Table 10.1 Mains Supply 3x200-240 V AC

Specifications
**VLT® AutomationDrive Operating
Instructions**

	P5K5		P7K5		P11K	
High/ Normal Load ¹⁾	HO	NO	HO	NO	HO	NO
Typical Shaft Output [kW]	5.5	7.5	7.5	11	11	15
Enclosure IP20	B3		B3		B4	
Enclosure IP21	B1		B1		B2	
Enclosure IP55, IP66	B1		B1		B2	
Output current						
Continuous (3x200-240 V) [A]	24.2	30.8	30.8	46.2	46.2	59.4
Intermittent (60 s overload) (3x200-240 V) [A]	38.7	33.9	49.3	50.8	73.9	65.3
Continuous kVA (208 V AC) [kVA]	8.7	11.1	11.1	16.6	16.6	21.4
Max. input current						
Continuous (3x200-240 V) [A]	22	28	28	42	42	54
Intermittent (60 s overload) (3x200-240 V) [A]	35.2	30.8	44.8	46.2	67.2	59.4
Additional specifications						
IP21 max. cable cross-section ⁵⁾ (mains, brake, load sharing) [mm ² (AWG)] ²⁾	16,10, 16 (6,8,6)		16,10, 16 (6,8,6)		35,-,- (2,-,-)	
IP21 max. cable cross-section ⁵⁾ (motor) [mm ² (AWG)] ²⁾	10,10,- (8,8,-)		10,10,- (8,8,-)		35,25,25 (2,4,4)	
IP20 max. cable cross-section ⁵⁾ (mains, brake, motor and load sharing)	10,10,- (8,8,-)		10,10,- (8,8,-)		35,-,- (2,-,-)	
Max. cable cross-section with Disconnect [mm ² (AWG)] ²⁾	16,10,10 (6,8,8)					
Estimated power loss at rated max. load [W] ⁴⁾	239	310	371	514	463	602
Weight, enclosure IP21, IP55, IP66 [kg]	23		23		27	
Efficiency ⁴⁾	0.964		0.959		0.964	

Table 10.2 Mains Supply 3x200-240 V AC

Specifications

VLT® AutomationDrive Operating Instructions

	P15K		P18K		P22K		P30K		P37K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft Output [kW]	15	18.5	18.5	22	22	30	30	37	37	45
Enclosure IP20	B4		C3		C3		C4		C4	
Enclosure IP21	C1		C1		C1		C2		C2	
Enclosure IP55, IP66	C1		C1		C1		C2		C2	
Output current										
Continuous (3x200-240 V) [A]	59.4	74.8	74.8	88	88	115	115	143	143	170
Intermittent (60 s overload) (3x200-240 V) [A]	89.1	82.3	112	96.8	132	127	173	157	215	187
Continuous kVA (208 V AC) [kVA]	21.4	26.9	26.9	31.7	31.7	41.4	41.4	51.5	51.5	61.2
Max. input current										
Continuous (3x200-240 V) [A]	54	68	68	80	80	104	104	130	130	154
Intermittent (60 s overload) (3x200-240 V) [A]	81	74.8	102	88	120	114	156	143	195	169
Additional specifications										
IP20 max. cable cross-section ⁵⁾ (mains, brake, motor and load sharing)	35 (2)		50 (1)		50 (1)		150 (300MCM)		150 (300MCM)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (mains, motor) [mm ² (AWG)] ²⁾	50 (1)		50 (1)		50 (1)		150 (300MCM)		150 (300MCM)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (brake, load sharing) [mm ² (AWG)] ²⁾	50 (1)		50 (1)		50 (1)		95 (3/0)		95 (3/0)	
Max cable size with mains disconnect [mm ² (AWG)] ²⁾	50, 35, 35 (1, 2, 2)						95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350MCM, 300MCM, 4/0)	
Estimated power loss at rated max. load [W] ⁴⁾	624	737	740	845	874	1140	1143	1353	1400	1636
Weight, enclosure IP21, IP55/IP66 [kg]	45		45		45		65		65	
Efficiency ⁴⁾	0.96		0.97		0.97		0.97		0.97	

Table 10.3 Mains Supply 3x200-240 V AC

For fuse ratings, see 10.3.1 Fuses

1) High overload = 160% torque during 60 s. Normal overload = 110% torque during 60 s.

2) American Wire Gauge.

3) Measured using 5 m screened motor cables at rated load and rated frequency.

4) The typical power loss is at nominal load conditions and expected to be within $\pm 15\%$ (tolerance relates to variety in voltage and cable conditions).

Values are based on a typical motor efficiency (eff2/eff3 border line). Motors with lower efficiency will also add to the power loss in the frequency converter and opposite.

If the switching frequency is increased compared to the default setting, the power losses may rise significantly.

LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 W to the losses. (Though typical only 4 W extra for a fully loaded control card, or options for slot A or slot B, each).

Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for ($\pm 5\%$).

5) The three values for the max. cable cross section are for single core, flexible wire and flexible wire with sleeve, respectively.

Specifications

VLT® AutomationDrive Operating Instructions

	PK 37	PK 55	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical Shaft Output [kW]	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5
Enclosure IP20/IP21	A2	A2	A2	A2	A2	A2	A2	A2	A3	A3
Enclosure IP20 (FC 301 only)	A1	A1	A1	A1	A1					
Enclosure IP55, IP66	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A5	A5
Output current										
High overload 160% for 1 min.										
Shaft output [kW]	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5
Continuous (3x380-440 V) [A]	1.3	1.8	2.4	3	4.1	5.6	7.2	10	13	16
Intermittent (3x380-440 V) [A]	2.1	2.9	3.8	4.8	6.6	9.0	11.5	16	20.8	25.6
Continuous (3x441-500 V) [A]	1.2	1.6	2.1	2.7	3.4	4.8	6.3	8.2	11	14.5
Intermittent (3x441-500 V) [A]	1.9	2.6	3.4	4.3	5.4	7.7	10.1	13.1	17.6	23.2
Continuous kVA (400 V AC) [kVA]	0.9	1.3	1.7	2.1	2.8	3.9	5.0	6.9	9.0	11.0
Continuous kVA (460 V AC) [kVA]	0.9	1.3	1.7	2.4	2.7	3.8	5.0	6.5	8.8	11.6
Max. input current										
Continuous (3x380-440 V) [A]	1.2	1.6	2.2	2.7	3.7	5.0	6.5	9.0	11.7	14.4
Intermittent (3x380-440 V) [A]	1.9	2.6	3.5	4.3	5.9	8.0	10.4	14.4	18.7	23.0
Continuous (3x441-500 V) [A]	1.0	1.4	1.9	2.7	3.1	4.3	5.7	7.4	9.9	13.0
Intermittent (3x441-500 V) [A]	1.6	2.2	3.0	4.3	5.0	6.9	9.1	11.8	15.8	20.8
Additional specifications										
IP20, IP21 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)] ²⁾	4,4,4 (12,12,12) (min. 0.2(24))									
IP55, IP66 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)]	4,4,4 (12,12,12)									
Max. cable cross section ⁵⁾ with disconnect	6,4,4 (10,12,12)									
Estimated power loss at rated max. load [W] ⁴⁾	35	42	46	58	62	88	116	124	187	255
Weight, enclosure IP20	4.7	4.7	4.8	4.8	4.9	4.9	4.9	4.9	6.6	6.6
Enclosure IP55, IP66	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	14.2	14.2
Efficiency ⁴⁾	0.93	0.95	0.96	0.96	0.97	0.97	0.97	0.97	0.97	0.97
0.37-7.5 kW only available as 160% high overload.										

Table 10.4 Mains Supply 3x380-500 V AC (FC 302), 3x380-480 V AC (FC 301)

Specifications

VLT® AutomationDrive Operating Instructions

	P11K		P15K		P18K		P22K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft output [kW]	11	15	15	18.5	18.5	22.0	22.0	30.0
Enclosure IP20	B3		B3		B4		B4	
Enclosure IP21	B1		B1		B2		B2	
Enclosure IP55, IP66	B1		B1		B2		B2	
Output current								
Continuous (3x380-440 V) [A]	24	32	32	37.5	37.5	44	44	61
Intermittent (60 s overload) (3x380-440 V) [A]	38.4	35.2	51.2	41.3	60	48.4	70.4	67.1
Continuous (3x441-500 V) [A]	21	27	27	34	34	40	40	52
Intermittent (60 s overload) (3x441-500 V) [A]	33.6	29.7	43.2	37.4	54.4	44	64	57.2
Continuous kVA (400 V AC) [kVA]	16.6	22.2	22.2	26	26	30.5	30.5	42.3
Continuous kVA (460 V AC) [kVA]		21.5		27.1		31.9		41.4
Max. input current								
Continuous (3x380-440 V) [A]	22	29	29	34	34	40	40	55
Intermittent (60 s overload) (3x380-440 V) [A]	35.2	31.9	46.4	37.4	54.4	44	64	60.5
Continuous (3x441-500 V) [A]	19	25	25	31	31	36	36	47
Intermittent (60 s overload) (3x441-500 V) [A]	30.4	27.5	40	34.1	49.6	39.6	57.6	51.7
Additional specifications								
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (mains, brake, load sharing) [mm ² (AWG)] ²⁾	16, 10, 16 (6, 8, 6)		16, 10, 16 (6, 8, 6)		35,-,-(2,-,-)		35,-,-(2,-,-)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (motor) [mm ² (AWG)] ²⁾	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35, 25, 25 (2, 4, 4)		35, 25, 25 (2, 4, 4)	
IP20 max. cable cross-section ⁵⁾ (mains, brake, motor and load sharing)	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,-,-(2,-,-)		35,-,-(2,-,-)	
Max. cable cross-section with Disconnect [mm ² (AWG)] ²⁾	16, 10, 10 (6, 8, 8)							
Estimated power loss at rated max. load [W] ⁴⁾	291	392	379	465	444	525	547	739
Weight, enclosure IP20 [kg]	12		12		23.5		23.5	
Weight, enclosure IP21, IP55, 66 [kg]	23		23		27		27	
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 10.5 Mains Supply 3x380-500 V AC (FC 302), 3x380-480 V AC (FC 301)

Specifications

VLT® AutomationDrive Operating Instructions

	P30K		P37K		P45K		P55K		P75K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft output [kW]	30	37	37	45	45	55	55	75	75	90
Enclosure IP20	B4		C3		C3		C4		C4	
Enclosure IP21	C1		C1		C1		C2		C2	
Enclosure IP55, IP66	C1		C1		C1		C2		C2	
Output current										
Continuous (3x380-440 V) [A]	61	73	73	90	90	106	106	147	147	177
Intermittent (60 s overload) (3x380-440 V) [A]	91.5	80.3	110	99	135	117	159	162	221	195
Continuous (3x441-500 V) [A]	52	65	65	80	80	105	105	130	130	160
Intermittent (60 s overload) (3x441-500 V) [A]	78	71.5	97.5	88	120	116	158	143	195	176
Continuous kVA (400 V AC) [kVA]	42.3	50.6	50.6	62.4	62.4	73.4	73.4	102	102	123
Continuous kVA (460 V AC) [kVA]		51.8		63.7		83.7		104		128
Max. input current										
Continuous (3x380-440 V) [A]	55	66	66	82	82	96	96	133	133	161
Intermittent (60 s overload) (3x380-440 V) [A]	82.5	72.6	99	90.2	123	106	144	146	200	177
Continuous (3x441-500 V) [A]	47	59	59	73	73	95	95	118	118	145
Intermittent (60 s overload) (3x441-500 V) [A]	70.5	64.9	88.5	80.3	110	105	143	130	177	160
Additional specifications										
IP20 max. cable cross-section ⁵⁾ (mains and motor)	35 (2)		50 (1)		50 (1)		150 (300 MCM)		150 (300 MCM)	
IP20 max. cable cross-section ⁵⁾ (brake and load sharing)	35 (2)		50 (1)		50 (1)		95 (4/0)		95 (4/0)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (mains, motor) [mm ² (AWG)] ²⁾	50 (1)		50 (1)		50 (1)		150 (300 MCM)		150 (300MCM)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (brake, load sharing) [mm ² (AWG)] ²⁾	50 (1)		50 (1)		50 (1)		95 (3/0)		95 (3/0)	
Max cable size with mains disconnect [mm ² (AWG)] ²⁾	50, 35, 35 (1, 2, 2)						95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350 MCM, 300 MCM, 4/0)	
Estimated power loss at rated max. load [W] ⁴⁾	570	698	697	843	891	1083	1022	1384	1232	1474
Weight, enclosure IP21, IP55, IP66 [kg]	45		45		45		65		65	
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.99	

Table 10.6 Mains Supply 3x380-500 V AC (FC 302), 3x380-480 V AC (FC 301)

For fuse ratings, see 10.3.1 Fuses

1) High overload = 160% torque during 60 s. Normal overload = 110% torque during 60 s.

2) American Wire Gauge.

3) Measured using 5 m screened motor cables at rated load and rated frequency.

4) The typical power loss is at nominal load conditions and expected to be within $\pm 15\%$ (tolerance relates to variety in voltage and cable conditions).

Values are based on a typical motor efficiency (eff2/eff3 border line). Motors with lower efficiency will also add to the power loss in the frequency converter and opposite.

If the switching frequency is increased compared to the default setting, the power losses may rise significantly.

LCP and typical control card power consumptions are included. Further options and customer load may add up to 30W to the losses. (Though typical only 4W extra for a fully loaded control card, or options for slot A or slot B, each).

Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for ($\pm 5\%$).

5) The three values for the max. cable cross section are for single core, flexible wire and flexible wire with sleeve, respectively.

	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical Shaft Output [kW]	0.75	1.1	1.5	2.2	3	4	5.5	7.5
Enclosure IP20, IP21	A3	A3	A3	A3	A3	A3	A3	A3
Enclosure IP55	A5	A5	A5	A5	A5	A5	A5	A5
Output current								
Continuous (3x525-550 V) [A]	1.8	2.6	2.9	4.1	5.2	6.4	9.5	11.5
Intermittent (3x525-550 V) [A]	2.9	4.2	4.6	6.6	8.3	10.2	15.2	18.4
Continuous (3x551-600 V) [A]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0
Intermittent (3x551-600 V) [A]	2.7	3.8	4.3	6.2	7.8	9.8	14.4	17.6
Continuous kVA (525 V AC) [kVA]	1.7	2.5	2.8	3.9	5.0	6.1	9.0	11.0
Continuous kVA (575 V AC) [kVA]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0
Max. input current								
Continuous (3x525-600 V) [A]	1.7	2.4	2.7	4.1	5.2	5.8	8.6	10.4
Intermittent (3x525-600 V) [A]	2.7	3.8	4.3	6.6	8.3	9.3	13.8	16.6
Additional specifications								
IP20, IP21 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)] ²⁾	4,4,4 (12,12,12) (min. 0.2 (24))							
IP55, IP66 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)]	4,4,4 (12,12,12)							
Max. cable cross section ⁵⁾ with disconnect	6,4,4 (10,12,12)							
Estimated power loss at rated max. load [W] ⁴⁾	35	50	65	92	122	145	195	261
Weight, Enclosure IP20 [kg]	6.5	6.5	6.5	6.5	6.5	6.5	6.6	6.6
Weight, enclosure IP55 [kg]	13.5	13.5	13.5	13.5	13.5	13.5	14.2	14.2
Efficiency ⁴⁾	0.97	0.97	0.97	0.97	0.97	0.97	0.97	0.97

Table 10.7 Mains Supply 3x525-600 V AC (FC 302 only)

Specifications

VLT® AutomationDrive Operating Instructions

	P11K		P15K		P18K		P22K		P30K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft Output [kW]	11	15	15	18.5	18.5	22	22	30	30	37
Enclosure IP21, IP55, IP66	B1		B1		B2		B2		C1	
Enclosure IP20	B3		B3		B4		B4		B4	
Output current										
Continuous (3x525-550 V) [A]	19	23	23	28	28	36	36	43	43	54
Intermittent (3x525-550 V) [A]	30	25	37	31	45	40	58	47	65	59
Continuous (3x525-600 V) [A]	18	22	22	27	27	34	34	41	41	52
Intermittent (3x525-600 V) [A]	29	24	35	30	43	37	54	45	62	57
Continuous kVA (550 V AC) [kVA]	18.1	21.9	21.9	26.7	26.7	34.3	34.3	41.0	41.0	51.4
Continuous kVA (575 V AC) [kVA]	17.9	21.9	21.9	26.9	26.9	33.9	33.9	40.8	40.8	51.8
Max. input current										
Continuous at 550 V [A]	17.2	20.9	20.9	25.4	25.4	32.7	32.7	39	39	49
Intermittent at 550 V [A]	28	23	33	28	41	36	52	43	59	54
Continuous at 575 V [A]	16	20	20	24	24	31	31	37	37	47
Intermittent at 575 V [A]	26	22	32	27	39	34	50	41	56	52
Additional specifications										
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (mains, brake, load sharing) [mm ² (AWG)] ²⁾	16, 10, 10 (6, 8, 8)		16, 10, 10 (6, 8, 8)		35,-,-(2,-,-)		35,-,-(2,-,-)		50,-,- (1,-,-)	
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (motor) [mm ² (AWG)] ²⁾	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35, 25, 25 (2, 4, 4)		35, 25, 25 (2, 4, 4)		50,-,- (1,-,-)	
IP20 max. cable cross-section ⁵⁾ (mains, brake, motor and load sharing)	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,-,-(2,-,-)		35,-,-(2,-,-)		35,-,-(2,-,-)	
Max. cable cross-section with Disconnect [mm ² (AWG)] ²⁾	16, 10, 10 (6, 8, 8)									
Estimated power loss at rated max. load [W] ⁴⁾	225		285		329		700		700	
Weight, enclosure IP21, [kg]	23		23		27		27		27	
Weight, enclosure IP20 [kg]	12		12		23.5		23.5		23.5	
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.98	

Table 10.8 Mains Supply 3x525-600 V AC (FC 302 only)

Specifications

VLT® AutomationDrive Operating Instructions

	P37K		P45K		P55K		P75K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft Output [kW]	37	45	45	55	55	75	75	90
Enclosure IP21, IP55, IP66	C1	C1	C1		C2		C2	
Enclosure IP20	C3	C3	C3		C4		C4	
Output current								
Continuous (3x525-550 V) [A]	54	65	65	87	87	105	105	137
Intermittent (3x525-550 V) [A]	81	72	98	96	131	116	158	151
Continuous (3x525-600 V) [A]	52	62	62	83	83	100	100	131
Intermittent (3x525-600 V) [A]	78	68	93	91	125	110	150	144
Continuous kVA (550 V AC) [kVA]	51.4	61.9	61.9	82.9	82.9	100.0	100.0	130.5
Continuous kVA (575 V AC) [kVA]	51.8	61.7	61.7	82.7	82.7	99.6	99.6	130.5
Max. input current								
Continuous at 550 V [A]	49	59	59	78.9	78.9	95.3	95.3	124.3
Intermittent at 550 V [A]	74	65	89	87	118	105	143	137
Continuous at 575 V [A]	47	56	56	75	75	91	91	119
Intermittent at 575 V [A]	70	62	85	83	113	100	137	131
Additional specifications								
IP20 max. cable cross-section ⁵⁾ (mains and motor)	50 (1)				150 (300 MCM)			
IP20 max. cable cross-section ⁵⁾ (brake and load sharing)	50 (1)				95 (4/0)			
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (mains, motor) [mm ² (AWG)] ²⁾	50 (1)				150 (300 MCM)			
IP21, IP55, IP66 max. cable cross-section ⁵⁾ (brake, load sharing) [mm ² (AWG)] ²⁾	50 (1)				95 (4/0)			
Max cable size with mains disconnect [mm ² (AWG)] ²⁾	50, 35, 35 (1, 2, 2)				95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350MCM, 300MCM, 4/0)	
Estimated power loss at rated max. load [W] ⁴⁾	850		1100		1400		1500	
Weight, enclosure IP20 [kg]	35		35		50		50	
Weight, enclosure IP21, IP55 [kg]	45		45		65		65	
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 10.9 Mains Supply 3x525-600 V AC (FC 302 only)

Specifications

VLT® AutomationDrive Operating Instructions

	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical Shaft Output [kW]	1.1	1.5	2.2	3	4	5.5	7.5
Enclosure IP20 (only)	A3	A3	A3	A3	A3	A3	A3
Output current High overload 160% for 1 min							
Continuous (3x525-550 V) [A]	2.1	2.7	3.9	4.9	6.1	9	11
Intermittent (3x525-550 V) [A]	3.4	4.3	6.2	7.8	9.8	14.4	17.6
Continuous kVA (3x551-690 V) [A]	1.6	2.2	3.2	4.5	5.5	7.5	10
Intermittent kVA (3x551-690 V) [A]	2.6	3.5	5.1	7.2	8.8	12	16
Continuous kVA 525 V AC	1.9	2.5	3.5	4.5	5.5	8.2	10
Continuous kVA 690 V AC	1.9	2.6	3.8	5.4	6.6	9	12
Max. input current							
Continuous (3x525-550 V) [A]	1.9	2.4	3.5	4.4	5.5	8	10
Intermittent (3x525-550 V) [A]	3.0	3.9	5.6	7.1	8.8	13	16
Continuous kVA (3x551-690 V) [A]	1.4	2.0	2.9	4.0	4.9	6.7	9
Intermittent kVA (3x551-690 V) [A]	2.3	3.2	4.6	6.5	7.9	10.8	14.4
Additional specifications							
IP20 max. cable cross section ⁵⁾ (mains, motor, brake and load sharing) [mm ² (AWG)]	0.2-4 (24-12)						
Estimated power loss at rated max. load [W] ⁴⁾	44	60	88	120	160	220	300
Weight, enclosure IP20 [kg]	6.6	6.6	6.6	6.6	6.6	6.6	6.6
Efficiency ⁴⁾	0.96	0.96	0.96	0.96	0.96	0.96	0.96

Table 10.10 A3 Frame,
Mains Supply 3x525-690 V AC IP20/Protected Chassis

Specifications

VLT® AutomationDrive Operating Instructions

	P11K		P15K		P18K		P22K	
High/Normal Load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft output at 550 V [kW]	7.5	11	11	15	15	18.5	18.5	22
Typical Shaft output at 575 V [hp]	11	15	15	20	20	25	25	30
Typical Shaft output at 690 V [kW]	11	15	15	18.5	18.5	22	22	30
Enclosure IP21, IP55	B2		B2		B2		B2	
Output current								
Continuous (3x525-550 V) [A]	14	19	19	23	23	28	28	36
Intermittent (60 s overload) (3x525-550 V) [A]	22.4	20.9	30.4	25.3	36.8	30.8	44.8	39.6
Continuous (3x551-690 V) [A]	13	18	18	22	22	27	27	34
Intermittent (60 s overload) (3x551-690 V) [A]	20.8	19.8	28.8	24.2	35.2	29.7	43.2	37.4
Continuous KVA (at 550 V) [KVA]	13.3	18.1	18.1	21.9	21.9	26.7	26.7	34.3
Continuous KVA (at 575 V) [KVA]	12.9	17.9	17.9	21.9	21.9	26.9	26.9	33.9
Continuous KVA (at 690 V) [KVA]	15.5	21.5	21.5	26.3	26.3	32.3	32.3	40.6
Max. input current								
Continuous (3x525-690 V) [A]	15	19.5	19.5	24	24	29	29	36
Intermittent (60 s overload) (3x525-690 V) [A]	23.2	21.5	31.2	26.4	38.4	31.9	46.4	39.6
Additional specifications								
Max. cable cross section (mains, load share and brake) [mm ² (AWG)]	35,-,- (2,-,-)							
Max. cable cross section (motor) [mm ² (AWG)]	35, 25, 25 (2, 4, 4)							
Max cable size with mains disconnect [mm ² (AWG)] ²⁾	16,10,10 (6,8, 8)							
Estimated power loss at rated max. load [W] ⁴⁾	228		285		335		375	
Weight, enclosure IP21, IP55 [kg]	27							
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 10.11 B2 Frame,
Mains Supply 3x525-690 V AC IP21/IP55 - NEMA 1/NEMA 12 (FC 302 only)

Specifications

VLT® AutomationDrive Operating Instructions

	P30K		P37K		P45K		P55K		P75K	
High/Normal Load*	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical Shaft output at 550 V [kW]	22	30	30	37	37	45	45	55	55	75
Typical Shaft output at 575 V [hp]	30	40	40	50	50	60	60	75	75	100
Typical Shaft output at 690 V [kW]	30	37	37	45	45	55	55	75	75	90
Enclosure IP21, IP55	C2		C2		C2		C2		C2	
Output current										
Continuous (3x525-550 V) [A]	36	43	43	54	54	65	65	87	87	105
Intermittent (60 s overload) (3x525-550 V) [A]	54	47.3	64.5	59.4	81	71.5	97.5	95.7	130.5	115.5
Continuous (3x551-690 V) [A]	34	41	41	52	52	62	62	83	83	100
Intermittent (60 s overload) (3x551-690 V) [A]	51	45.1	61.5	57.2	78	68.2	93	91.3	124.5	110
Continuous KVA (at 550 V) [KVA]	34.3	41.0	41.0	51.4	51.4	61.9	61.9	82.9	82.9	100.0
Continuous KVA (at 575 V) [KVA]	33.9	40.8	40.8	51.8	51.8	61.7	61.7	82.7	82.7	99.6
Continuous KVA (at 690 V) [KVA]	40.6	49.0	49.0	62.1	62.1	74.1	74.1	99.2	99.2	119.5
Max. input current										
Continuous (at 550 V) [A]	36	49	49	59	59	71	71	87	87	99
Continuous (at 575 V) [A]	54	53.9	72	64.9	87	78.1	105	95.7	129	108.9
Additional specifications										
Max. cable cross section (mains and motor) [mm ² (AWG)]	150 (300 MCM)									
Max. cable cross section (load share and brake) [mm ² (AWG)]	95 (3/0)									
Max cable size with mains disconnect [mm ² (AWG)] ²⁾	95, 70, 70 (3/0, 2/0, 2/0)						185, 150, 120 (350 MCM, 300 MCM, 4/0)		-	
Estimated power loss at rated max. load [W] ⁴⁾	480		592		720		880		1200	
Weight, enclosure IP21, IP55 [kg]	65									
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.98	

Table 10.12 C2 Frame,
Mains Supply 3x525-690 V AC IP21/IP55 - NEMA 1/NEMA 12 (FC 302 only)

Specifications

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	P37K		P45K	
High/Normal Load ¹⁾	HO	NO	HO	NO
Typical Shaft output at 550 V [kW]	30	37	37	45
Typical Shaft output at 575 V [hp]	40	50	50	60
Typical Shaft output at 690 V [kW]	37	45	45	55
Enclosure IP20 only	C3		C3	
Output current 150% for 1 min (HO), 110% for 1 min (NO)				
Continuous (3x525-550 V) [A]	43	54	54	65
Intermittent (60 s overload) (3x525-550 V) [A]	64.5	59.4	81	71.5
Continuous (3x551-690 V) [A]	41	52	52	62
Intermittent (60 s overload) (3x551-690 V) [A]	61.5	57.2	78	68.2
Continuous KVA (at 550 V) [KVA]	41	51.4	51.4	62
Continuous KVA (at 690 V) [KVA]	49	62.2	62.2	74.1
Max. input current				
Continuous (at 550 V) [A]	41.5	52.1	52.1	62.7
Intermittent (at 550 V) [A]	62.2	57.3	78.1	68.9
Continuous (at 690 V) [A]	39.5	50.1	50.1	59.8
Intermittent (at 690 V) [A]	59.3	55.1	75.2	65.8
Additional specifications				
Max. cable cross section (mains, load share and brake) [mm² (AWG)]	50 (1)			
Max. cable cross section (motor) [mm² (AWG)]	50 (1)			
Estimated power loss at rated max. load [W] ⁴⁾	592		720	
Weight, enclosure IP20 [kg]	35		35	
Efficiency ⁴⁾	0.98		0.98	

**Table 10.13 C3 Frame,
Mains Supply 3x525-690 V AC IP20/Protected Chassis (FC 302 only)**

For fuse ratings, see 10.3.1 Fuses

¹⁾ High overload=160% torque during 60 s. Normal overload=110% torque during 60 s.

²⁾ American Wire Gauge.

³⁾ Measured using 5 m screened motor cables at rated load and rated frequency.

⁴⁾ The typical power loss is at nominal load conditions and expected to be within $\pm 15\%$ (tolerance relates to variety in voltage and cable conditions).

Values are based on a typical motor efficiency (eff2/eff3 border line). Motors with lower efficiency will also add to the power loss in the frequency converter and opposite.

If the switching frequency is increased compared to the default setting, the power losses may rise significantly.

LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 W to the losses. (Though typical only 4 W extra for a fully loaded control card, or options for slot A or slot B, each).

Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for ($\pm 5\%$).

⁵⁾ The three values for the max. cable cross section are for single core, flexible wire and flexible wire with sleeve, respectively.

10.2 General Technical Data

Mains supply

Supply Terminals (6-Pulse)	L1, L2, L3
Supply Terminals (12-Pulse)	L1-1, L2-1, L3-1, L1-2, L2-2, L3-2
Supply voltage	200-240 V $\pm 10\%$
Supply voltage	FC 301: 380-480 V/FC 302: 380-500 V $\pm 10\%$
Supply voltage	FC 302: 525-600 V $\pm 10\%$
Supply voltage	FC 302: 525-690 V $\pm 10\%$

Mains voltage low / mains drop-out:

During low mains voltage or a mains drop-out, the frequency converter continues until the intermediate circuit voltage drops below the minimum stop level, which corresponds typically to 15% below the frequency converter's lowest rated supply voltage. Power-up and full torque cannot be expected at mains voltage lower than 10% below the frequency converter's lowest rated supply voltage.

Supply frequency	50/60 Hz $\pm 5\%$
Max. imbalance temporary between mains phases	3.0 % of rated supply voltage
True Power Factor (λ)	≥ 0.9 nominal at rated load
Displacement Power Factor ($\cos \phi$)	near unity (> 0.98)
Switching on input supply L1, L2, L3 (power-ups) ≤ 7.5 kW	maximum 2 times/min.
Switching on input supply L1, L2, L3 (power-ups) 11-75 kW	maximum 1 time/min.
Switching on input supply L1, L2, L3 (power-ups) ≥ 90 kW	maximum 1 time/2 min.
Environment according to EN60664-1	overvoltage category III/pollution degree 2

The unit is suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical Amperes, 240/500/600/ 690 V maximum.

Motor output (U, V, W)

Output voltage	0-100% of supply voltage
Output frequency (0.25-75 kW)	FC 301: 0.2-590 Hz/FC 302: 0-590 Hz
Output frequency (90-1000 kW)	0-590 ¹⁾ Hz
Output frequency in Flux Mode (FC 302 only)	0-300 Hz
Switching on output	Unlimited
Ramp times	0.01-3600 s

¹⁾ Voltage and power dependent

Torque characteristics

Starting torque (constant torque)	maximum 160% for 60 s ¹⁾
Starting torque	maximum 180% up to 0.5 s ¹⁾
Overload torque (constant torque)	maximum 160% for 60 s ¹⁾
Starting torque (variable torque)	maximum 110% for 60 s ¹⁾
Overload torque (variable torque)	maximum 110% for 60 s
Torque rise time in VVC ^{plus} (independent of fsw)	10 ms
Torque rise time in FLUX (for 5 kHz fsw)	1 ms

¹⁾ Percentage relates to the nominal torque.

²⁾ The torque response time depends on application and load but as a general rule, the torque step from 0 to reference is 4-5 x torque rise time.

Digital inputs

Programmable digital inputs	FC 301: 4 (5) ¹⁾ /FC 302: 4 (6) ¹⁾
Terminal number	18, 19, 27 ¹⁾ , 29 ¹⁾ , 32, 33,
Logic	PNP or NPN
Voltage level	0 - 24 V DC
Voltage level, logic '0' PNP	< 5 V DC
Voltage level, logic '1' PNP	> 10 V DC
Voltage level, logic '0' NPN ²⁾	> 19 V DC
Voltage level, logic '1' NPN ²⁾	< 14 V DC

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Maximum voltage on input	28 V DC
Pulse frequency range	0-110 kHz
(Duty cycle) Min. pulse width	4.5 ms
Input resistance, R_i	approx. 4 k Ω

Safe stop Terminal 37^{3, 4)} (Terminal 37 is fixed PNP logic)

Voltage level	0-24 V DC
Voltage level, logic'0' PNP	<4 V DC
Voltage level, logic'1' PNP	>20 V DC
Maximum voltage on input	28 V DC
Typical input current at 24 V	50 mA rms
Typical input current at 20 V	60 mA rms
Input capacitance	400 nF

All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

¹⁾ Terminals 27 and 29 can also be programmed as output.

²⁾ Except safe stop input Terminal 37.

³⁾ See 2.5 Safe Stop for further information about terminal 37 and Safe Stop.

⁴⁾ When using a contactor with a DC coil inside in combination with Safe Stop, it is important to make a return way for the current from the coil when turning it off. This can be done by using a freewheel diode (or, alternatively, a 30 or 50 V MOV for quicker response time) across the coil. Typical contactors can be bought with this diode.

Analog inputs

Number of analog inputs	2
Terminal number	53, 54
Modes	Voltage or current
Mode select	Switch S201 and switch S202
Voltage mode	Switch S201/switch S202 = OFF (U)
Voltage level	FC 301: 0 to +10 V/FC 302: -10 to +10 V (scaleable)
Input resistance, R_i	approx. 10 k Ω
Max. voltage	± 20 V
Current mode	Switch S201/switch S202 = ON (I)
Current level	0/4 to 20 mA (scaleable)
Input resistance, R_i	approx. 200 Ω
Max. current	30 mA
Resolution for analog inputs	10 bit (+ sign)
Accuracy of analog inputs	Max. error 0.5% of full scale
Bandwidth	FC 301: 20 Hz/FC 302: 100 Hz

The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

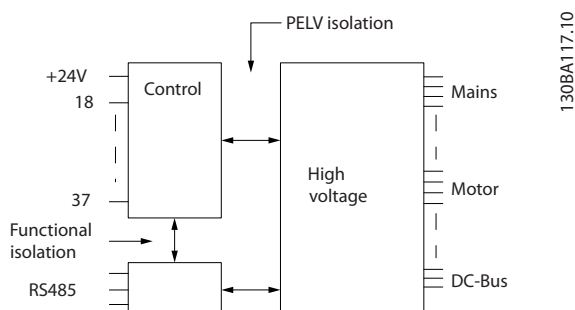


Illustration 10.1

Specifications

VLT® AutomationDrive Operating Instructions

Pulse/encoder inputs

Programmable pulse/encoder inputs	2/1
Terminal number pulse/encoder	29 ¹⁾ , 33 ²⁾ / 32 ³⁾ , 33 ³⁾
Max. frequency at terminal 29, 32, 33	110 kHz (Push-pull driven)
Max. frequency at terminal 29, 32, 33	5 kHz (open collector)
Min. frequency at terminal 29, 32, 33	4 Hz
Voltage level	see section on Digital input
Maximum voltage on input	28 V DC
Input resistance, R _i	approx. 4 kΩ
Pulse input accuracy (0.1-1 kHz)	Max. error: 0.1% of full scale
Encoder input accuracy (1-11 kHz)	Max. error: 0.05 % of full scale

The pulse and encoder inputs (terminals 29, 32, 33) are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

¹⁾ FC 302 only

²⁾ Pulse inputs are 29 and 33

³⁾ Encoder inputs: 32 = A, and 33 = B

Digital output

Programmable digital/pulse outputs	2
Terminal number	27, 29 ¹⁾
Voltage level at digital/frequency output	0-24 V
Max. output current (sink or source)	40 mA
Max. load at frequency output	1 kΩ
Max. capacitive load at frequency output	10 nF
Minimum output frequency at frequency output	0 Hz
Maximum output frequency at frequency output	32 kHz
Accuracy of frequency output	Max. error: 0.1 % of full scale
Resolution of frequency outputs	12 bit

¹⁾ Terminal 27 and 29 can also be programmed as input.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Analog output

Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4 to 20 mA
Max. load GND - analog output less than	500 Ω
Accuracy on analog output	Max. error: 0.5% of full scale
Resolution on analog output	12 bit

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, 24 V DC output

Terminal number	12, 13
Output voltage	24 V +1, -3 V
Max. load	FC 301: 130mA/FC 302: 200 mA

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same potential as the analog and digital inputs and outputs.

Control card, 10 V DC output

Terminal number	±50
Output voltage	10.5 V ±0.5 V
Max. load	15 mA

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, RS-485 serial communication

Terminal number	68 (P,TX+, RX+), 69 (N,TX-, RX-)
Terminal number 61	Common for terminals 68 and 69

The RS-485 serial communication circuit is functionally separated from other central circuits and galvanically isolated from the supply voltage (PELV).

Control card, USB serial communication

USB standard	1.1 (Full speed)
USB plug	USB type B "device" plug

Connection to PC is carried out via a standard host/device USB cable.

The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

The USB ground connection is not galvanically isolated from protection earth. Use only an isolated laptop as PC connection to the USB connector on the frequency converter.

Relay outputs

Programmable relay outputs	FC 301 all kW: 1/FC 302 all kW: 2
Relay 01 Terminal number	1-3 (break), 1-2 (make)
Max. terminal load (AC-1) ¹⁾ on 1-3 (NC), 1-2 (NO) (Resistive load)	240 V AC, 2A
Max. terminal load (AC-15) ¹⁾ (Inductive load @ cosφ 0.4)	240 V AC, 0.2A
Max. terminal load (DC-1) ¹⁾ on 1-2 (NO), 1-3 (NC) (Resistive load)	60 V DC, 1A
Max. terminal load (DC-13) ¹⁾ (Inductive load)	24 V DC, 0.1A
Relay 02 (FC 302 only) Terminal number	4-6 (break), 4-5 (make)
Max. terminal load (AC-1) ¹⁾ on 4-5 (NO) (Resistive load) ²⁾³⁾ Overvoltage cat. II	400 V AC, 2A
Max. terminal load (AC-15) ¹⁾ on 4-5 (NO) (Inductive load @ cosφ 0.4)	240 V AC, 0.2A
Max. terminal load (DC-1) ¹⁾ on 4-5 (NO) (Resistive load)	80 V DC, 2A
Max. terminal load (DC-13) ¹⁾ on 4-5 (NO) (Inductive load)	24 V DC, 0.1A
Max. terminal load (AC-1) ¹⁾ on 4-6 (NC) (Resistive load)	240 V AC, 2A
Max. terminal load (AC-15) ¹⁾ on 4-6 (NC) (Inductive load @ cosφ 0.4)	240 V AC, 0.2A
Max. terminal load (DC-1) ¹⁾ on 4-6 (NC) (Resistive load)	50 V DC, 2A
Max. terminal load (DC-13) ¹⁾ on 4-6 (NC) (Inductive load)	24 V DC, 0.1A
Min. terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO)	24 V DC 10 mA, 24 V AC 20 mA
Environment according to EN 60664-1	overvoltage category III/pollution degree 2

¹⁾ IEC 60947 part 4 and 5

The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).

²⁾ Overvoltage Category II

³⁾ UL applications 300 V AC2A

Cable lengths and cross sections for control cables¹⁾

Max. motor cable length, screened	FC 301: 50 m/FC 301 (Frame size A1): 25 m/FC 302: 150 m
Max. motor cable length, unscreened	FC 301: 75 m/FC 301 (Frame size A1): 50 m/FC 302: 300 m
Maximum cross section to control terminals, flexible/rigid wire without cable end sleeves	1.5 mm ² /16 AWG
Maximum cross section to control terminals, flexible wire with cable end sleeves	1 mm ² /18 AWG
Maximum cross section to control terminals, flexible wire with cable end sleeves with collar	0.5 mm ² /20 AWG
Minimum cross section to control terminals	0.25 mm ² /24 AWG

¹⁾ For power cables, see 10.1 Power-dependent Specifications.

Control card performance

Scan interval	FC 301: 5 ms/FC 302: 1 ms
---------------	---------------------------

Control characteristics

Resolution of output frequency at 0-590 Hz	±0.003 Hz
Repeat accuracy of Precise start/stop (terminals 18, 19)	≤±0.1 ms
System response time (terminals 18, 19, 27, 29, 32, 33)	≤ 2 ms
Speed control range (open loop)	1:100 of synchronous speed
Speed control range (closed loop)	1:1000 of synchronous speed
Speed accuracy (open loop)	30-4000 rpm: error ±8 rpm
Speed accuracy (closed loop), depending on resolution of feedback device	0-6000 rpm: error ±0.15 rpm
Torque control accuracy (speed feedback)	max error ±5% of rated torque

All control characteristics are based on a 4-pole asynchronous motor

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Environment

Enclosure	IP20 ¹⁾ /Type 1, IP21 ²⁾ /Type 1, IP55/Type 12, IP66
Vibration test	1.0 g
Max. THVD	10%
Max. relative humidity	5% - 93% (IEC 721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 60068-2-43) H ₂ S test	class Kd
Ambient temperature ³⁾	Max. 50 °C (24-hour average maximum 45 °C)

¹⁾ Only for ≤ 3.7 kW (200-240 V), ≤ 7.5 kW (400-480/500 V)

²⁾ As enclosure kit for ≤ 3.7 kW (200-240 V), ≤ 7.5 kW (400-480/500 V)

³⁾ Derating for high ambient temperature, see special conditions in the Design Guide

Minimum ambient temperature during full-scale operation	0 °C
Minimum ambient temperature at reduced performance	- 10 °C
Temperature during storage/transport	-25 to +65/70 °C
Maximum altitude above sea level without derating	1000 m

Derating for high altitude, see special conditions in the Design Guide.

EMC standards, Emission	EN 61800-3, EN 61000-6-3/4, EN 55011
EMC standards, Immunity	EN 61800-3, EN 61000-6-1/2, EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6

See section on special conditions in the Design Guide.

10.3 Fuse Specifications

10.3.1 Fuses

It is recommended to use fuses and/or circuit breakers on the supply side as protection in case of component break-down inside the frequency converter (first fault).

NOTE

This is mandatory in order to ensure compliance with IEC 60364 for CE or NEC 2009 for UL.

⚠ WARNING

Personnel and property must be protected against the consequence of component break-down internally in the frequency converter.

Branch Circuit Protection

In order to protect the installation against electrical and fire hazard, all branch circuits in an installation, switch gear, machines etc., must be protected against short-circuit and over-current according to national/international regulations.

NOTE

The recommendations given do not cover Branch circuit protection for UL.

Short-circuit protection

Danfoss recommends using the fuses/Circuit Breakers mentioned below to protect service personnel and property in case of component break-down in the frequency converter.

10.3.2 Recommendations

⚠ WARNING

In case of malfunction, not following the recommendation may result in personnel risk and damage to the frequency converter and other equipment.

The following tables list the recommended rated current. Recommended fuses are of the type gG for small to medium power sizes. For larger powers, aR fuses are recommended. For Circuit Breakers, Moeller types have been tested to have a recommendation. Other types of circuit breakers may be used provide they limit the energy into the frequency converter to a level equal to or lower than the Moeller types.

If fuses/Circuit Breakers according to recommendations are chosen, possible damages on the frequency converter will mainly be limited to damages inside the unit.

For further information please see Application Note *Fuses and Circuit Breakers*.

10.3.3 CE Compliance

Fuses or Circuit Breakers are mandatory to comply with IEC 60364. Danfoss recommend using a selection of the following.

The fuses below are suitable for use on a circuit capable of delivering 100,000 Arms (symmetrical), 240 V, 480 V, 500 V, 600 V, or 690 V depending on the frequency converter voltage rating. With the proper fusing the frequency converter short circuit current rating (SCCR) is 100,000 Arms.

The following UL listed fuses are suitable:

- UL248-4 class CC fuses
- UL248-8 class J fuses
- UL248-12 class R fuses (RK1)
- UL248-15 class T fuses

The following max. fuse size and type have been tested:

Enclosure size	Power [kW]	Recommended fuse size	Recommended Max. fuse	Recommended circuit breaker Moeller	Max trip level [A]
A1	0.25-1.5	gG-10	gG-25	PKZM0-16	16
A2	0.25-2.2	gG-10 (0.25-1.5) gG-16 (2.2)	gG-25	PKZM0-25	25
A3	3.0-3.7	gG-16 (3) gG-20 (3.7)	gG-32	PKZM0-25	25
B3	5.5	gG-25	gG-63	PKZM4-50	50
B4	7.5-15	gG-32 (7.5) gG-50 (11) gG-63 (15)	gG-125	NZMB1-A100	100
C3	18.5-22	gG-80 (18.5) aR-125 (22)	gG-150 (18.5) aR-160 (22)	NZMB2-A200	150
C4	30-37	aR-160 (30) aR-200 (37)	aR-200 (30) aR-250 (37)	NZMB2-A250	250
A4	0.25-2.2	gG-10 (0.25-1.5) gG-16 (2.2)	gG-32	PKZM0-25	25
A5	0.25-3.7	gG-10 (0.25-1.5) gG-16 (2.2-3) gG-20 (3.7)	gG-32	PKZM0-25	25
B1	5.5-7.5	gG-25 (5.5) gG-32 (7.5)	gG-80	PKZM4-63	63
B2	11	gG-50	gG-100	NZMB1-A100	100
C1	15-22	gG-63 (15) gG-80 (18.5) gG-100 (22)	gG-160 (15-18.5) aR-160 (22)	NZMB2-A200	160
C2	30-37	aR-160 (30) aR-200 (37)	aR-200 (30) aR-250 (37)	NZMB2-A250	250

Table 10.14 200-240 V, Frame Sizes A, B and C

Enclosure size	Power [kW]	Recommended fuse size	Recommended Max. fuse	Recommended circuit breaker Moeller	Max trip level [A]
A1	0.37-1.5	gG-10	gG-25	PKZM0-16	16
A2	0.37-4.0	gG-10 (0.37-3) gG-16 (4)	gG-25	PKZM0-25	25
A3	5.5-7.5	gG-16	gG-32	PKZM0-25	25
B3	11-15	gG-40	gG-63	PKZM4-50	50
B4	18.5-30	gG-50 (18.5) gG-63 (22) gG-80 (30)	gG-125	NZMB1-A100	100
C3	37-45	gG-100 (37) gG-160 (45)	gG-150 (37) gG-160 (45)	NZMB2-A200	150
C4	55-75	aR-200 (55) aR-250 (75)	aR-250	NZMB2-A250	250
A4	0.37-4	gG-10 (0.37-3) gG-16 (4)	gG-32	PKZM0-25	25
A5	0.37-7.5	gG-10 (0.37-3) gG-16 (4-7.5)	gG-32	PKZM0-25	25
B1	11-15	gG-40	gG-80	PKZM4-63	63
B2	18.5-22	gG-50 (18.5) gG-63 (22)	gG-100	NZMB1-A100	100
C1	30-45	gG-80 (30) gG-100 (37) gG-160 (45)	gG-160	NZMB2-A200	160
C2	55-75	aR-200 (55) aR-250 (75)	aR-250	NZMB2-A250	250

Table 10.15 380-500 V, Frame Sizes A, B and C

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Enclosure size	Power [kW]	Recommended fuse size	Recommended Max. fuse	Recommended circuit breaker Moeller	Max trip level [A]
A2	0-75-4.0	gG-10	gG-25	PKZM0-25	25
A3	5.5-7.5	gG-10 (5.5) gG-16 (7.5)	gG-32	PKZM0-25	25
B3	11-15	gG-25 (11) gG-32 (15)	gG-63	PKZM4-50	50
B4	18.5-30	gG-40 (18.5) gG-50 (22) gG-63 (30)	gG-125	NZMB1-A100	100
C3	37-45	gG-63 (37) gG-100 (45)	gG-150	NZMB2-A200	150
C4	55-75	aR-160 (55) aR-200 (75)	aR-250	NZMB2-A250	250
A5	0.75-7.5	gG-10 (0.75-5.5) gG-16 (7.5)	gG-32	PKZM0-25	25
B1	11-18	gG-25 (11) gG-32 (15) gG-40 (18.5)	gG-80	PKZM4-63	63
B2	22-30	gG-50 (22) gG-63 (30)	gG-100	NZMB1-A100	100
C1	37-55	gG-63 (37) gG-100 (45) aR-160 (55)	gG-160 (37-45) aR-250 (55)	NZMB2-A200	160
C2	75	aR-200 (75)	aR-250	NZMB2-A250	250

Table 10.16 525-600 V, Frame Sizes A, B and C

Enclosure size	Power [kW]	Recommended fuse size	Recommended Max. fuse	Recommended circuit breaker Moeller	Max trip level [A]
A3	1.1	gG-6	gG-25	-	-
	1.5	gG-6	gG-25		
	2.2	gG-6	gG-25		
	3	gG-10	gG-25		
	4	gG-10	gG-25		
	5.5	gG-16	gG-25		
	7.5	gG-16	gG-25		
B2	11	gG-25 (11)	gG-63	-	-
	15	gG-32 (15)			
	18	gG-32 (18)			
	22	gG-40 (22)			
C2	30	gG-63 (30)	gG-80 (30) gG-100 (37) gG-125 (45) gG-160 (55-75)	-	-
	37	gG-63 (37)			
	45	gG-80 (45)			
	55	gG-100 (55)			
	75	gG-125 (75)			
C3	37	gG-80	gG-100 gG-125	-	-
	45	gG-100			

Table 10.17 525-690 V, Frame Sizes A, B and C

UL Compliance

Fuses or Circuit Breakers are mandatory to comply with NEC 2009. Danfoss recommends using a selection of the following

500 V, or 600 V depending on the frequency converter voltage rating. With the proper fusing the drive Short Circuit Current Rating (SCCR) is 100,000 Arms.

The fuses below are suitable for use on a circuit capable of delivering 100,000 Arms (symmetrical), 240 V, or 480 V, or

	Recommended max. fuse					
Power [kW]	Bussmann Type RK1 ¹⁾	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
0.25-0.37	KTN-R-05	JKS-05	JJN-05	FNQ-R-5	KTK-R-5	LP-CC-5
0.55-1.1	KTN-R-10	JKS-10	JJN-10	FNQ-R-10	KTK-R-10	LP-CC-10
1.5	KTN-R-15	JKS-15	JJN-15	FNQ-R-15	KTK-R-15	LP-CC-15
2.2	KTN-R-20	JKS-20	JJN-20	FNQ-R-20	KTK-R-20	LP-CC-20
3.0	KTN-R-25	JKS-25	JJN-25	FNQ-R-25	KTK-R-25	LP-CC-25
3.7	KTN-R-30	JKS-30	JJN-30	FNQ-R-30	KTK-R-30	LP-CC-30
5.5	KTN-R-50	KS-50	JJN-50	-	-	-
7.5	KTN-R-60	JKS-60	JJN-60	-	-	-
11	KTN-R-80	JKS-80	JJN-80	-	-	-
15-18.5	KTN-R-125	JKS-125	JJN-125	-	-	-
22	KTN-R-150	JKS-150	JJN-150	-	-	-
30	KTN-R-200	JKS-200	JJN-200	-	-	-
37	KTN-R-250	JKS-250	JJN-250	-	-	-

Table 10.18 200-240 V, Frame Sizes A, B and C

	Recommended max. fuse			
Power [kW]	SIBA Type RK1	Littel fuse Type RK1	Ferraz-Shawmut Type CC	Ferraz-Shawmut Type RK1 ³⁾
0.25-0.37	5017906-005	KLN-R-05	ATM-R-05	A2K-05-R
0.55-1.1	5017906-010	KLN-R-10	ATM-R-10	A2K-10-R
1.5	5017906-016	KLN-R-15	ATM-R-15	A2K-15-R
2.2	5017906-020	KLN-R-20	ATM-R-20	A2K-20-R
3.0	5017906-025	KLN-R-25	ATM-R-25	A2K-25-R
3.7	5012406-032	KLN-R-30	ATM-R-30	A2K-30-R
5.5	5014006-050	KLN-R-50	-	A2K-50-R
7.5	5014006-063	KLN-R-60	-	A2K-60-R
11	5014006-080	KLN-R-80	-	A2K-80-R
15-18.5	2028220-125	KLN-R-125	-	A2K-125-R
22	2028220-150	KLN-R-150	-	A2K-150-R
30	2028220-200	KLN-R-200	-	A2K-200-R
37	2028220-250	KLN-R-250	-	A2K-250-R

Table 10.19 200-240 V, Frame Sizes A, B and C

Power [kW]	Recommended max. fuse			
	Bussmann Type JFHR2 ²⁾	Littel fuse JFHR2	Ferraz- Shawmut JFHR2 ⁴⁾	Ferraz- Shawmut J
0.25-0.37	FWX-5	-	-	HSJ-6
0.55-1.1	FWX-10	-	-	HSJ-10
1.5	FWX-15	-	-	HSJ-15
2.2	FWX-20	-	-	HSJ-20
3.0	FWX-25	-	-	HSJ-25
3.7	FWX-30	-	-	HSJ-30
5.5	FWX-50	-	-	HSJ-50
7.5	FWX-60	-	-	HSJ-60
11	FWX-80	-	-	HSJ-80
15-18.5	FWX-125	-	-	HSJ-125
22	FWX-150	L25S-150	A25X-150	HSJ-150
30	FWX-200	L25S-200	A25X-200	HSJ-200
37	FWX-250	L25S-250	A25X-250	HSJ-250

Table 10.20 200-240 V, Frame Sizes A, B and C

- 1) KTS-fuses from Bussmann may substitute KTN for 240 V frequency converters.
- 2) FWH-fuses from Bussmann may substitute FWX for 240 V frequency converters.
- 3) A6KR fuses from FERRAZ SHAWMUT may substitute A2KR for 240 V frequency converters.
- 4) A50X fuses from FERRAZ SHAWMUT may substitute A25X for 240 V frequency converters.

Power [kW]	Recommended max. fuse					
	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
0.37-1.1	KTS-R-6	JKS-6	JJS-6	FNQ-R-6	KTk-R-6	LP-CC-6
1.5-2.2	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTk-R-10	LP-CC-10
3	KTS-R-15	JKS-15	JJS-15	FNQ-R-15	KTk-R-15	LP-CC-15
4	KTS-R-20	JKS-20	JJS-20	FNQ-R-20	KTk-R-20	LP-CC-20
5.5	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTk-R-25	LP-CC-25
7.5	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTk-R-30	LP-CC-30
11	KTS-R-40	JKS-40	JJS-40	-	-	-
15	KTS-R-50	JKS-50	JJS-50	-	-	-
18	KTS-R-60	JKS-60	JJS-60	-	-	-
22	KTS-R-80	JKS-80	JJS-80	-	-	-
30	KTS-R-100	JKS-100	JJS-100	-	-	-
37	KTS-R-125	JKS-125	JJS-125	-	-	-
45	KTS-R-150	JKS-150	JJS-150	-	-	-
55	KTS-R-200	JKS-200	JJS-200	-	-	-
75	KTS-R-250	JKS-250	JJS-250	-	-	-

Table 10.21 380-500 V, Frame Sizes A, B and C

Power [kW]	Recommended max. fuse			
	SIBA Type RK1	Littel fuse Type RK1	Ferraz- Shawmut Type CC	Ferraz- Shawmut Type RK1
0.37-1.1	5017906-006	KLS-R-6	ATM-R-6	A6K-6-R
1.5-2.2	5017906-010	KLS-R-10	ATM-R-10	A6K-10-R
3	5017906-016	KLS-R-15	ATM-R-15	A6K-15-R
4	5017906-020	KLS-R-20	ATM-R-20	A6K-20-R
5.5	5017906-025	KLS-R-25	ATM-R-25	A6K-25-R
7.5	5012406-032	KLS-R-30	ATM-R-30	A6K-30-R
11	5014006-040	KLS-R-40	-	A6K-40-R
15	5014006-050	KLS-R-50	-	A6K-50-R
18	5014006-063	KLS-R-60	-	A6K-60-R
22	2028220-100	KLS-R-80	-	A6K-80-R
30	2028220-125	KLS-R-100	-	A6K-100-R
37	2028220-125	KLS-R-125	-	A6K-125-R
45	2028220-160	KLS-R-150	-	A6K-150-R
55	2028220-200	KLS-R-200	-	A6K-200-R
75	2028220-250	KLS-R-250	-	A6K-250-R

Table 10.22 380-500 V, Frame Sizes A, B and C

Power [kW]	Recommended max. fuse			
	Bussmann JFHR2	Ferraz- Shawmut J	Ferraz- Shawmut JFHR2 ¹⁾	Littel fuse JFHR2
0.37-1.1	FWH-6	HSJ-6	-	-
1.5-2.2	FWH-10	HSJ-10	-	-
3	FWH-15	HSJ-15	-	-
4	FWH-20	HSJ-20	-	-
5.5	FWH-25	HSJ-25	-	-
7.5	FWH-30	HSJ-30	-	-
11	FWH-40	HSJ-40	-	-
15	FWH-50	HSJ-50	-	-
18	FWH-60	HSJ-60	-	-
22	FWH-80	HSJ-80	-	-
30	FWH-100	HSJ-100	-	-
37	FWH-125	HSJ-125	-	-
45	FWH-150	HSJ-150	-	-
55	FWH-200	HSJ-200	A50-P-225	L50-S-225
75	FWH-250	HSJ-250	A50-P-250	L50-S-250

Table 10.23 380-500 V, Frame Sizes A, B and C

1) Ferraz-Shawmut A50QS fuses may substitute for A50P fuses.

	Recommended max. fuse					
Power [kW]	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
0.75-1.1	KTS-R-5	JKS-5	JJS-6	FNQ-R-5	KTK-R-5	LP-CC-5
1.5-2.2	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTK-R-10	LP-CC-10
3	KTS-R-15	JKS-15	JJS-15	FNQ-R-15	KTK-R-15	LP-CC-15
4	KTS-R-20	JKS-20	JJS-20	FNQ-R-20	KTK-R-20	LP-CC-20
5.5	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTK-R-25	LP-CC-25
7.5	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTK-R-30	LP-CC-30
11	KTS-R-35	JKS-35	JJS-35	-	-	-
15	KTS-R-45	JKS-45	JJS-45	-	-	-
18	KTS-R-50	JKS-50	JJS-50	-	-	-
22	KTS-R-60	JKS-60	JJS-60	-	-	-
30	KTS-R-80	JKS-80	JJS-80	-	-	-
37	KTS-R-100	JKS-100	JJS-100	-	-	-
45	KTS-R-125	JKS-125	JJS-125	-	-	-
55	KTS-R-150	JKS-150	JJS-150	-	-	-
75	KTS-R-175	JKS-175	JJS-175	-	-	-

Table 10.24 525-600 V, Frame Sizes A, B and C

	Recommended max. fuse			
Power [kW]	SIBA Type RK1	Littel fuse Type RK1	Ferraz-Shawmut Type RK1	Ferraz-Shawmut J
0.75-1.1	5017906-005	KLS-R-005	A6K-5-R	HSJ-6
1.5-2.2	5017906-010	KLS-R-010	A6K-10-R	HSJ-10
3	5017906-016	KLS-R-015	A6K-15-R	HSJ-15
4	5017906-020	KLS-R-020	A6K-20-R	HSJ-20
5.5	5017906-025	KLS-R-025	A6K-25-R	HSJ-25
7.5	5017906-030	KLS-R-030	A6K-30-R	HSJ-30
11	5014006-040	KLS-R-035	A6K-35-R	HSJ-35
15	5014006-050	KLS-R-045	A6K-45-R	HSJ-45
18	5014006-050	KLS-R-050	A6K-50-R	HSJ-50
22	5014006-063	KLS-R-060	A6K-60-R	HSJ-60
30	5014006-080	KLS-R-075	A6K-80-R	HSJ-80
37	5014006-100	KLS-R-100	A6K-100-R	HSJ-100
45	2028220-125	KLS-R-125	A6K-125-R	HSJ-125
55	2028220-150	KLS-R-150	A6K-150-R	HSJ-150
75	2028220-200	KLS-R-175	A6K-175-R	HSJ-175

Table 10.25 525-600 V, Frame Sizes A, B and C

¹⁾ 170M fuses shown from Bussmann use the -/80 visual indicator. -TN/80 Type T, -/110 or TN/110 Type T indicator fuses of the same size and amperage may be substituted.

	Recommended max. fuse					
Power [kW]	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
[kW]						
1.1	KTS-R-5	JKS-5	JJS-6	FNQ-R-5	KTK-R-5	LP-CC-5
1.5-2.2	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTK-R-10	LP-CC-10
3	KTS-R15	JKS-15	JJS-15	FNQ-R-15	KTK-R-15	LP-CC-15
4	KTS-R20	JKS-20	JJS-20	FNQ-R-20	KTK-R-20	LP-CC-20
5.5	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTK-R-25	LP-CC-25
7.5	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTK-R-30	LP-CC-30
11	KTS-R-35	JKS-35	JJS-35	-	-	-
15	KTS-R-45	JKS-45	JJS-45	-	-	-
18	KTS-R-50	JKS-50	JJS-50	-	-	-
22	KTS-R-60	JKS-60	JJS-60	-	-	-
30	KTS-R-80	JKS-80	JJS-80	-	-	-
37	KTS-R-100	JKS-100	JJS-100	-	-	-
45	KTS-R-125	JKS-125	JJS-125	-	-	-
55	KTS-R-150	JKS-150	JJS-150	-	-	-
75	KTS-R-175	JKS-175	JJS-175	-	-	-

Table 10.26 525-690 V, Frame Sizes A, B and C

	Recommended max. fuse							
Power [kW]	Max. prefuse	Bussmann E52273 RK1/JDDZ	Bussmann E4273 J/JDDZ	Bussmann E4273 T/JDDZ	SIBA E180276 RK1/JDDZ	Littelfuse E81895 RK1/JDDZ	Ferraz- Shawmut E163267/E2137 RK1/JDDZ	Ferraz- Shawmut E2137 J/HSJ
11	30 A	KTS-R-30	JKS-30	JKJS-30	5017906-030	KLS-R-030	A6K-30-R	HST-30
15-18.5	45 A	KTS-R-45	JKS-45	JJS-45	5014006-050	KLS-R-045	A6K-45-R	HST-45
22	60 A	KTS-R-60	JKS-60	JJS-60	5014006-063	KLS-R-060	A6K-60-R	HST-60
30	80 A	KTS-R-80	JKS-80	JJS-80	5014006-080	KLS-R-075	A6K-80-R	HST-80
37	90 A	KTS-R-90	JKS-90	JJS-90	5014006-100	KLS-R-090	A6K-90-R	HST-90
45	100 A	KTS-R-100	JKS-100	JJS-100	5014006-100	KLS-R-100	A6K-100-R	HST-100
55	125 A	KTS-R-125	JKS-125	JJS-125	2028220-125	KLS-150	A6K-125-R	HST-125
75	150 A	KTS-R-150	JKS-150	JJS-150	2028220-150	KLS-175	A6K-150-R	HST-150
* UL compliance only 525-600 V								

Table 10.27 525-690 V*, Frame Sizes B and C

10.4 Connection Tightening Torques

Enclosure	Power (kW)			Torque (Nm)						
	200-240 V	380-480/500 V	525-600 V	525-690 V	Mains	Motor	DC connection	Brake	Earth	Relay
A2	0.25-2.2	0.37-4.0			1.8	1.8	1.8	1.8	3	0.6
A3	3.0-3.7	5.5-7.5	0.75-7.5	1.1-7.5	1.8	1.8	1.8	1.8	3	0.6
A4	0.25-2.2	0.37-4.0			1.8	1.8	1.8	1.8	3	0.6
A5	0.25-3.7	0.37-7.5	0.75-7.5		1.8	1.8	1.8	1.8	3	0.6
B1	5.5-7.5	11-15	11-15		1.8	1.8	1.5	1.5	3	0.6
B2	11	18	18	11	4.5	4.5	3.7	3.7	3	0.6
		22	22	22	4.5	4.5	3.7	3.7	3	0.6
B3	5.5-7.5	11-15	11-15		1.8	1.8	1.8	1.8	3	0.6
B4	11-15	18-30	18-30		4.5	4.5	4.5	4.5	3	0.6
C1	15-22	30-45	30-45		10	10	10	10	3	0.6
C2	30-37	55-75	55-75	30-75	14/24 ¹⁾	14/24 ¹⁾	14	14	3	0.6
C3	18-22	37-45	37-45	45-55	10	10	10	10	3	0.6
C4	30-37	55-75	55-75		14/24 ¹⁾	14/24 ¹⁾	14	14	3	0.6

Table 10.28 Tightening of Terminals

¹⁾ For different cable dimensions x/y, where $x \leq 95 \text{ mm}^2$ and $y \geq 95 \text{ mm}^2$.

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